

1 **Electrospun Nanofibre Membrane Based Transparent Slippery** 2 **Liquid-Infused Porous Surfaces with Icephobic Properties**

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8 ***Abstract***

9 Icephobic surfaces have attracted increasing attention due to their wide ranging application
10 areas from wind and solar energy systems to aviation. Slippery liquid-infused porous surfaces
11 (SLIPS) are being explored for passive ice protection due to their lower ice adhesion strength.
12 In this study, we present a cost-effective and scalable electrospinning technique to produce
13 freestanding nanofibrous polymeric surfaces for the fabrication of transparent icephobic
14 SLIPS. The diameter of the electrospun fibres produced varied from 200 to 400 nm and the
15 membranes had a theoretical porosity of $71.6 \pm 4.1\%$. Furthermore, three different lubricants
16 polychlorotrifluoroethylene oil (PcTFE), silicone oil and liquid paraffin, were used and it was
17 observed that when silicone oil and PcTFE were used as lubricants for SLIPS, they provided
18 high optical transparency (>90%) in the visible light spectrum compared to PVDF-co-HFP
19 itself. All SLIPS were subjected to centrifugal ice adhesion testing which revealed their ice
20 adhesion strengths lower than 1 KPa with significant delay in droplet icing compared to
21 aluminium reference, from 5 up to 41 sec. The results indicated that enhanced icephobic
22 properties of electrospun membranes have been clearly demonstrated.

23 **Keywords:** Slippery liquid-infused porous surfaces (SLIPS), electrospun, nanofibres, icephobic
24 surface, ice adhesion strength.

25 **1. Introduction**

26 Ice accretion often causes serious problems in many areas such as decreased efficiency of
27 energy systems (i.e. wind turbines, solar panels), delays for air transportation or personal
28 injuries from falling ice masses and structural damage of buildings due to the excessive weights
29 of ice [1-4]. Many approaches to prevent surfaces from ice-causing problems have been
30 investigated such as active heating systems [5], chemical de-icing fluids [6] (typically
31 composed of ethylene glycol or propylene glycol) and mechanical removal [7]. These
32 approaches either have considerable energy consumption or bring no negligible environmental
33 impacts. As such, producing surfaces with anti-icing or icephobic properties to reduce the
34 impact of the ice accretion is of vital importance to many industrial services.

35 Aizenberg *et al.* [8] proposed slippery liquid-infused porous surfaces (SLIPS) inspired from
36 the *Nepenthes* pitcher plant. This structure consists of two main parts: 1) porous surface and 2)
37 lubricant, and had remarkable slippery behaviour against immiscible liquids. Although there
38 are several challenges remaining for the application of SLIPS in harsh conditions such as
39 evaporation of lubricants, durability of the structure or the contamination of the surface with
40 dust, significant icephobic properties have been achieved. Subramanyam *et al.* [9] focused on
41 the effect of the texture density of silicon microposts on the ice adhesion properties of the
42 SLIPS. They produced micropost surfaces using photolithography techniques and chose silicon
43 oil and tetramethyl tetraphenyl trisiloxane as the lubricants. The results showed that the
44 increasing texture density of the surface led to decreased ice adhesion strength. Dou *et al.* [10]
45 reported a study showing a polyurethane anti-icing coating with an aqueous lubricating layer
46 and ice adhesion strength as low as 30 KPa was obtained. Erbil *et al.* [11] produced SLIPS
47 with hydrophobic polypropylene sorbent mats and hydrophilic cellulose-based filter paper
48 surfaces as porous structure, with different hydrophobic and hydrophilic liquids as lubricants.
49 It was suggested that the hydrophilic lubricant impregnated hydrophilic porous surface would

50 be promising candidates for anti-icing application because of their improved droplet icing
51 times. Wang *et al.* [12] produced SLIPS by infusing perfluorinated lubricant into smooth/
52 hierarchical structured surfaces and found that low surface energy is a critical issue for the
53 sliding speed. Zhu *et al.* [13] prepared SLIPS using rough polydimethylsiloxane (PDMS)
54 coatings by adding silica nanoparticles. Silicon oil was infused to produce SLIPS and 75 KPa
55 of ice adhesion strength obtained. Chen *et al.* [14] produced four different structures
56 (hydrophobic, superhydrophobic, silicic and fluoruous slippery coatings) and evaluated their
57 performance in anti-icing applications. They demonstrated that SLIPS differed from other
58 surfaces in frost growth mechanism and frost formation time which provides better anti icing
59 and de-icing properties.

