

A new regression model to predict BIPV cell temperature for various climates using a high-resolution CFD microclimate model

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Abstract

Understanding of cell temperature of Building Integrated Photovoltaics (BIPV) is essential in the calculation of their conversion efficiency, durability and installation costs. Current PV cell temperature models mainly fail to provide accurate predictions in complex arrangement of BIPVs under various climatic conditions. To address this limitation, this paper proposes a new regression model for prediction of the BIPV cell temperature in various climates and design conditions, including the effects of relative PV position to the roof edge, solar radiation intensity, wind speed, and wind direction. To represent the large number of possible climatic and design scenarios, the advanced technique of Latin Hypercube Sampling was firstly utilized to reduce the number of investigated scenarios from 13,338 to 374. Then, a high-resolution validated full-scale 3-dimensional Computational Fluid Dynamics (CFD) microclimate model was developed for modelling of BIPV's cell temperature, and then was applied to model all the reduced scenarios. A nonlinear multivariable regression model was afterward fit to this population of 374 sets of CFD simulations. Eventually, the developed regression model was evaluated with new sets of unused climatic and design data when a high agreement with a mean discrepancy of 3% between the predicted and simulated BIPV cell temperatures was observed.

Keywords: Building, BIPV, Latin Hypercube Sampling, Regression, CFD

Nomenclature

T_c	PV cell temperature	K	T_a	Ambient air temperature	K
k_r	Ross coefficient	$\text{m}^2\text{K}/\text{W}$	G_t	Solar irradiance	W/m^2
U	Wind speed	m/s	C_a, C_b	SNL model coefficients	
ΔT	Difference of T_c and back surface temperature under G_o	K	x, y, z	Computational cell length in three dimensions	m
L, W, H	Dimension of objects	m	u	Fluid velocity	m/s
p	Fluid pressure	pa	Q'_c	Convective heat flux	W/m^2
G_o	Reference solar radiation	W/m^2	ρ	Air density	kg/m^3
\vec{g}	Gravitational acceleration	m/s^2	$\bar{\tau}_{eff}$	Effective stress tensor	
μ_{eff}	Effective viscosity	m^2/s	\bar{I}	Unit tensor	
μ_t	Eddy viscosity	m^2/s	μ	Sum of molecular viscosity	m^2/s
ρ_0	Constant density under operating temperature T_0	kg/m^3	G_k	Mean velocity gradient contributed to k	W/m^3
β	Thermal expansion	$1/\text{K}$	k	Turbulence kinetic energy	J/kg
ε	Turbulence dissipation rate	m^2/s^3	T_0	Operating temperature	K

G_b	Buoyancy contributed to k	W/m^3	S_k	User-defined source of k	
$\sigma_k, \sigma_\varepsilon$	Prandtl number for k and ε		C_μ	Model constant	
$C_{1\varepsilon}, C_{2\varepsilon}$	Model constants		S_ε	User-defined source of ε	
E	Energy of unit mass component	m^2/s^2	\bar{h}	Sensitivity enthalpy	m^2/s^2
λ_f	Flow thermal conductivity	W/mK	λ_t	Turbulence conductivity	W/mK
$\bar{h}_j \vec{j}_j$	Enthalpy transportation of diffusion	W/m^2	λ	Coefficient of thermal conductivity	W/mK
S_h	User-defined source of energy		S_r	Solar load	W/m^3
Q'	Heat flux	W/m^2	$\varepsilon_{m,r}$	Emissivity of exposed roof surface	
σ	Stefan-Boltzmann constant		T_{sky}	Sky temperature	K
T_r	Roof temperature	K	$\varepsilon_{m,s}$	Sky emissivity	
U_z	Local flow speed at H_z	m/s	U_{met}	Meteorological wind velocity	m/s
H_z	Local height	m	H_{met}	Height of meteorological station	m
α	Wind shear exponent		I_z	Local turbulence intensity	
δ_G	Terrain boundary thickness	m	k_z	Local turbulence kinetic energy	m^2/s^2
ε_z	Local turbulence dissipation rate	m^3/s^3	L_a	Vertical temperature gradient	K/m
E_r	Radius of the Earth	m	PI	PV position index	
θ	Relative wind angle	°	N	Population size	
n	Sample size		p_s	Sample proportion	
z_c	Critical value at a given confidence level		l	Distance between bottom edge of PV panel and roof	m
d	Margin of error		R^2	Coefficient of determination	
Y_i	Observed (simulated) value of each sample		\hat{Y}_i	Predicted value of each sample	
\bar{Y}_i	Mean of all observed value		k_{coeff}	Total number of coefficients in regression	
$RMSE$	Root mean square error		E_1	Relative gap	
$FAC2$	Fraction of predictions within a factor of two of observations				

25

26 1. Introduction

27 The share of renewable energy has increased in the world primary consumptions from
28 14% of global demands in 1998 to 19.3 % in 2015 (Goldemberg, 2000; Renewable Energy
29 Policy Network for the 21st Century [REN21], 2017). It is expected that renewable energy
30 share takes one quarter of the whole energy market by 2040 with an average annual increase
31 rate of 2.8% (Energy Information Administration [EIA], 2017) with a potential to be expanded
32 over a long-term period of time (up to 30-80% by 2100 according to Panwar, Kaushik, and
33 Kothari (2011)). Among the markets of clean energy, photovoltaic (PV) technologies have
34 shown a promising success during past years while it was predicted to keep permeating with
35 further improvements in PV's performances (REN21, 2017). Solar PVs are vastly integrated
36 or partially integrated to building roofs and façades, known as building integrated
37 photovoltaics (BIPV), converting solar energy into electricity on the site and supporting the
38 building energy demands (Elkarmi & Abu-Shikhah, 2012; Bramanti, 2015).

