## Every quantum helps: Operational advantage of quantum resources beyond convexity

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Identifying what quantum-mechanical properties are useful to untap a superior performance in quantum technologies is a pivotal question. Quantum resource theories provide a unified framework to analyze and understand such properties, as successfully demonstrated for entanglement and coherence. While these are examples of convex resources, for which quantum advantages can always be identified, many physical resources are described by a non-convex set of free states and their interpretation has so far remained elusive. Here we address the fundamental question of the usefulness of quantum resources without convexity assumption, by providing two operational interpretations of the generalized robustness measure in general resource theories. First, we characterize the generalized robustness in terms of a non-linear resource witness and reveal that any state is more advantageous than a free one in some multi-copy channel discrimination task. Next, we consider a scenario where a theory is characterized by multiple constraints and show that the generalized robustness coincides with the worst-case advantage in a single-copy channel discrimination setting. Based on these characterizations, we conclude that every quantum resource state shows a qualitative and quantitative advantage in discrimination problems in a general resource theory even without any specification on the structure of the free states.

**Introduction**.— The drive to interpret and characterize signature properties of quantum mechanics spurred the rise of quantum information theory and shed new light on foundational questions of modern science [1]. The further realization that such properties can be exploited as *resources* to enhance computational power, sensing precision, communication security, and many more tasks unlocked a technological overhaul whose impact is unfolding at an astounding pace [2]. Under the hood of such impressive advances, key questions remain: What fundamental ingredients are needed for the optimal performance of quantum technologies? Does *every* quantum feature lead to an advantage in practical applications?

Addressing these and related questions can be facilitated by the study of quantum resource theories (QRTs) [3-5], which classify quantum states and operations into free (not useful, akin to 'classical') versus non-free (potentially useful as 'resources'), and provide a mathematically rigorous formalism to validate various measures of quantum properties and investigate their operational significance. The generalized robustness [6–8] is one such prominent quantifier in the framework of QRTs. It is calculable with semidefinite programming for several representative cases, including *k*-entanglement [9], coherence [10], multilevel coherence [11], asymmetry [12], magic [13, 14], and steering [15]. It also has an operational characterization, which was initially shown for steering [15], coherence [10], and asymmetry [12]. Notably, Ref. [16] generalized these results showing that, in any convex QRT on finite-dimensional state spaces, the generalized robustness can be interpreted operationally as the advantage of a quantum resource state in some channel discrimination task [17-20]. This result was recently extended to dynamical resource theories [21, 22], general probabilistic theories [21], and infinitedimensional convex QRTs [23, 24]. However, these analyses heavily rely on the convex geometry of the set of resourcefree states, which guarantees the connection between the generalized robustness and *resource witness* [25, 26]. A straightforward generalization of these operational approaches is no longer applicable when the convexity assumption is dropped.

Nevertheless, physically well-motivated quantum resources do not necessarily have a convex structure. For example, non-Gaussianity is widely regarded as an advantageous or even essential resource for quantum optical technologies [27], yet the set of Gaussian states in continuous variable systems [28, 29] is non-convex. The set of quantum Markov chains [30], as well as the sets of states with no quantum discord [31, 32], e.g., classical-classical and classical-quantum states [33, 34], are also not convex. Furthermore, tailored resource theories in which physical limitations are identified from experimental constraints are not a priori expected to be built upon a convex set of free states. In fact, classical randomness can be regarded as a resource [35, 36], meaning that convexity itself may well be expensive in general. Hence, the current lack of techniques towards resources beyond convexity significantly impedes a unified understanding of fundamental advantages and limitations of quantum mechanical properties, which general QRTs [4, 5, 13, 16, 21-24, 36-54] aim to achieve.

In this Letter, we bridge this gap by providing universal operational characterizations for general QRTs without convexity restriction, based on the generalized robustness (see Fig. 1).