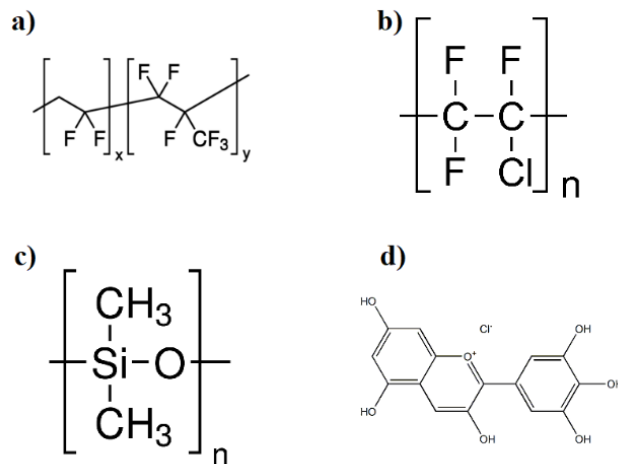
60 For icephobic coatings on solar energy harvesting systems, windows and curtain walls,
61 transparency has critical importance [15]. If the layer is not sufficiently optical transparent,
62 some of the sunlight would be difficult to reach the solar systems which significantly affects
63 the efficiency of the solar cells. However, there are only a limited number of study about
64 transparent icephobic coatings [15-18]. Wu *et al.* produced transparent icephobic coatings
65 using bio-based epoxy and reported a 50 KPa ice adhesion strength was obtained at -20 °C with
66 a transmittance as high as 81% [15]. Chen *et al.* produced self-cleaning icephobic surfaces
67 using modified SiO₂ nanoparticles and an approximate 58 KPa ice adhesion strength was
68 obtained at -15 °C with the transmittance of 97.8% [16]. In another study, Chen *et al.* produced
69 porous cellulose lauroyl ester films using nanoprecipitation technique into which
70 perfluoropolyether was infused into the pores to obtain SLIPS. It was reported that this SLIPS
71 had good anti-icing properties with the transmittance between 30 and 80% [17]. To understand
72 the ice nucleation process, Shen *et al.* [19] investigated the effects of nanostructural features
73 on interfacial ice nucleation and it was found that during the freezing process, the solid–liquid
74 contact type determined the macroscopic freezing process.

75 Up to now, different production methods were employed for the production of porous surfaces
76 for icephobic SLIPS, such as self-assembly [20, 21], laser writing [22, 23], phase separation
77 [24] and electrospinning [25]. These methods have their own advantages as well as
78 disadvantages such as necessity to high laser energies [26], technical barriers for large-scale
79 implementations [27], and limitation in polymer selection [28]. In this study, we present a
80 cost-effective and scalable electrospinning technique to produce freestanding nanofibrous
81 polymeric surfaces for the fabrication of transparent icephobic SLIPS. Three types of lubricants
82 (silicone oil, fluorinated oil and paraffin liquid) were used for the preparation of the SLIPS and
83 the key properties including droplet icing time, ice adhesion strength and optical transmittance
84 in the visible light spectrum were investigated.

85 **2. MATERIALS and METHODS**

86 **2.1 Materials and substrates**

87 For the production of electrospun membrane, Poly (vinylidene fluoride-co-
88 hexafluoropropylene) (PVDF-co-HFP) with average M_w 400.000, average M_n 130.000,
89 dimethylformamide (DMF, >99%) and acetone (>99.9%) was purchased from Sigma Aldrich
90 (UK). Fluorinated lubricant Poly (chlorotrifluoroethylene) (PcTFE) was kindly supplied by
91 Halocarbon (USA). Other two types of lubricants (silicon oil and paraffin wax oil) were
92 supplied from Aldrich. The chemical structures of the materials are shown in Figure 1. For the
93 icephobic comparison purpose, AL2024-T3 aluminum alloy was used as reference. All
94 chemicals were used as received, without further purification.



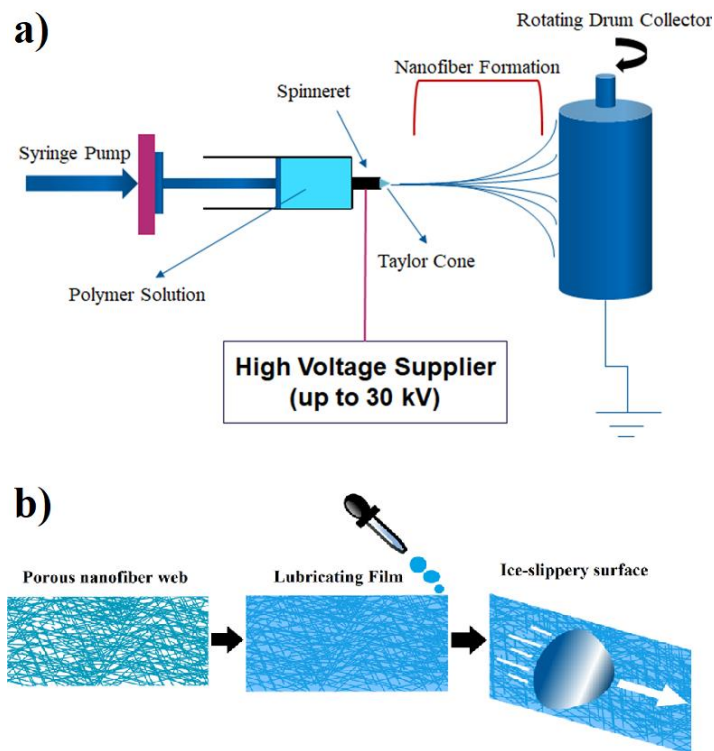
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96 **Figure 1.** Chemical structures of (a) PVDF-co-HFP, (b) PCTFE (c) silicone oil and (d)
 97 paraffin liquid