39 In ideal experimental conditions, the electrical efficiency of a typical PV system is 15-20 %
40 (Kalogirou, 2014). Accumulative heat impacted on a PV panel leads to the elevation of
41 surface/cell temperature (T_s/T_c) and thereby causes a drop of cell efficiency, normally
42 occurring when operating temperature exceeds 25 °C (Solanki, 2013), with a rate of -0.2 %/°C
43 to -0.45 %/°C for amorphous and crystalline-silicon-based PVs (Kalogirou, 2014). In addition,
44 the high temperature degrades the PV materials and hence shorten their durability, which is
45 expected as 30-35 years for such integrated systems (Bahaj, 2003). This implies that the PV
46 cell temperature should be controlled either with advanced mechanical cooling approaches

47 or alternatively with natural ventilation, particularly in hot climate where there is a high risk of
48 hot spot formations.

49 [Elkarmi and Abu-Shikhah \(2012\)](#) recommended an elaborative scrutiny of the installation
50 site before the PV implementation to access an optimum performance. This implies that, to
51 evaluate the reliability and feasibility of a BIPV project, tools are required to assess the near-
52 field airflow around cell surfaces and further to estimate their operating thermal behaviour.
53 [Skoplaki and Palyvos \(2009\)](#) undertook a literature review of methods to determine the PV
54 operating temperate, including implicit and explicit methods. The PV temperature given by
55 the former method depends on some variables relying on temperature, for example, the panel
56 efficiency, while the explicit method calculates temperature directly. In general, it is crucial
57 that these models should include the impact of surrounding environment in their calculations
58 although there were only few developed models finding T_c from its relation with the
59 surrounding environment. Example of such models is an explicit calculation by [\(Ross Jr, 1976\)](#):
60

$$T_c = T_a + k_r G_t \quad (1)$$

61 where T_a is the ambient air temperature (K), G_t is solar irradiance (W/m^2) and k_r is Ross
62 coefficient ($\text{m}^2\text{K}/\text{W}$); the adapted values of which are summarized from reference data
63 [\(Nordmann & Clavadetscher, 2003\)](#). Another example is a model to predict PV temperature
64 from a nominal operating cell temperature (NOCT) measured in the nominal terrestrial
65 environment (NTE) condition, also known as the standard reference environment, which is
66 specified as $800 \text{ W}/\text{m}^2$ irradiance normal to a free-running device mounted rack with an
67 optimum tilt ventilation against 1m/s wind at an ambient temperature of 20°C [\(Markvart & Bogus, 2000\)](#):
68

$$T_c = T_a + (T_{c,NOCT} - 20) \frac{G_t}{800} \quad (2)$$

69 where NOCT means the referring variable to the value at the nominal terrestrial environment.
70 Furthermore, a model was developed by Sandia National Laboratories (SNL) [\(King, Boyson, & Kratochvill, 2004; Skoplaki & Palyvos, 2009\)](#), which includes wind speed in its equation:
71

$$T_c = T_a + G_t \cdot (e^{C_a + C_b U}) + \frac{G_t}{G_o} \cdot \Delta T \quad (3)$$

72 where C_a and C_b are the model coefficients determined by the module type and mounting
73 method. U represents the wind speed (m/s), and ΔT is the temperature difference (K)
74 between the solar cell and rear surface measured under a reference solar radiation flux of
75 $G_o = 1000 \text{ W}/\text{m}^2$.

76 All these models included the effect of solar radiation and ambient temperature. However,
77 the effect of wind speed was only considered by SNL model via empirical coefficients,
78 depending on the module assemblies and mountings. The NOCT model only took a default
79 natural ventilation value against the wind of 1m/s whilst the ventilation effect was simply
80 inducted by assigning different array installations in the first model. In conclusion, none of
81 these methods took the influence of stochastic wind directions into the account, which can

be source of a huge discrepancy in the prediction of PV cell temperature. For example, an assessment undertaken by D'Orazio, Perna & Di Giuseppe (2014) within typical Italian climate showed that the deviation between the calculated temperature by NOCT and measurement was up to 12 °C while this value was 8°C between the SNL method and measurement. In another study by Assoa, Gaillard, Ménézo, Negri, & Sauzedde (2018), it was reported that NOCT model significantly overestimated the PV cell temperature while Ross coefficient failed to evaluate the heat dissipation due to the lack in consideration of the site wind conditions.

As another limitation, the current site surveying for BIPV installation was mainly focused on the solar data and overshadowing of surroundings, but seldom considering the wind effect (Bagatelos & Henson, 2012). There were few studies through field measurements that considered variation of weather conditions though entirely focused on wind speed rather than wind direction (Kaldellis, Kapsali, & Kavadias 2014; Gökmen, 2016). Despite of the well understood fact that PVs' natural cooling is impacted by the integration type, building geometry, and district planning with stochastic climates, there is scarce investigation, paying attention to the impact of these factors although difficult to predict, especially in complex urban morphologies. In conclusion, site survey and experimental techniques in measurement of PV cell temperature face a high operating cost and many difficulties for repetitive tests to minimize site-dependent influences, placing them as less preferred options. On the other side, Computational Fluid Dynamics (CFD) technique is considered as a promising approach to deliver quantitative studies due to its high flexibility and accuracy with less operating cost.