On the one hand, we consider a concept of *multi-copy re-source witness*, extending ideas previously investigated in entanglement theory [55, 56]. Resource witnesses are instrumental in detecting the usefulness of entanglement [57] and any convex resource [16]. We provide a characterization of the generalized robustness in arbitrary dimensions and exploit it to give general constructions of multi-copy witnesses. This allows us to prove that *all* resource states in general QRTs (re-

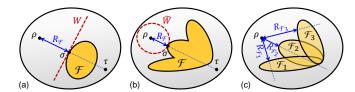


FIG. 1. Generalized robustness  $R_{\mathcal{F}}$  of a state  $\rho$  in (a) convex and (b)– (c) non-convex QRTs [Def. 1]. The first two panels illustrate the link between  $R_{\mathcal{F}}$  and witness operators, respectively for (a) the convex case [16] and (b) the non-convex case [Thm. 2]. Panel (c) depicts the evaluation of  $R_{\mathcal{F}}$  as minimization over convex subsets  $\mathcal{F}_k$  forming a non-convex set  $\mathcal{F}$  of free states [Eq. (7)]. Our constructions in (b) and (c) reveal qualitative [Thm. 3] and quantitative advantages [Thm. 4] of all non-free states of general QRTs in channel discrimination tasks.

gardless of the topology of free set) produce an operational advantage in some multi-input channel discrimination task.

On the other hand, we investigate a scenario motivated by QRTs with possibly multiple constraints, that is, a case where the set of free states is composed in general of several different convex subsets. We find that the generalized robustness quantifies the *worst-case* advantage for channel discrimination with respect to each subset and thus captures the versatility of resource states in the presence of competing constraints.

Our results show that, without assuming convexity, every quantum state identified as not free in a general QRT has the potential to lead to an advantage in discrimination problems, and the generalized robustness is established as a universal indicator of such operational advantage. This answers the final question raised in the opening paragraph of this Letter.

In the following, we focus on exposing the main ideas and results concerning QRTs defined for quantum states. A companion paper [58] contains detailed proofs of the main results of this manuscript, more examples, and extensions to dynamical QRTs including quantum channels and instruments [21, 48, 49, 51, 59–73], as well as other tasks based on channel exclusion and weight-based resource measures [74–80].

Generalized robustness in general QRTs.— We consider general QRTs on a *d*-dimensional Hilbert space  $\mathcal{H}$  (for finite *d*). The set  $\mathcal{F}(\mathcal{H})$  of free states is defined as some closed subset of the set  $\mathcal{D}(\mathcal{H})$  of all states of the system  $\mathcal{H}$ . The generalized robustness resource quantifier is defined as follows.

**Definition 1.** Let  $\rho \in \mathcal{D}(\mathcal{H})$  be a quantum state. The generalized robustness  $R_{\mathcal{F}(\mathcal{H})}(\rho)$  of  $\rho$  with respect to the set  $\mathcal{F}(\mathcal{H})$  of free states is defined by (see Fig. 1)

$$R_{\mathcal{F}(\mathcal{H})}(\rho) \coloneqq \min_{\tau \in \mathcal{D}(\mathcal{H})} \left\{ s \ge 0 : \frac{\rho + s\tau}{1+s} \eqqcolon \sigma \in \mathcal{F}(\mathcal{H}) \right\}.$$
(1)

This captures how much the quantum state  $\rho$  can tolerate mixing with some other state  $\tau$  until all of its resource content is washed out. Note that we do not assume convexity of  $\mathcal{F}(\mathcal{H})$  while, conventionally, the notion of the generalized robustness has been studied for convex resource theories [7, 8, 10, 16].

A key feature underlying the operational interpretation of generalized robustness in convex QRTs [10, 16, 57] is the fact

that such a measure can be recast as the expectation value of an optimal *linear* resource witness, represented by a (red dashed) *straight* line in Fig. 1(a). Our first main result is to show that such a connection can still be established in nonconvex QRTs, but it requires the use of a multi-copy witness, that is, a *nonlinear* operator separating resource states from the generally non-convex set of free states, illustrated by the (red dashed) *curved* line in Fig. 1(b).