98 **2.2 Methods**

99 ***Preparation of electrospun membrane***

100 For the process of electrospinning, 15 wt. % concentration of PVDF-co-HFP solution was
 101 prepared using DMF and acetone mixture (50:50 wt. %). The applied voltage was chosen as
 102 17.5 kV with 1.25 ml/h flow rate and 13 cm collector-needle tip distance. The thickness of the
 103 electrospun membrane was controlled by the deposition time of fibres, and approximately 40
 104 μm thickness was obtained with 3 hour deposition time. The schematic diagram of the
 105 electrospinning process is given in Figure 2 (a).



106

107 **Figure 2.** (a) Schematic illustration of the electrospinning process and (b) preparation steps
 108 of ice-slippy SLIPS

109

110 ***Fabrication of SLIPS***

111 Three types of lubricants were used for the fabrication of SLIPS (PcTFE, silicone oil and
 112 paraffin wax oil). Approximately, 30 mg/cm² of lubricant was infused into the porous
 113 electrospun nanofibre membrane with a Pasteur pipette upon a balance. All samples were kept
 114 in a 45° tilted plate for overnight to get rid of excess oil and approximately 40 μm of thickness
 115 was obtained. The preparation steps of the SLIPS are given in Figure 2 (b).

116 **2.3 Microstructural and performance characterisation**

117 Surface morphology of the electrospun membranes was investigated using scanning electron
 118 microscope (Joel 7000), and ImageJ was used to analyse the diameter distribution of fibres

119 with 50 measurements. The porosity of the electrospun membrane was investigated by the
120 volume-mass calculation.

121 For the topographic characterisation, Zeta-20 profilometer, which has ability to analyse
122 transparent surfaces, was used with 50 x magnification. Surface roughness, height profiles and
123 topographic images were obtained with these analyses.

124 Static and dynamic contact angles of the samples were measured using a FTA200 dynamic
125 contact angle system and the contact angle hysteresis of samples were calculated using Eq. (1).

126

$$127 \quad \theta_{hyst} = \theta_{adv} - \theta_{rec} \quad \text{Eq.(1)}$$

128

129 where θ_{hyst} is contact angle hysteresis, θ_{adv} is the advancing contact angle and θ_{rec} is the
130 receding contact angle.

131 Ice adhesion tests were performed using a home-made setup, according to centrifuge method
132 [29, 30]. A glaze ice block with 1.3 g mass was attached on the sample surface in a -10°C
133 chamber for the measurement. Ice adhesion strengths were calculated using Eq. (2).

$$134 \quad F = mr\omega^2 \quad \text{Eq. (2)}$$

135 where F is the centrifugal force, ω is the rotation speed at the detachment of the glaze ice block,
136 m is the mass of the ice in kilograms and r is the length of beam [31].

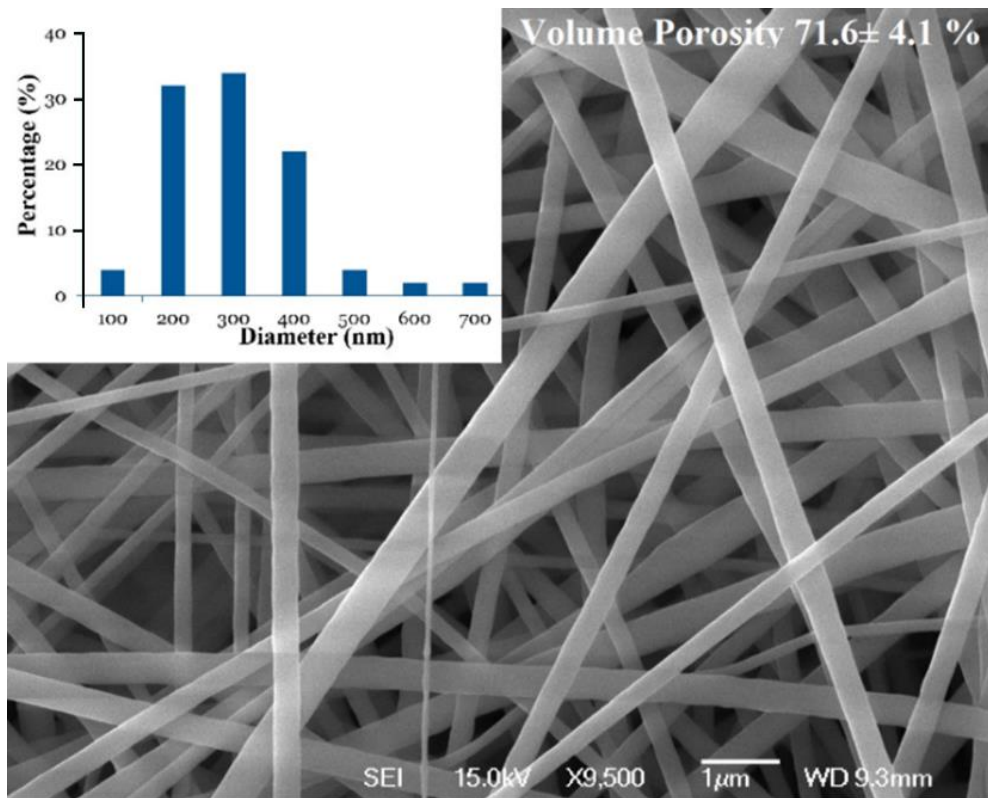
137 The water droplet icing tests were performed by observing the water droplets on a cold plate
138 setting at -10°C with a constant volume (4 μ L) on five spots of samples [31]. The average icing
139 duration was recorded to evaluate the anti-icing performance and droplet images were taken
140 every 10 seconds until the droplet was completely frozen.