Table 1 Summary of previous CFD studies for the design of BIPVs

Authors	Type	Dimension	Turbulence model	Investigation
Hemmer, Saad, Popa & Polidori (2017)	BIPV	2D	laminar	Impact of mounting geometry impacts on convection
Wilson and Paul (2011)	BIPV	2D	laminar	
Gan (2009a, 2009b)	BIPV	2D	RNG k- ϵ turbulence	
Liao et al. (2005)	BIPV/T	2D	k- ϵ model	Convection beneath/ over PV
Jubayer, Karava, & Savory (2010)	BIPV/T	3D	Realizable k- ϵ / SST k- ω	Impact of:
Karava, Jubayer, Savory & Li (2012)	BIPV/T	3D		-Velocity (Liao, et al., 2005; Karava et al., 2012; Zogou & Stapountzis 2012; Zhang, 2017)
Teo, Lee & Hawlader (2012)	PV/T	3D	-	-Solar radiation (Liao, 2005; Zhang, et al., 2017)
Zogou and Stapountzis (2012)	BIPV/T	3D	k- ϵ model	-Wind direction (Karava, et al., 2012)
Zhang, Mirzaei and Carmeliet (2017)	BIPV	3D	Standard k- ϵ model	-PV tilt (Karava, et al., 2012)
Koyunbaba, Yilmaz & Ulgen (2013)	BIPV	2D	Standard k- ϵ model	-Active cooling at backside (Teo, et al., 2012)
ElSayed (2016)	BIPV	2D	k- ϵ model	Impact of velocity on thermal behavior
Mirzaei and Zhang (2015)	BIPV	3D	Standard k- ϵ model	
Jubayer (2014)	PV	3D	k- ω turbulence	Impact of wind on ground mounted stand-alone PV

CFD has been widely applied to reproduce thermal and velocity patterns around tested panels to find optimal BIPV designs. For example, the critical cavity size was found to be 0.02m by Wilson and Paul (2011), and 0.12-0.15 m and 0.14-0.16 m by Gan (2009a) for multi- and single module systems, respectively. Table 1 summarizes some of the recent CFD studies related to the design of BIPVs. As it can be seen in Table 1, most studies were focused on the cavity, but barely considering the airflow above the cell (Liao, et al., 2005; Gan 2009a, 2009b; Wilson & Paul, 2011; Koyunbaba, et al., 2013); although some investigated the nearfields around, only velocity field was analysed, but no thermal performance was included (Jubayer, et al., 2010; Karava, et al., 2012); furthermore, many of them also simulated the BIPV design in the limited range of variations; for example, only 0-20 degree wind directions were considered in (Karava, et al., 2012). Despite of the mentioned advantageous of CFD techniques in understanding of airflow and temperature fields around BIPVs, it is computationally impractical to investigate BIPVs with a 3D CFD model under a wide range of variation considering all influential parameters under more realistic climatic conditions, therefore, sensitivity tests of integrated PVs to different parameters are required.

Therefore, the aim of this study is to develop a high-resolution regression model to predict BIPVs' cell temperature, including effects of various PV design and climatic scenarios by taking advantage of a full-scale 3D CFD model, validated with a wind tunnel measurement study. The simulations of all these climatic and design scenarios are impractical as the enormous population size required to cover all of them; thus, the goal is to minimize the intensive computational load of the CFD model by only simulation of the representative samples of scenarios determined by using Latin Hypercube Sampling method. To calculate the minimum population size of the sampling method, a sensitivity analysis was initially conducted to reduce the strip amount of each variable. Finally, a new regression model was fit to the simulated scenarios and was successfully evaluated in prediction of the BIPV cell temperature under various climatic and design scenarios. It should be noted that developed CFD in this study is validated with the experimental data and has a high level of reliability and accuracy and will be used to evaluate the performance of the new regression models due to the limitation in access to the realistic experimental data.