*Multi-copy resource witness based on generalized robustness.*— Here we construct a family of *m*-copy operators for each m = 2, 3, ..., d and then show that, for an arbitrary free state  $\sigma$ , there is at least one *m* such that the corresponding *m*copy witness can discern a given resource state  $\rho$  from  $\sigma$ . Our construction relies on the generalized Bloch representation of *d*-dimensional quantum states [81, 82]. Given a quantum state  $\eta \in \mathcal{D}(\mathcal{H})$ , we let  $\vec{x} \equiv (x_1, x_2, ..., x_{d^2-1})$  denote a generalized Bloch vector given by  $\eta = \frac{1}{d} \left( I + \sqrt{\frac{d(d-1)}{2}} \sum_{j=1}^{d^2-1} x_j \lambda_j \right)$ , where *I* is the  $d \times d$  identity matrix, and  $\{\lambda_j\}_j$  denote the  $d \times d$  generalized Gell-Mann matrices with normalization  $\text{Tr}[\lambda_i^{\dagger}\lambda_j] =$  $2\delta_{ij}$  [81, 82]. Take a resource state  $\rho \in \mathcal{D}(\mathcal{H}) \setminus \mathcal{F}(\mathcal{H})$  with generalized Bloch vector  $\vec{r} \equiv (r_j)$ . According to the characterization given in Ref. [83], for a fixed s > 0, any state  $\eta$  with generalized Bloch vector  $\vec{x}$  that can be written as  $\eta = \frac{\rho + s'\tau}{1+s'}$ using some  $0 < s' \leq s$  and  $\tau \in \mathcal{D}(\mathcal{H})$  must satisfy

$$S_{m,\rho,s}(\eta) \coloneqq S_m\left(\frac{1+s}{s}\eta - \frac{1}{s}\rho\right) \ge 0$$

for all m = 1, 2, ..., d, where  $S_m$  is defined recursively as  $S_m(A) := \frac{1}{m} \sum_{l=1}^m ((-1)^{l-1} \operatorname{Tr} [A^l] S_{m-l}(A))$  for an operator A, with  $m \ge 1$  and  $S_0(A) := 1$ . Note that  $S_1(A) = \operatorname{Tr}[A]$ , hence  $S_{1,\rho,s}(\eta) = 1 \ge 0$  is trivially satisfied for any state  $\eta \in \mathcal{D}(\mathcal{H})$ .

By definition,  $S_{m,\rho,s}$  is a degree-*m* real-valued polynomial with respect to  $\vec{x}$  for all m = 1, 2, ..., d and for any s > 0. Hence, for an arbitrary choice of *m* and *s*, there exists a Hermitian operator  $W_m(\rho, s)$  on  $\mathcal{H}^{\otimes m}$  such that  $\text{Tr} [W_m(\rho, s)\eta^{\otimes m}] = S_{m,\rho,s}(\eta)$  for all  $\eta \in \mathcal{D}(\mathcal{H})$ ; see [58] for an explicit construction. With this characterization, we show the following:

- 1.  $S_{m,\rho,s}(\rho) = S_m(\rho) \ge 0$  for all m = 2, 3, ..., d.
- 2. If  $s < R_{\mathcal{F}(\mathcal{H})}(\rho)$ , then for any free state  $\sigma \in \mathcal{F}(\mathcal{H})$ , there exists  $2 \le m \le d$  such that  $S_{m,\rho,s}(\sigma) < 0$ .
- 3. If  $s \ge R_{\mathcal{F}(\mathcal{H})}(\rho)$ , there exists a free state  $\sigma \in \mathcal{F}(\mathcal{H})$  such that  $S_{m,\rho,s}(\sigma) \ge 0$  for all  $m = 2, 3, \dots, d$ .

Thus, the family  $\mathcal{W}_{\rho,s} := (\mathcal{W}_m(\rho, s) : m = 2, 3, ..., d)$  of Hermitian operators satisfies the two conditions:  $\min_{m=2,3,...,d} \operatorname{Tr} [\mathcal{W}_m(\rho, s)\rho^{\otimes m}] \ge 0$ , and  $\min_{m=2,3,...,d} \operatorname{Tr} [\mathcal{W}_m(\rho, s)\sigma^{\otimes m}] < 0, \forall \sigma \in \mathcal{F}(\mathcal{H})$ . By defining  $\widetilde{\mathcal{W}}_m(\rho, s) := -C(\mathcal{W}(\rho, s) + \Delta_m(\rho, s)I^{\otimes m})$  with appropriate scalar  $\Delta_m(\rho, s) > 0$  and any normalization constant C > 0, we have that the family  $\widetilde{\mathcal{W}}_{\rho,s} := (\widetilde{\mathcal{W}}_m(\rho, s) : m = 2, 3, ..., d)$  defines a (multi-copy) resource witness for  $s < R_{\mathcal{F}(\mathcal{H})}(\rho)$ .