141 Optical properties of the samples were evaluated using a biochrom Libra S22 UV/vis
142 spectrometer for the range of 300 to 900 nm and optical analyses of SLIPS performed with a
143 microscope slide and subtraction carried out by software to find real optical values.

144 **3. RESULTS and DISCUSSION**

145 **3.1 Surface morphology**

146 Porous fibrous membrane along with high porosity between the fibres ($71.6 \pm 4.1\%$) was
147 obtained from the electrospinning process, as shown in Figure 3. Most of the fibres had a
148 diameter range between 100 and 400 nm which can offer a high surface area. It is important
149 because the high surface area can provide more contact area between lubricant and the fibres.
150 Because the PVDF-co-HFP fibres highly oleophilic, higher contact area can offer better
151 capability of containing the lubricant, which is one of the main concern of SLIPS.

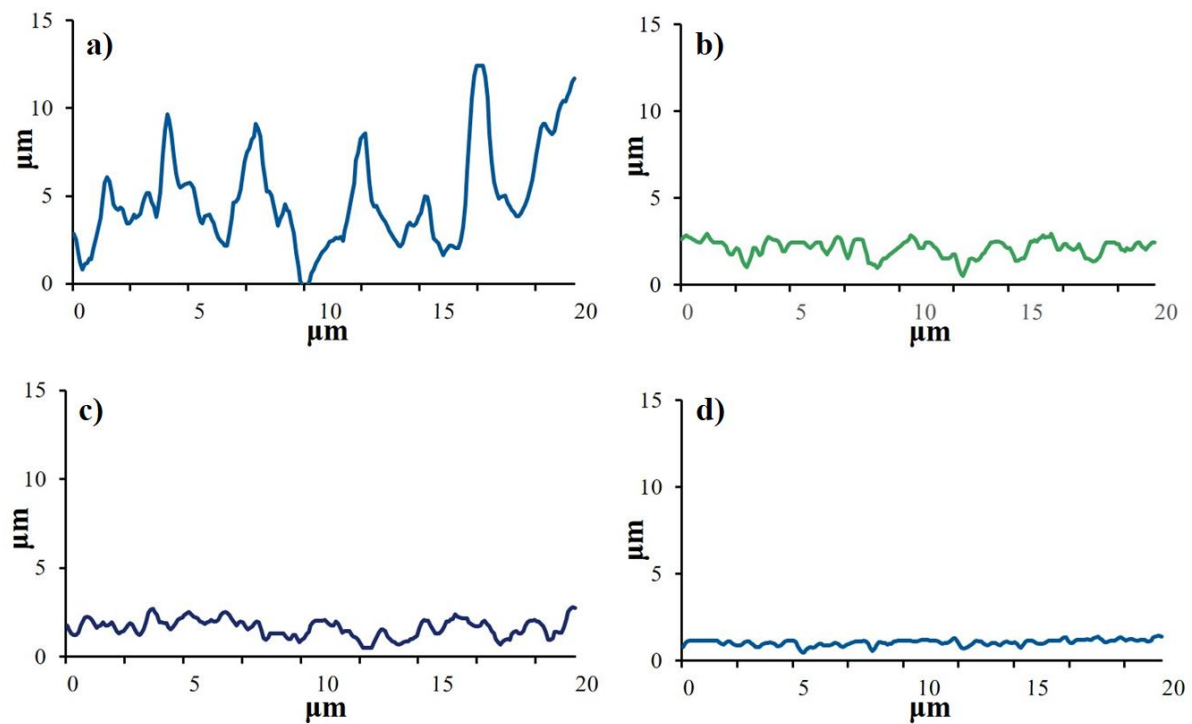


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153 **Figure 3.** SEM analyses of the as-prepared electrospun membrane (Inset: distribution of fibre
154 diameter)

155 Surface height profiles of the samples, before and after lubricant infusion, are shown in Figure
156 4. It was found that the membrane surfaces without lubricant had the maximum peak-

157 valley heights of approximately 15 μm . The pores in the structures provided the valleys whilst
158 the overlapping fibres provided the peaks. After the infusion of the lubricants, the
159 maximum peak-valley heights of the samples had decreased to approximately less than 3 μm
160 range which is an indication that the lubricant had filled most of the pores. All SLIPS have low
161 peak-valley heights and there is no significant difference between the three lubricants explored,
162 according to height profiles.