133 2. Methodology

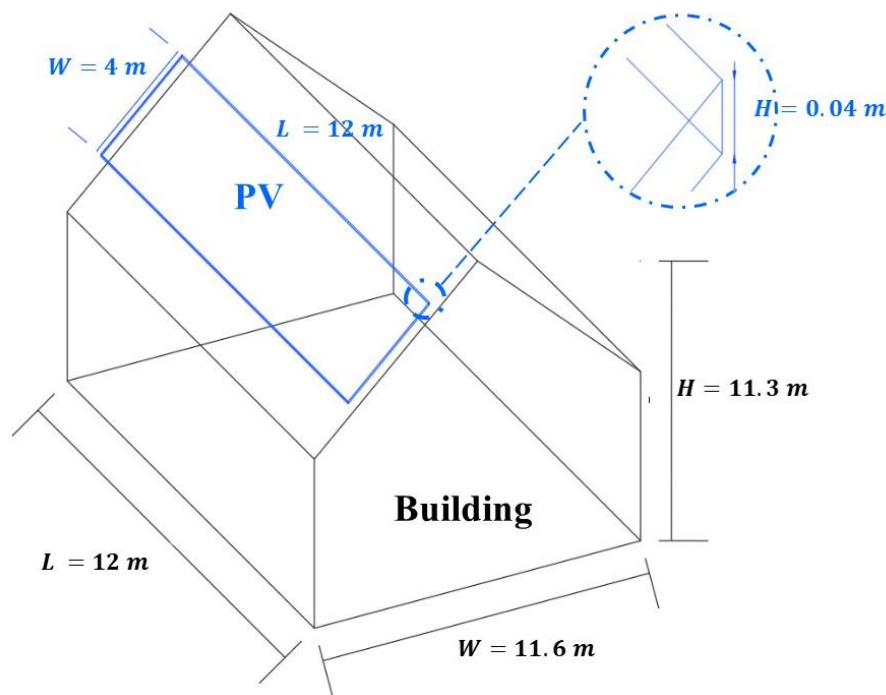


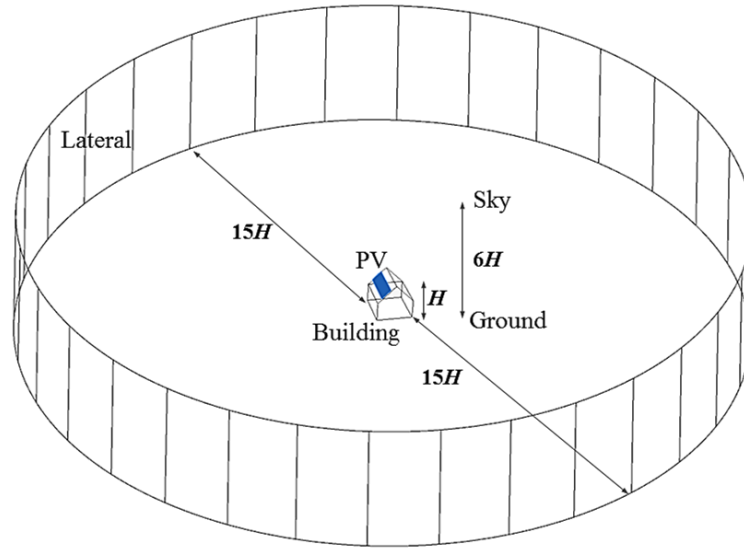
Figure 1 Full-scale BIPV construction

136 2.1. CFD modelling

137 2.1.1 Microclimatic and BIPV models

138 The computational model used in this study was developed from a properly validated
 139 CFD model representing BIPV in a wind tunnel experiment (Mirzaei, Paterna & Carmeliet,
 140 2014; Mirzaei & Carmeliet, 2015; Zhang, et al., 2017). The original model was enlarged to a
 141 full-scale BIPVs as shown in Figure 1. After removing the radiation simulator, the wind tunnel
 142 surfaces were then replaced with a cylindrical microclimate, which have a minor deviation in
 143 accuracy from the wind-tunnel model with the rectangular shape (Mirzaei & Carmeliet, 2013),
 144 although with a higher flexibility in capturing the stochastic approaching wind. The lateral wall
 145 of the cylindrical domain was placed far from the building by at least $15H$ (H is the height of
 146 the building) as shown in Figure 2 in accordance with the best practice guidelines (Tominaga,
 147 et al., 2008) to ensure the airflow from different directions reaching a fully developed condition.
 148 Also, the lateral wall was divided into multiple planes evenly to be able to assign the
 149 approaching winds from different directions. The sky boundary was settled at $5H$ above the
 150 building. The basic mesh configuration was generated based on a previous study of (Zhang,
 151 et al., 2017) to achieve a high agreement between CFD simulation and wind tunnel
 152 experiment. The average uncertainty of computational results of developed model from the
 153 measurements was found as 8.0% in overall with 13.2% in the cavity and 7.2% for the
 154 normalized velocity in the upstream region (Zhang, et al., 2017). In terms of the temperature
 155 field, the accuracy of developed computational model exceeds 95% and 90% for temperature
 156 predictions of the BIPV surface and its surrounding airflows, respectively. As only a slight
 157 difference is implemented in the quality of both meshes, the new CFD mesh was considered

158 to perform similarly as the validated wind tunnel mesh.



159
160 *Figure 2 Model of BIPV with cylindrical microclimatic domain*

161 A PV panel with the dimensions of 12 m × 4 m × 0.04 m ($L \times W \times H$) was integrated to
 162 the pitched roof of a full-size building with dimensions of 12 m × 11.6 m × 11.3 m ($L \times W \times$
 163 H). The PV panel covered 50 % of the roof area mounted parallel to the 45 ° inclined roof
 164 with an air cavity of 0.3 m; the fixed cavity distance satisfied the suggested minimum value
 165 to reduce the occurrence of overheating in the BIPV (Gan, 2009a). There are approximately
 166 0.16 million structured cells used to construct the BIPV and its nearby boundary layers (as
 167 seen in Figure 3) whilst the size of the whole model is about 1.85 million cells in the new
 168 mesh.

169 2.1.2 Governing equations

170 ANSYS FLUENT 18.1 was employed for modelling the fluid flow and heat transfer around
 171 the PV panels in this study. Standard wall-function treatment was applied to the boundary
 172 flow around the wall surfaces where dense inflated boundary layer grids were utilized. For all
 173 the simulations, the governing equations were Reynolds Averaged Navier-Stokes (RANS)
 174 scheme with the Standard $k-\varepsilon$ turbulence model under the steady-state conditions:

$$\frac{\partial}{\partial x_j} (u_j) = 0 \quad (4)$$

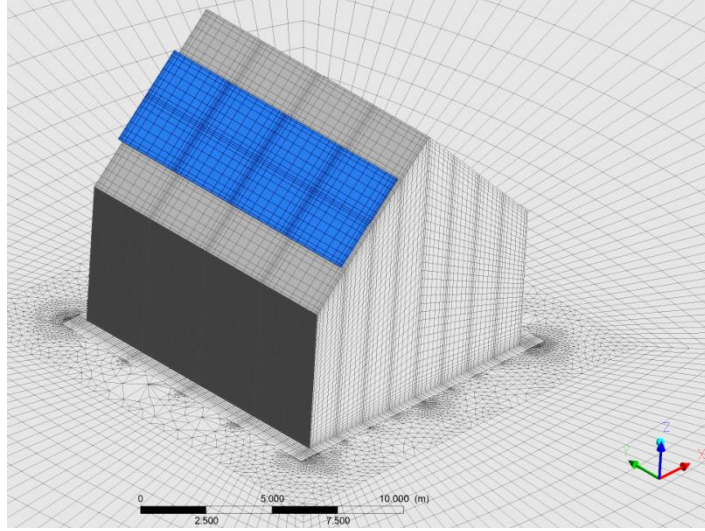


Figure 3 Computational grids of BIPV

$$\rho u_j \frac{\partial u_i}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \frac{\partial}{\partial x_j} \bar{\tau}_{eff} + \rho \vec{g} \quad (5)$$