**Theorem 2.** Let  $\mathcal{H}$  be a d-dimensional Hilbert space. Let  $\rho \in \mathcal{D}(\mathcal{H}) \setminus \mathcal{F}(\mathcal{H})$  be a resource state. Then, we can construct

a family  $\widetilde{W}_{\rho,s} := (\widetilde{W}_m(\rho, s) : m = 2, 3, ..., d)$  of Hermitian operators such that

$$\max_{\substack{m=2,3,\dots,d}} \operatorname{Tr} \left[ \widetilde{W}_m(\rho, s) \rho^{\otimes m} \right] < 0,$$

$$\max_{\substack{m=2,3,\dots,d}} \operatorname{Tr} \left[ \widetilde{W}_m(\rho, s) \sigma^{\otimes m} \right] \ge 0, \quad \forall \sigma \in \mathcal{F}(\mathcal{H}),$$
(2)

*if and only if*  $s < R_{\mathcal{F}(\mathcal{H})}(\rho)$ *. In particular,* 

$$\sup \{s > 0 : \widetilde{W}_{\rho,s} \text{ is a witness} \} = R_{\mathcal{F}(\mathcal{H})}(\rho).$$

This result establishes a fundamental connection between generalized robustness and multi-copy witnesses in general QRTs. Moreover, when *s* grows closer to  $R_{\mathcal{F}(\mathcal{H})}$ , the family  $\widetilde{W}_{\rho,s}$  serves as a better witness, in the sense that it can detect more resource states. Indeed, if s' < s, then we see that [58]

$$\{\eta \in \mathcal{D}(\mathcal{H}) : \operatorname{Tr}[\widetilde{W}_m(\rho, s')\eta^{\otimes m}] < 0, \ \forall m = 2, 3, \dots, d\}$$
$$\subseteq \{\eta \in \mathcal{D}(\mathcal{H}) : \operatorname{Tr}[\widetilde{W}_m(\rho, s)\eta^{\otimes d}] < 0, \ \forall m = 2, 3, \dots, d\}.$$

*Example: Single-Qubit QRTs.*— To illustrate our result, let us consider the instance of single-qubit QRTs (d = 2).

In the single-qubit case, we can only focus on  $S_2$ . By definition, we have  $S_2(A) = (\text{Tr}[A]^2 - \text{Tr}[A^2])/2$ . Note that for a Hermitian operator  $\eta$  with Bloch vector  $\vec{x} \equiv (x_1, x_2, x_3)$ , the condition  $S_2(\eta) \ge 0$  can be written as  $x_1^2 + x_2^2 + x_3^2 \le 1$ , whose region is equivalent to the Bloch ball.

Fix a single-qubit state  $\rho$  with Bloch vector  $\vec{r} \equiv (r_1, r_2, r_3)$ . For any quantum state  $\eta$  with Bloch vector  $\vec{x}$ , we have

$$S_{2,\rho,s}(\eta) = \frac{1}{4} - \frac{\|\vec{r}\|^2}{4s^2} + \frac{(1+s)(\vec{r}\cdot\vec{x})}{2s^2} - \frac{(1+s)^2\|\vec{x}\|^2}{4s^2}.$$
 (3)

Now, we construct a 2-copy witness  $W(\rho, s)$  such that  $\operatorname{Tr}[W(\rho, s)\eta^{\otimes 2}] = S_{2,\rho,s}(\eta)$ . One such witness is given as [58]  $W(\rho, s) := \left(\frac{\|I^{n}\|^{2}}{s^{2}} - 1\right)I \otimes I + \frac{(1+s)}{s^{2}} \sum_{j=1}^{3} \left[(1+s)(\sigma_{j} \otimes \sigma_{j}) - r_{j}(I \otimes \sigma_{j} + \sigma_{j} \otimes I)\right]$ , where  $(\sigma_{1}, \sigma_{2}, \sigma_{3})$  are the Pauli matrices. The operator  $W(\rho, s)$  defines a spherical boundary around the state  $\rho$  within the Bloch sphere, with radius proportional to s. It amounts to a witness when s is smaller than the generalized robustness of  $\rho$ . The larger s is, the more effective  $W(\rho, s)$  is as a witness. In the limit of  $s \to R_{\mathcal{F}(\mathcal{H})}(\rho)$ , the boundary is tangent to the free set  $\mathcal{F}(\mathcal{H})$ , denoting an optimal witness [see Fig. 1(b)].