163

164

165 **Figure 4.** Height profiles of the (a) PVDF-co-HFP electrospun membrane

166 and SLIPS with (b) silicone oil, (c) paraffin oil and (d) PctFE

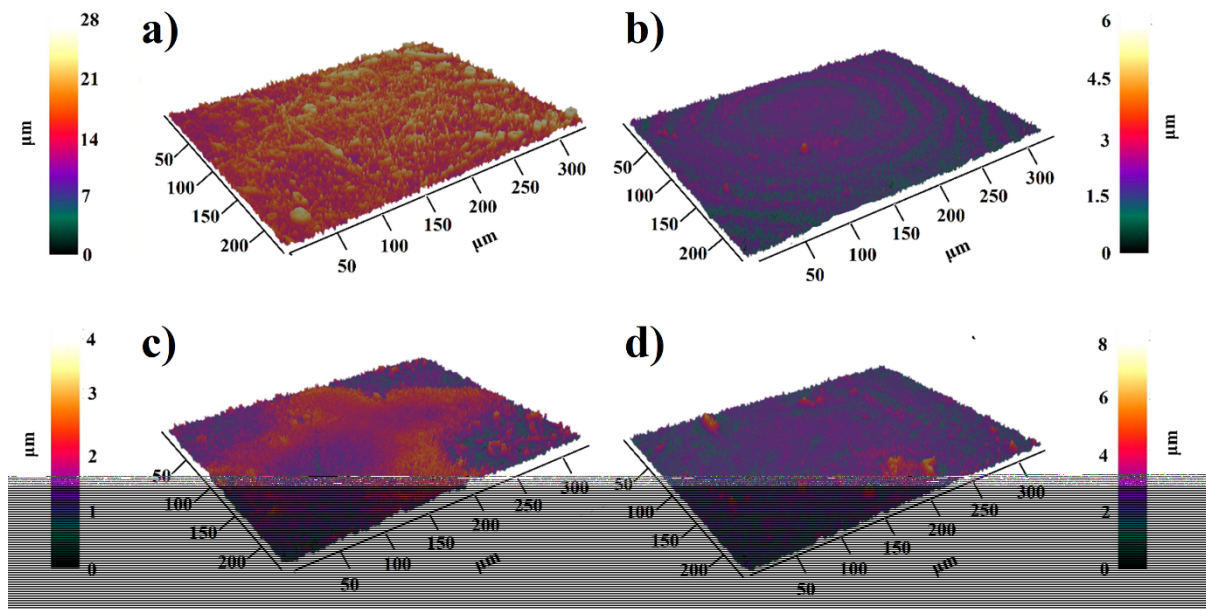
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168 The 3D topographic images of the samples are given in Figure 5. The fibrous structure of the

169 electrospun membranes can be reflected in Figure 5 (a) which is a lubricant free structure. After

170 the infusion of the lubricant, no fibrous structure could be observed. The roughness of the
171 electrospun membrane also decreased dramatically, consistent with the height profile results.

172



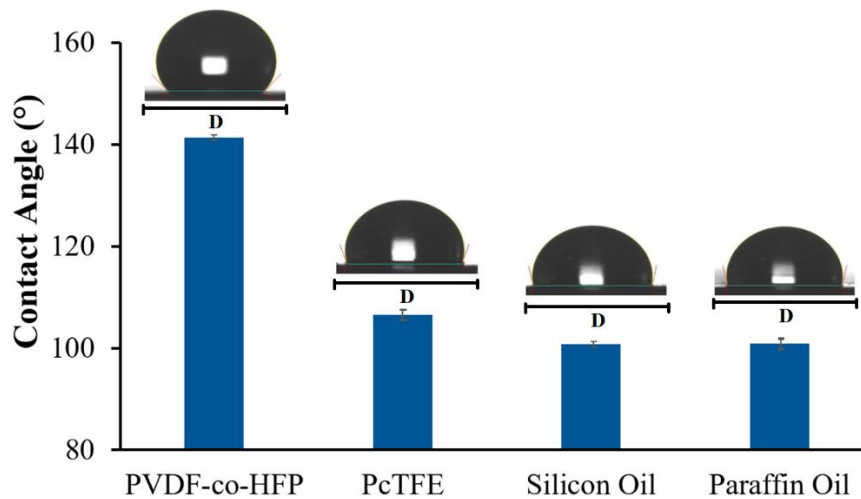
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174 **Figure 5.** 3D topographic images of (a) PVDF-co-HFP electrospun membrane (b) SLIPS
175 with PctFE, (c) SLIPS with silicone oil and (d) SLIPS with liquid paraffin