where u is the airflow velocity (m/s), ρ is the air density (kg/m³), p is the pressure (pa). Subscripts i, j, k represent the three dimensions (i.e. 1, 2 and 3). $\bar{\tau}_{eff}$ is the effective stress tensor, which is given by:

$$\bar{\tau}_{eff} = \mu_{eff} \left[\left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) - \frac{2}{3} \frac{\partial u_i}{\partial x_i} \bar{I} \right] \quad (6)$$

where \bar{I} is the unit tensor and the effective viscosity, μ_{eff} is the sum of the molecular viscosity (μ) and eddy viscosity (μ_t):

$$\mu_{eff} = \mu + \mu_t \quad (7)$$

Term $\rho \vec{g}$ in Eq. (5) is representing the gravitational force where the buoyancy effect is reflected. Buossinesq approximation was used to determine the change of air density with temperature in this term:

$$(\rho - \rho_0)g \approx -\rho_0 \beta (T - T_0) \quad (8)$$

where ρ_0 is the constant density under the operating temperature T_0 (K) and β is the thermal expansion coefficient (K⁻¹). As $\beta(T - T_0)$ is much less than one in this study, the Boussinesq model is a valid assumption. Moreover, the Standard k - ε model was solved by the following equations for k and ε , respectively:

$$\frac{\partial}{\partial x_i} (\rho k u_i) = \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] + G_k + G_b - \rho \varepsilon + S_k \quad (9)$$

$$\frac{\partial}{\partial x_i}(\rho \varepsilon u_i) = \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_t}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{1\varepsilon} \frac{\varepsilon}{k} G_k - C_{2\varepsilon} \rho \frac{\varepsilon^2}{k} + S_\varepsilon \quad (10)$$

189 where G_k , G_b and S_k are the contributed k by mean velocity gradients, buoyancy and user-
 190 defined source, respectively. σ_k and σ_ε are the Prandtl number of turbulence k and ε ,
 191 respectively. $C_{1\varepsilon}$ and $C_{2\varepsilon}$ are model constants while S_ε represents ε generated by a user-
 192 defined source. With this model, the eddy viscosity (μ_t) can be calculated using the
 193 turbulence kinetic energy and dissipation rate as follows:

$$\mu_t = C_\mu \rho \frac{k^2}{\varepsilon} \quad (11)$$

194 where the default values of model constants are found as $C_\mu = 0.09$, $\sigma_k = 1.0$, $\sigma_\varepsilon = 1.3$, $C_{1\varepsilon} =$
 195 1.44 and $C_{2\varepsilon} = 1.92$. The energy of fluid region was also given by the following governing
 196 equation:

$$\rho u_j \frac{\partial E}{\partial x_j} = \frac{\partial}{\partial x_j} \left[(\lambda_f + \lambda_t) \frac{\partial T}{\partial x_j} \right] - p \frac{\partial u_j}{\partial x_j} - \frac{\partial}{\partial x_j} \sum_j \bar{h}_j \vec{J}_j + \frac{\partial u_j}{\partial x_j} \bar{\tau}_{eff} + S_h \quad (12)$$

197 where $E = \bar{h} - \frac{p}{\rho} + \frac{u^2}{2}$ and \bar{h} is the sensitivity enthalpy (m^2/s^2). λ_f and λ_t are the flow thermal
 198 conductivity and turbulence conductivity. Term $\sum_j \bar{h}_j \vec{J}_j$ indicates the enthalpy transportation
 199 due to the species diffusion. S_h is the user-defined source of energy.

200 Solar radiation was projected into the PV panel in a normal direction using a solar ray
 201 tracing model, which gave the source term in the energy equation of PV solid region as below:

$$\frac{\partial}{\partial x_j} \left(\lambda \frac{\partial T_c}{\partial x_j} \right) + S_r = 0 \quad (13)$$

202 where λ is the thermal conductivity (W/mK), T_c is the PV cell temperature (K) and S_r is the
 203 solar load (W/m^3) added to PV cells.

204 The roof of building was insulated from the ambient environment. As the PV panel
 205 covered only half of the roof area, the other half was exposed to the sunlight, which may
 206 cause overheating over the roof surface. The longwave radiative heat loss to the sky was
 207 then introduced at the exposed surfaces by editing the radiation boundary condition heat flux
 208 (Q') as:

$$Q' = \varepsilon_{m,r} \sigma (T_{sky}^4 - T_r^4) \quad (14)$$

209 where $\varepsilon_{m,r}$ is the emissivity of the exposed roof surface and σ is Stefan-Boltzmann constant
 210 $= 5.670367 \times 10^{-8} \text{ W/m}^2\text{K}^4$. T_{sky} and T_r are the sky and roof temperatures (K), respectively.
 211 T_{sky} was set at 285.13 K determined through (Gliha, Kruczek, Gh. Etemad & Thibault, 2011)
 212 by $T_{sky} = (\varepsilon_{m,s} T_a^4)^{1/4}$ where T_a is the air temperature set to be 298.15K in this study, and

213 $\varepsilon_{m,s} \approx 0.836$ is the sky emissivity approximated based on a range of the dew point
 214 temperature (Chen, Clark, Maloney, Mei & Kasher, 1995).