**Operational advantage in multi-input channel discrimination**.— The multi-copy witness constructed in the previous section leads to an operational advantage of all resource states in general QRTs without convexity restriction for a variant of channel discrimination, which we call *m-input channel discrimination*. In *m*-input channel discrimination, one aims to distinguish channels that act on *m* independently and identically distributed (i.i.d.) copies  $\rho^{\otimes m}$  of a given state  $\rho$  in a black box setting. Let  $\{p_i, \Lambda_i^{(m)}\}_i$  be an ensemble of channels, where channels  $\Lambda_i^{(m)}$  on  $\mathcal{D}(\mathcal{H}^{\otimes m})$  are randomly picked with prior probability  $p_i$ . Once a channel  $\Lambda_i^{(m)}$  is sampled, it acts on the *m*-copy register of the given probe state  $\rho$ ; that is, at the output, we have  $\Lambda_i^{(m)}(\rho^{\otimes m})$ . Our goal is to figure out which specific channel from the channel ensemble acted on the input state. To identify the label *i*, we perform a quantum measurement  $\{M_i\}_i$  to the output state. The success probability for this *m*-input channel discrimination task is given by

$$p_{\text{succ}}\left(\left\{p_{i},\Lambda_{i}^{(m)}\right\}_{i},\left\{M_{i}\right\}_{i},\rho^{\otimes m}\right) \coloneqq \sum_{i}p_{i}\operatorname{Tr}\left[M_{i}\Lambda_{i}^{(m)}(\rho^{\otimes m})\right].$$
 (4)

In this task, given a quantum state and a channel ensemble, we aim to maximize the success probability by choosing the best measurement strategy. This task generalizes a single-copy channel discrimination task in Ref. [16] to the multi-copy scenario. To characterize the advantage of a resource state  $\rho$  in this scenario, we consider the ratio between the best success probability when using the given state  $\rho$  versus a free state.

Theorem 2 shows that for any given *d*-dimensional resource state  $\rho$ , we may construct a family  $\widetilde{W}_{\rho,s} = (\widetilde{W}_m(\rho, s) : m = 2, 3, ..., d)$  such that for any free state  $\sigma \in \mathcal{F}(\mathcal{H})$ , at least one  $\widetilde{W}_m(\rho, s)$  separates  $\rho^{\otimes m}$  from  $\sigma^{\otimes m}$ . This separation implies that *all resource states* in a general QRT without convexity restriction enable an operational advantage, formalized as follows.

**Theorem 3.** Let  $\mathcal{H}$  be a d-dimensional Hilbert space. For any resource state  $\rho \in \mathcal{D}(\mathcal{H}) \setminus \mathcal{F}(\mathcal{H})$ , there exists a family of channel ensembles  $(\{p_i, \Lambda_i^{(m)}\}_i)_{m=2}^d$  such that

$$\min_{\sigma \in \mathcal{F}(\mathcal{H})} \max_{m=2,3,\ldots,d} \frac{\max_{\{M_i^{(m)}\}_i} p_{\text{succ}}(\{p_i, \Lambda_i^{(m)}\}_i, \{M_i^{(m)}\}_i, \rho^{\otimes m})}{\max_{\{M_i^{(m)}\}_i} p_{\text{succ}}(\{p_i, \Lambda_i^{(m)}\}_i, \{M_i^{(m)}\}_i, \sigma^{\otimes m})} > 1.$$

This can be proven by considering an *m*-input channel discrimination with two channels for each m = 2, 3, ..., d, based on the witness  $\widetilde{W}_{\rho,s}$ . The proof strategy is inspired by those in Refs. [57] and [16], and a detailed proof is reported in [58].