176 3.2 Wetting characteristics

177 Water contact angles of the SLIPS are shown in Figure 6. The electrospun PVDF-co-HFP
178 membranes produced possessed average contact angle of 141.2°. After the infusion of oils, the
179 roughness and composition of the surface had been changed. So the measured contact angles
180 reflect mostly the nature of the oils used in the SLIPS instead of the fibres. Additionally,
181 according to Cassie-Baxter mechanism, air pockets on the surface have great impact on the
182 hydrophobicity. After the lubricant infusion, theoretically, the air pockets would be
183 significantly reduced with the lubricants which minimised the roughness effect from the as-
184 produced PVDF-co-HFP electrospun membrane structure. Therefore, the static contact angles
185 of the SLIPS decreased dramatically compared to the unfilled fibrous structure, although the

186 contact angles were still in the hydrophobic range ($>90^\circ$). The SLIPS with silicon and paraffin
187 oils have very close contact angles (approximately 98°). When the PcTFE was used as lubricant
188 for SLIPS, the surface exhibited a higher contact angle (108°) possibly due to the fluorine
189 containing chemical structures which offered lower surface energy.



190

191 **Figure 6.** Static contact angles results of the as-produced membrane and SLIPS ($D=3.0$ mm)

192 Contact angle hysteresis of the samples are shown in Figure 7. Although all SLIPS have lower
193 static contact angles, they also have significantly lower contact angle hysteresis than the as-
194 produced PVDF-co-HFP electrospun membrane. Therefore despite lower contact angle of
195 SLIPS, water droplet would have much higher mobility on the SLIPS compared to lubricant
196 free structure. This is an expected effect of the lubricants reported elsewhere[32]. It is also
197 notable that SLIPS has stable contact angle hysteresis (CAH) with increasing droplet volume.
198 However, the CAH values of the PVDF-co-HFP is significantly dependent on the size of the
199 droplet. The lowest CAH obtained was on the PcTFE SLIPS for the droplet size $3.75 \mu\text{L}$, with
200 approximately 5.5° .

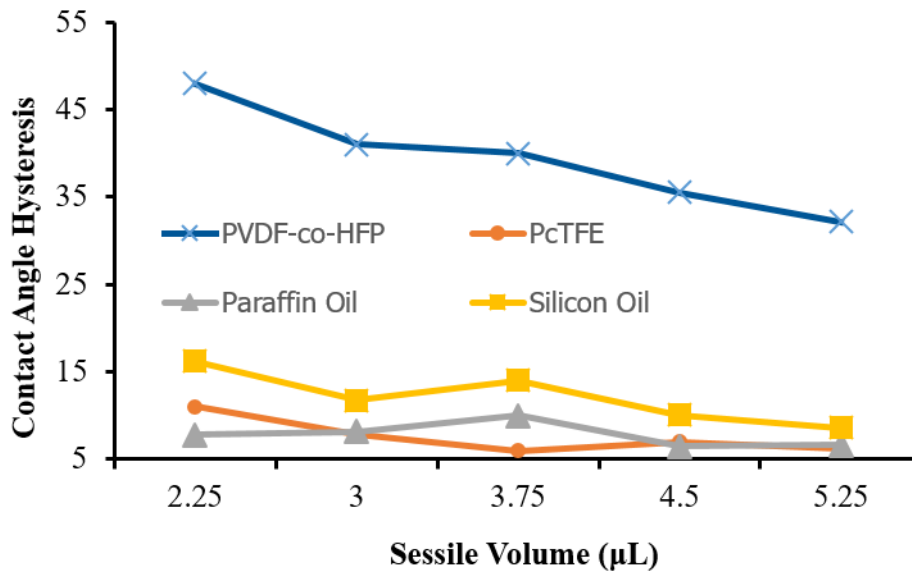


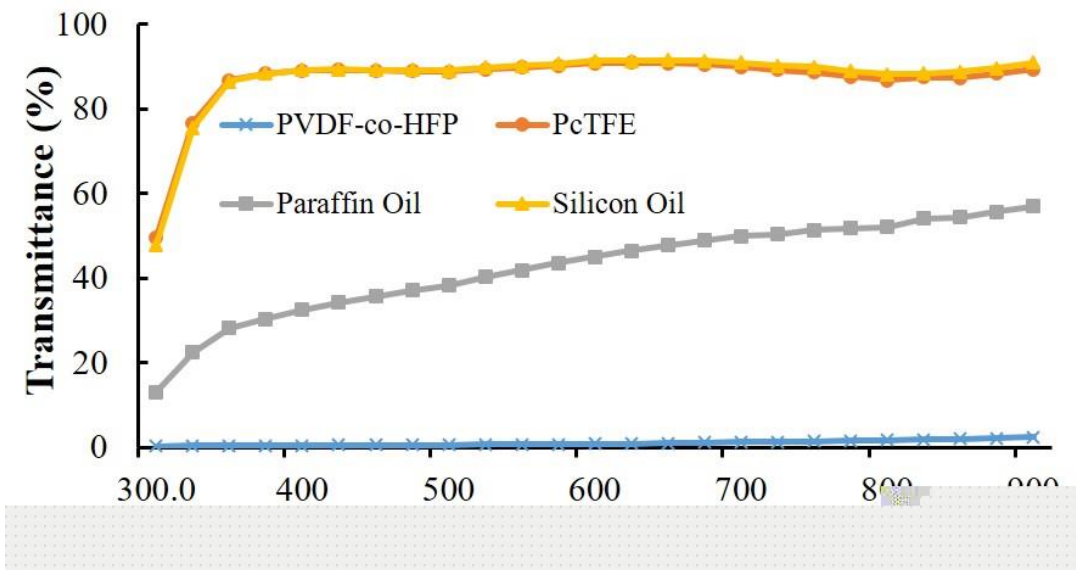
Figure 7. Contact angle hysteresis of the samples