215 2.1.3 CFD setup and boundary conditions

216 Solar load was directly applied to the upward PV surface and the exposed roof. An
 217 assumption of no participation in solar model was made for the roof area covered by the PV
 218 panel and other building surfaces. The velocity pattern at the inflow boundaries was given by
 219 the exponent power law (Tominaga, et al., 2008):

$$U_z = U_{met} \left(\frac{H_z}{H_{met}} \right)^\alpha \quad (15)$$

220 where U_z is the local wind speed (m/s) at the height of H_z (m). U_{met} is the reference wind
 221 velocity (m/s) measured at the meteorological station where the data are collected at the
 222 height $H_{met} = 10$ m. $\alpha = 0.2$ is the wind shear exponent, which depends on the terrain
 223 description type and it was taken as a suburban terrain in this study. The vertical profiles for
 224 k and ε were estimated from the corresponding local turbulence intensity (I_z) given by the
 225 following equation (Tominaga, et al., 2008):

$$I_z = 0.1 \left(\frac{H_z}{\delta_G} \right)^{(-\alpha-0.05)} \quad (16)$$

226 where δ_G is the boundary thickness of a specific terrain taken as 450 m in this study. An
 227 acceptable assumption of the local turbulence kinetic energy (k_z) was utilized from I_z for the
 228 atmospheric boundary layer flow (Tominaga, et al., 2008):

$$k_z = (I_z U_z)^2 \quad (17)$$

229 The local ε_z values were then determined through:

$$\varepsilon_z = C_\mu^{1/2} k_z \frac{U_{met}}{H_{met}} \alpha \left(\frac{H_z}{H_{met}} \right)^{(\alpha-1)} \quad (18)$$

230 The air temperature is decreasing along the vertical direction in the troposphere
 231 (Department of Energy U.S. [DOE], 2016) and thus its profile was given by:

$$T_{a,z} = T_{a,met} - L_a \left(\frac{E_r H_{met}}{E_r + H_{met}} - \frac{E_r H_z}{E_r + H_z} \right) \quad (19)$$

232 where $T_{a,z}$ (K) is the local air temperature at elevation of H_z (m) from the ground and $T_{a,met}$
 233 (K) is the meteorological air temperature at its calculated height of H_{met} (m) in meteorological
 234 station of 1.5 m. $L_a = -0.0065$ K/m is the vertical temperature gradient and $E_r = 6356 \times 10^3$ m
 235 is the radius of the Earth.

236 *Table 2 CFD boundary conditions*

Boundary	Type	Treatment
----------	------	-----------

Ground / building surfaces	Wall	No-slip and adiabatic Not participate in the solar model Adiabatic/Insulated
Back & lateral surfaces of PV	Wall	No-slip and adiabatic Not participate in the solar model Coupled: zero heat generation
Sky/ laterals of the climatic domain	Symmetry	-
Front surface of PV	Wall	No-slip Absorptivity = 0.9 participate in the solar model Coupled: zero heat generation
Inflow	Velocity inlet	Vertical velocity profile Normal to the boundary Vertical k and ε profiles Vertical temperature profiles participate in the solar model
Outflow	Pressure outlet	Gauge pressure = 0 pa Vertical k and ε profiles Vertical temperature profiles participate in the solar model

Table 2 shows a summary of boundary conditions defined for the computational model in FLUENT 18.1 following recommendations by [Mirzaei and Haghighat \(2012\)](#). The absorptivity of the opaque dark PV surface was taken as 0.9 ([Reagan & Acklam, 1979](#)). SIMPLE algorithm was employed to solve the transport equations while all the transport equations were discretized with the second-order upwind scheme except the pressure, which was discretized with the second-order scheme. The convergence criterion was set as 10^{-6} for the energy equation while the values were set as 10^{-4} for the continuity, momentum and turbulence equations.

2.2. Sampling and sensitivity analysis

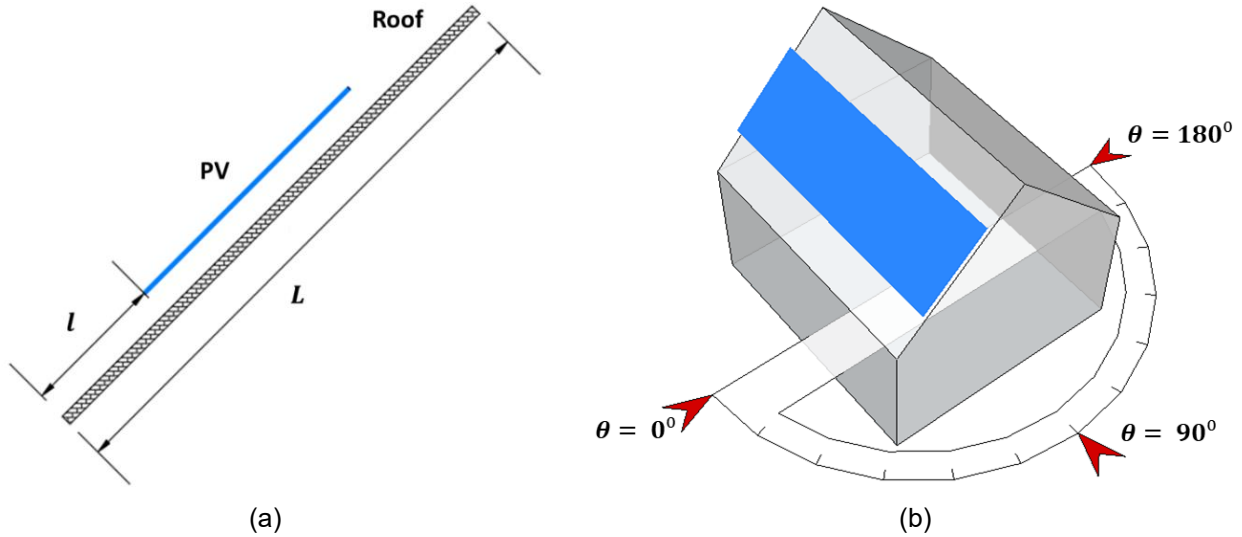
First, the thermal performance of PV panels was presented using the temperature difference between the cell and ambient (as the reference) temperatures. As a preliminary test, the influence of panel arrangement (stepped or flat) on its thermal performance was found to be insignificant, and thereby, only the flat PV arrangement was chosen to be simulated. Moreover, a new variable, PV position index (PI), was introduced to represent the relative location of the PV panel as the ratio of distance between the bottom and top edges of the PV panel over the roof width as seen in [Figure 4a](#):