*Remark.* While our construction requires  $m \le d$  inputs to reveal a discrimination advantage based on the generalized robustness, experimentally friendlier witnesses can be crafted just for detecting resource states in non-convex QRTs. Consider the operator  $W'_2(\rho, \varepsilon) := V + (\text{Tr}[\rho^2] - \varepsilon) I \otimes I - 2\rho \otimes I$ that can be implemented on 2 copies of  $\rho$ , where  $\varepsilon > 0$  and V is the swap operator,  $V |\psi\rangle \otimes |\phi\rangle = |\phi\rangle \otimes |\psi\rangle$  [84]. We have  $\text{Tr}[W'_2(\rho, \varepsilon)\eta^{\otimes 2}] = \text{Tr}[(\rho - \eta)^2] - \varepsilon$  for any state  $\eta$ . This defines an  $\varepsilon$ -ball around  $\rho$ , yielding a universal resource witness that satisfies Eqs. (2) with m = 2 for any d, if  $\varepsilon$  is small enough so that  $\text{Tr}[(\rho - \sigma)^2] \ge \varepsilon$  for all free states  $\sigma \in \mathcal{F}(\mathcal{H})$ .

**Operational advantage quantified by generalized robustness.**— In the previous section, based on the multi-copy witness constructed from generalized robustness, we showed a *qualitative* advantage of all resource states for channel discrimination in the framework of non-convex QRTs. The next question is whether we can provide a *quantitative* assessment of the operational advantage in general. Here we address this question by considering a slight variation of the problem.

Suppose that the set  $\mathcal{F}(\mathcal{H})$  of free states of an arbitrary QRT

can be expressed without loss of generality as a union

$$\mathcal{F}(\mathcal{H}) = \bigcup_{k} \mathcal{F}_{k}(\mathcal{H}), \tag{5}$$

where the subsets  $\mathcal{F}_k(\mathcal{H})$  are closed and *convex* for all *k* [Fig. 1(c)], and *k* is either a discrete or continuous label. Such a decomposition is always possible (and generally not unique) and describes a QRT characterized by multiple constraints.

For example, in the theory of quantum discord [31, 32], the set of free 'classical-quantum' states is given by the union of the convex subsets of incoherent-quantum states with a fixed local basis [33]. From a practical perspective, for applications such as 3D magnetic field sensing [85], one needs states with coherence in a specific set of bases, e.g., x, y, and z bases for a qubit. In this case, the set of free states is the union of the set of incoherent states with respect to the given bases, covering the three main axes of the Bloch sphere, while any other state is a resource. In another context, thermodynamical machines such as engines or refrigerators operating between different thermal baths are specified by a set of free states given by the union of the convex subsets corresponding to each equilibrium temperature [86, 87]. Also in the context of multipartite entanglement, states in the union of the sets of partition-separable states with respect to different bipartitions cannot have genuine multipartite entanglement [88, 89]. For any state out of this non-convex set, genuine multipartite entanglement can be activated from many copies of the state, characterizing this non-convex set from a resource perspective [88, 89].

Now, given a general QRT described by multiple constraints (i.e., multiple free subsets), how do we characterize the usefulness of resource states? It is natural to introduce a worst-case scenario in which we consider the possible advantage that a given state can provide in a task when compared to each subset of free states, and then minimize such advantage over all such subsets. This approach will result in a figure of merit assessing how useful that particular state is a priori guaranteed to be, regardless of which particular constraints are coming into play in each run of the task. An instance of such analysis had been explored in metrological contexts --- that is, looking for the worst-case precision that a probe state enables in phase estimation with limited prior knowledge of the phase shift generator — and led to seminal operational interpretations for discord-like quantifiers [90–92], which can now be regarded as special cases of our more general construction.

Here, we consider a channel discrimination task specified by a channel ensemble  $\{p_i, \Lambda_i\}_i$  acting on a single copy of an input state, corresponding to m = 1 in the *m*-input protocol described earlier. We focus on the achievable advantage of a resource state  $\rho$  with respect to states in each convex free subset  $\mathcal{F}_k(\mathcal{H})$ , maximized over the measurement  $\{M_i\}_i$ . In formula,

$$\max_{\{p_i,\Lambda_i\}_i,\{M_i\}_i} \frac{p_{\text{succ}}(\rho,\{p_i,\Lambda_i\}_i,\{M_i\}_i)}{\max_{\sigma_k \in \mathcal{T}_k(\mathcal{H})} p_{\text{succ}}(\sigma_k,\{p_i,\Lambda_i\}_i,\{M_i\}_i)},$$
(6)

where  $p_{\text{succ}}$  denotes the success probability, which is given in Eq. (4). We then consider the worst-case advantage of  $\rho$ defined as the infimum of Eq. (6) over all free subsets  $\mathcal{F}_k(\mathcal{H})$ . Remarkably, we find that such a worst-case advantage is exactly quantified by the generalized robustness of  $\rho$ , Eq. (1).