3.3 Optical properties

Optical transmittances of the samples are shown in Figure 8. PVDF-co-HFP electrospun membrane did not show significant transmittance in the visible light spectrum, between 300 and 900 nm wavelengths. The relationship between deposition time of electrospinning and transparency of PVDF-co-HFP has been discussed before [33] and it was found when the deposition time, or in other words thickness of the membrane increased, the transmittance of the electrospun membrane is decreases. It is well known that transparent materials are made up of components with uniform refractive indices and for multicomponent structures mismatch of the refractive indices results in opacity [34]. In other words, the possibility of light passing through a medium or not, depends on the homogeneity of the refractive index of the final structure. Infusion of the lubricant contributed drastically to the excellent transparency of the electrospun membrane, depending on the refractive index of lubricant used. When silicone oil and PcTFE, which have quite similar refractive indices as PVDF-co-HFP, were used as lubricants, they both provided transmittance higher than 90% because of the uniform refractive

218 index of the entire structure. The lowest transmittance obtained was lower than 40% when
219 paraffin oil was used as lubricant, which has large discrepancy compared to the refractive index
220 of PVDF-co-HFP. These results are promising because the produced SLIPS may be used for
221 energy harvesting systems where the transparency of the top surface would directly influence
222 the efficiency of the solar panels [35].

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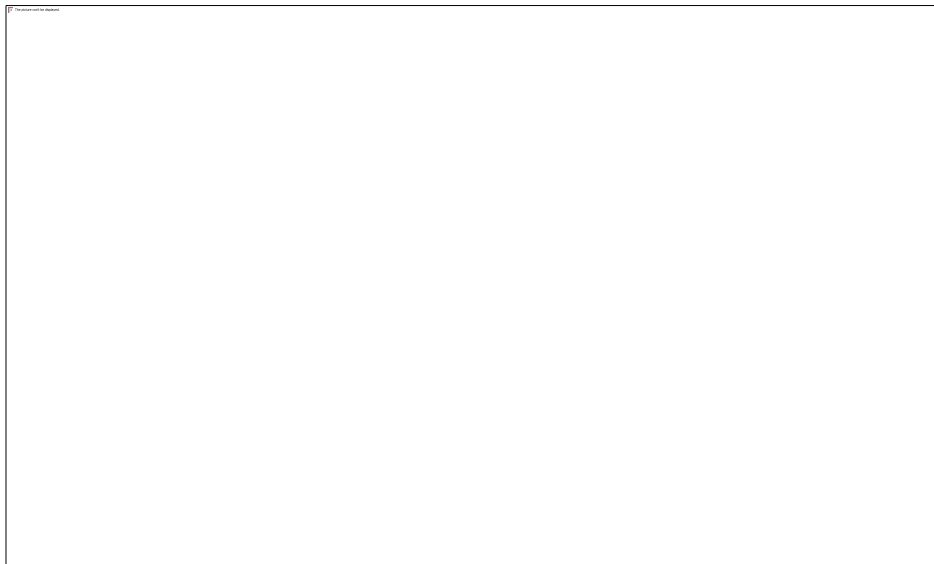
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225 **Figure 8.** Optical transmittances of samples

226 **3.4 Ice adhesion and droplet icing time**

227 Ice adhesion test results are presented in Figure 9. The results were compared with the
228 aluminum plate which is one of the most widely used materials for icephobic applications. It
229 was clear that the as-produced PVDF-co-HFP electrospun membrane had much lower ice
230 adhesion strength compared to an aluminum plate. Interestingly, infusion of the lubricant
231 reduced the ice adhesion strength even further. Although all the SLIPS have remarkable values
232 down to less than 1 KPa, SLIPS with paraffin oil had the best results with approximately 0.65
233 KPa ice adhesion strength which is lower than most of the reported studies [36]. The
234 significantly lower ice adhesion strength is associated with the following three aspects: 1) The

235 immiscibility of water-oil interface prevents water to produce ice anchors into the structure; 2)
236 SLIPS presents an ultra-smooth surface compared to any other solid and dry surfaces, allowing
237 ice to slide easily; and 3) The SLIPS offers very low surface tension of lubricants compared
238 with the most of solid surfaces. Low surface tension between lubricant-water interfaces
239 effectively prevents the formation of strong adhesion between lubricant and ice. It is also
240 worthy of note that all SLIPS demonstrated much better ice adhesion strength compared to
241 superhydrophobic surfaces which is considered as a good candidate for icephobic applications
242 [37].