$$PI = l/L \quad (20)$$

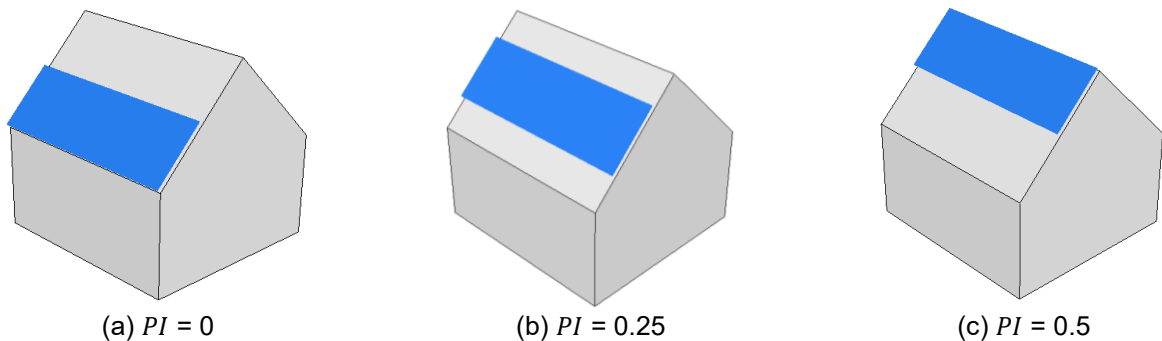
where l is the distance between the bottom and top edges of the PV panel. L is the width of the roof. In this study, three relative positions for the PV panel over the roof were considered, including the bottom ($PI = 0$), middle ($PI = 0.25$) and top ($PI = 0.5$) as displayed in [Figure 5](#).

Then, the investigation was designed to cover ranges of different climatic variables, including solar irradiance, wind direction and wind speed. A standard range of wind speed in Northern hemisphere is between 0-20 m/s with a highest frequency band lies in the range of

259 0-5m/s (Vautard, Cattiaux, Yiou, Thépaut & Ciais, 2010). However, the lowest wind speed
 260 was set as 0.5m/s rather than 0m/s, considering slow CFD convergence and $k-\varepsilon$ turbulence
 261 weakness in low Reynolds conditions. Furthermore, the solar irradiance was assumed to be
 262 uniformly distributed from 80 W/m² to 1,200 W/m² (King, et al., 2004). The stochastic relative
 263 wind angle was treated from $\theta = 0^\circ$ to $\theta = 180^\circ$, where $\theta = 0^\circ$ represents the direction of the
 264 BIPV orientation as shown in Figure 4b.



265 Figure 4 Schematic description of a) PV position index (PI) and b) relative wind angle
 266 (θ) Table 3 demonstrates the detailed value ranges for each variable. As it can be seen, there
 267 are numerous random permutation and combination of PV positions, solar radiation, wind
 268 direction and wind speed. Thus, it is practical to perform a sampling procedure to find only a
 269 limited number of scenarios required to be simulated with CFD that can technically represent
 270 the entire range of climatic conditions and PV positions. Before selecting samples through
 271 Latin Hypercube Sampling (LHS) method (Petropoulos & Srivastava 2016), a sensitivity test
 272 was conducted to determine the minimum strips of each microclimate variable, so that a
 273 smaller population size can be determined for the simulation. Latin Hypercube Sample
 274 method is a form of stratified sampling that applied to multiple variables. In principle, the
 275 method is to independently stratify each variable into N intervals with equal probability of 1/N
 276 and then to pick only one random sample point in every partition for each variable (Fang, Li
 277 & Sudjianto, 2005). It provides significant benefits in terms of sampling efficiency and
 278 computer processing time.



279 Figure 5 Schematic plot of the relative positions of PV panel over the roof and their corresponding PI

280
281

values

Table 3 Variable ranges and distributions for the sampling procedure

PV position (PI)					
Bottom		Middle		Top	Distribution
0		0.25		0.5	Uniform
Solar irradiance (G_t) & Relative wind angle (θ)					
		Left bound		Right bound	Distribution
G_t	80 W/m ²		1200 W/m ²		Uniform
θ	0°		180°		Uniform
Wind speed (U)					
Range	0.5 ~ 1 m/s	1 ~ 5 m/s	5 ~ 9 m/s	9 ~ 13 m/s	13 ~ 20 m/s
Frequency	0.0562	0.6387	0.2486	0.0456	0.0109

282 The benchmark case of the sensitivity analysis was defined as a PV panel mounted at
 283 the middle of the roof area ($PI = 0.25$) with a solar irradiance of 700 W/m² projected onto the
 284 surface while the wind was approaching opposite from the PV's orientation ($\theta = 180^\circ$) at a
 285 speed of 3 m/s. Table 4 lists the tested gaps of each variable for the parametric study of their
 286 impacts on the PV cell temperature (T_c) and PV surface convective heat transfer (q_c). For
 287 example, scenarios with solar irradiance of 750, 740 and 730 W/m² were tested to determine
 288 the sensitivity of T_c related to G_t while the critical interval was decided as one of the three
 289 studied gaps (i.e. 50, 40 and 30 W/m²) with respect to 700 W/m² in benchmark case as
 290 seen in Table 4.