**Theorem 4.** Let  $\mathcal{H}$  be a d-dimensional Hilbert space. Then, for any resource state  $\rho \in \mathcal{F}(\mathcal{H}) \setminus \mathcal{D}(\mathcal{H})$ ,

$$\inf_{k} \max_{\{p_i,\Lambda_i\}_i,\{M_i\}_i} \frac{p_{\text{succ}}(\rho,\{p_i,\Lambda_i\}_i,\{M_i\}_i)}{\max_{\sigma_k \in \mathcal{F}_i(\mathcal{H})} p_{\text{succ}}(\sigma_k,\{p_i,\Lambda_i\}_i,\{M_i\}_i)} = 1 + R_{\mathcal{F}(\mathcal{H})}(\rho).$$

This result illustrates that the generalized robustness in a general QRT precisely quantifies the usefulness of resource states in worst-case channel discrimination tasks. Crucially, this result does not depend on the specifics of the decomposition of the set of free states into convex subsets, but it holds for any representation of the form (5), therefore standing as a universal staple of QRTs. We remark that when the set  $\mathcal{F}(\mathcal{H})$  of free states is convex, the infimum over *k* can be omitted, and Theorem 4 recovers the known result for convex QRTs [16].

We now outline the proof, which consists of two main ingredients: (i) the results of [16] for convex QRTs, and (ii) the generalized robustness in the worst-case scenario. Let us fix an index *k*, and consider the corresponding convex free subset  $\mathcal{F}_k(\mathcal{H})$ . We can apply the result for convex QRTs [16] to  $\mathcal{F}_k(\mathcal{H})$ ; for any state  $\rho \in \mathcal{D}(\mathcal{H})$ , we have the characterization

$$\max_{\{p_i,\Lambda_i\}_i,\{M_i\}_i} \frac{p_{\text{succ}}(\rho,\{p_i,\Lambda_i\}_i,\{M_i\}_i)}{\max_{\sigma_k \in \mathcal{F}_k(\mathcal{H})} p_{\text{succ}}(\sigma_k,\{p_i,\Lambda_i\}_i,\{M_i\}_i)} = 1 + R_{\mathcal{F}_k(\mathcal{H})}(\rho).$$

Now, we consider the worst-case advantage; mathematically, we take the infimum over the index *k* on both sides. It only remains to evaluate  $\inf_k R_{\mathcal{F}}(\rho)$ . Observing that an optimal free state  $\sigma \in \mathcal{F}(\mathcal{H})$  should belong to one of the convex subsets  $\mathcal{F}_k(\mathcal{H})$ , we have the following identity, concluding the proof,

$$\inf_{k} R_{\mathcal{F}_{k}(\mathcal{H})}(\rho) = R_{\mathcal{F}(\mathcal{H})}(\rho).$$
(7)

Conclusion.— In this Letter, we tackled two outstanding problems: (i) Can every quantum state provide an advantage in informational tasks without the need to introduce additional constraints? and (ii) if yes, can such an advantage be quantified in general terms? We answered both questions in the affirmative by providing two different yet related characterizations of the generalized robustness in generally non-convex QRTs. First, we introduced a multi-copy resource witness in *d*-dimensional QRTs without convexity assumption, which guarantees that there exists a family of multi-input channel discrimination tasks in which all resource states show an operational advantage. Second, we showed that the generalized robustness exactly quantifies the operational advantage of a resource state in a single-copy channel discrimination task when a worst-case scenario is considered. In this setting, the nonconvex set of free states can be expressed as the union of multiple convex subsets, and the generalized robustness amounts to the minimum of all possible advantages that a resource state can achieve with respect to each free subset. Taken together, our results enhance the domain of applications of QRTs and

establish a fundamental stepping stone in the ongoing translation of quantum science into quantum technologies, by establishing that meaningful *quantumness* can be identified without any need for convexity requirements, and that such quantumness can be directly exploited for practical applications.

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