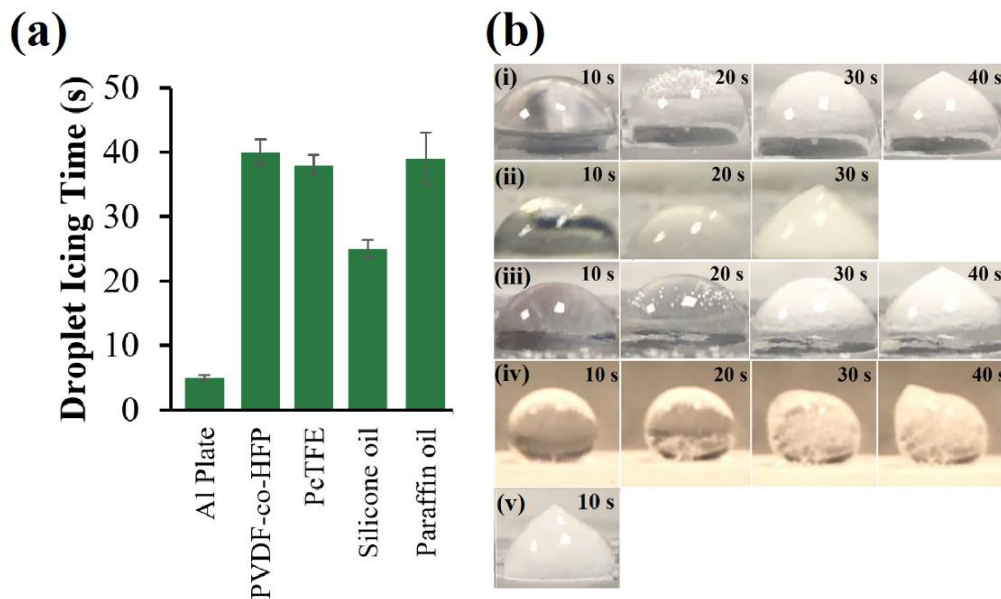
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244 **Figure 9.** Ice adhesion strengths of samples (Inset: ice adhesion test result of SLIPS with
245 silicon oil, paraffin oil and PcTFE, respectively)

246 The results of average droplet icing times with the images during icing process are given in
247 Figure 10. It was found that all of the designed structures had exceptional results compared to
248 the aluminum plate which has 5 seconds freezing time. The PVDF-co-HFP electrospun
249 membrane without any lubricant had the best results with more than 40 seconds icing time. It
250 has already been mentioned that this structure has more than 70% of porosity that means most
251 of the structure is only `air` which is a good thermal insulator. This structure also prevented

252 water droplets to freeze due to the thermal insulating effect of air. The SLIPS with PcTFE and
 253 paraffin oil has quite similar anti-icing behaviour with PVDF-co-HFP nanofibre membrane due
 254 to their significantly low thermal conductivities. It is believed that the anti-icing properties are
 255 more closely related to the surface structure, instead of chemical compositions [38]. However,
 256 SLIPS with silicone oil showed much lower icing time because of its much higher heat
 257 conduction ability. The thermal conductivities of PcTFE, liquid paraffin and silicone oil are
 258 0.065, 0.12 and 0.6 W/m/K, respectively. The water contact angle would also affect the droplet
 259 icing time. Lower contact angle of the droplet means larger contact area, then the heat
 260 resistance between the tested surface and the droplet would be reduced, causing to a decrease
 261 in icing time.

262



263

264 **Figure 10.** (a) Droplet icing times of samples, the images during the icing from the samples
 265 of SLIPS with (i) paraffin oil, (ii) silicon oil, (iii) PcTFE, (iv) PVDF-co-HFP nanofibre
 266 membrane and (v) Al plate.

267

268 4. CONCLUSIONS

269 In this study, we present a cost-effective and scalable electrospinning technique to produce
270 freestanding nanofibrous polymeric surfaces for the fabrication of transparent icephobic
271 SLIPS. Three liquids (PcTFE, silicon oil and paraffin liquid) were used as lubricants. The
272 topographical images of the samples showed that infusion of the lubricant provided smooth
273 surface which is one of the critical parameters for icephobic application. It was also found that
274 the mobility of the droplets on the SLIPS was enhanced dramatically compared to the as-
275 produced PVDF-co-HFP electrospun membrane. Because of the quite similar refractive indices
276 of lubricants and polymer, SLIPS with silicone oil and PcTFE showed transmittance as high as
277 90% in the visible light spectrum. All SLIPS exhibited low ice adhesion strength down to 1
278 KPa with icing delay time from 5 to 41 seconds. It is promising that these SLIPS surface can
279 be used for transparency and icephobicity required applications.

280 Acknowledgment

281 The authors would like to thank the Scientific and Technological Research Council of Turkey
282 (TUBITAK) for providing financial support to MAHMUT TAS with the program number
283 2213, the Nanoscale and Microscale Research Centre (nmRC) at University of Nottingham for
284 the access to instrumentation and Halocarbon for offering free PcTFE oil.

285

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