291

Table 4 Benchmark case and parametric controls for the sensitivity analysis

	G_t (W/m ²)	U (m/s)	θ (°)
Benchmark	700	3	180
Gap to benchmark	50	2.5	33.75
	40	2	22.5
	30	1.5	11.25

292

Hence, the sample size (n) can be determined by (LeBlanc, 2004):

$$n = \frac{N z_c^2 p_s (1 - p_s)}{d^2 (N - 1) + z_c^2 p_s (1 - p_s)} \quad (21)$$

293 where N is the population size, z_c is the critical value at a given confidence level, p_s is the
 294 sample proportion and d is the error margin. In this study, the confidence level and the margin
 295 error were assumed to be 95 % and 5 %, respectively; this guaranteed 95 % of the true value
 296 of population with an allowance of random error up to 5 %. The critical value for the
 297 confidence level of 95 % is 1.96 while the value of p_s is usually as 0.5 to ensure that the
 298 sample size is large enough to reflect the whole population (LeBlanc, 2004).

After deciding the sample size, Latin Hypercube Sampling method (Petropoulos & Srivastava, 2016) was used to generate evenly distributed random numbers from 0 to 1 for each investigated variable. These random numbers were then mapped into the range of each variable to fit their corresponding real values. For example, a random number of 0.773 within the range of 0-1 was indexed to 786 W/m² from 80-1200 W/m² solar irradiance range.

2.3. Multivariable fitting

After obtaining all sample results, a new regression of the cell temperature versus microclimate conditions and PV positions was developed with a nonlinear correlation using MATLAB none-linear-fit (NLINFIT) function. The benchmark formats for the solar irradiance and wind speed in the new regression were referred to their formats in accordance with the previous empirical models (i.e. NOCT and SNL). Moreover, the formats of PI and θ were proposed with a preliminary analysis of the simulation data. Curve fitting tool in MATLAB was employed to obtain a rough initial guess of coefficients for NLILFIT function and then to identify an optimum coefficient value for each term with a given explicit function format.

The results of simulations and the regression model were compared using several metrics to assess the goodness of fitting, including the coefficient of determination (R^2), the adjusted coefficient of determination (*Adjusted R^2*) and the root mean squared error (*RMSE*):

$$R^2 = 1 - \frac{\sum_{i=1}^n (Y_i - \hat{Y}_i)^2}{\sum_{i=1}^n (Y_i - \bar{Y})^2} \quad (22)$$

$$Adjusted R^2 = 1 - (1 - R^2) \frac{n - 1}{n - k_{coeff}} \quad (23)$$

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (Y_i - \hat{Y}_i)^2} \quad (24)$$

where Y_i and \hat{Y}_i are the observed (simulated) and predicted values of each sample, respectively. \bar{Y} is the mean of all Y_i and k_{coeff} is the total number of coefficients to be determined in the regression. The values of R^2 and *Adjusted R^2* are within the range of 0-1 while a value closer to 1 means the regression covers more variability, thereby, is more successful in fitting to the dataset. Inversely, a smaller value of *RMSE* is expected for a better prediction.

2.4. Qualification metrics for regression validation

Extra 40 cases (more than 10 % of sample size without being used to develop the multivariable regression model) randomly selected by Latin Hypercube Sampling were simulated to assess the validity of proposed regression. Two qualification metrics were introduced in this stage, the relative gap (E_1) and the fraction of predictions within a factor of two of observations (*FAC2*):

$$E_1 = \frac{1}{n} \sum_{i=1}^n \left| \frac{Y_i - \hat{Y}_i}{Y_i} \right| \quad (25)$$

$$FAC2 = \frac{1}{n} \sum_{i=1}^n n_i \text{ with } n_i = \begin{cases} 1 & \text{if } 0.5 \leq \frac{\hat{Y}_i}{Y_i} \leq 2.0 \\ 0 & \text{else} \end{cases} \quad (26)$$

FAC2, as the one of the most robust qualification metrics, with a value closer to 1 indicates a perfect matching between predictions and the observations while a *FAC2* greater than 0.5 can be claimed as good enough criterion (Chang & Hanna, 2004).

3. Results

3.1. Sensitivity analysis and sampling results

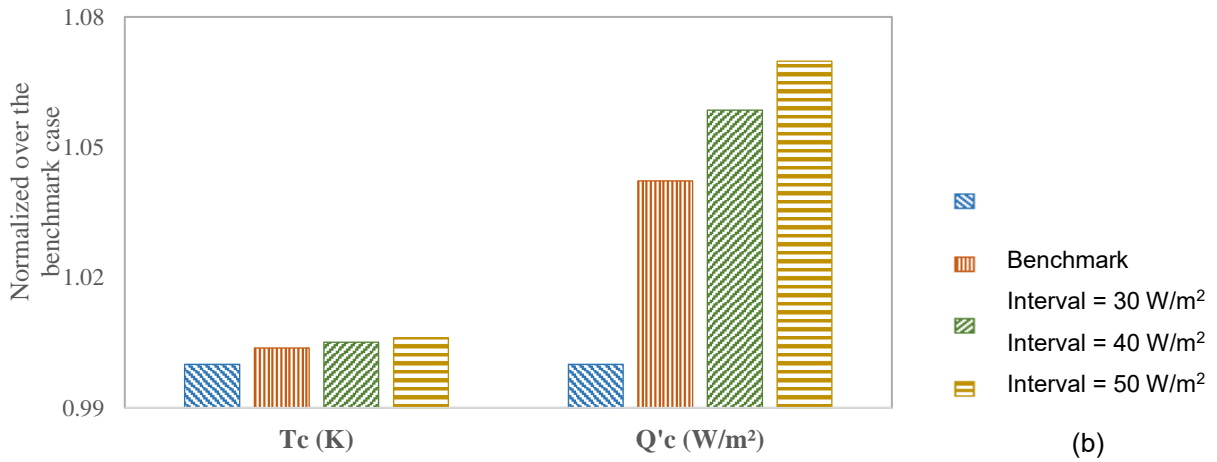
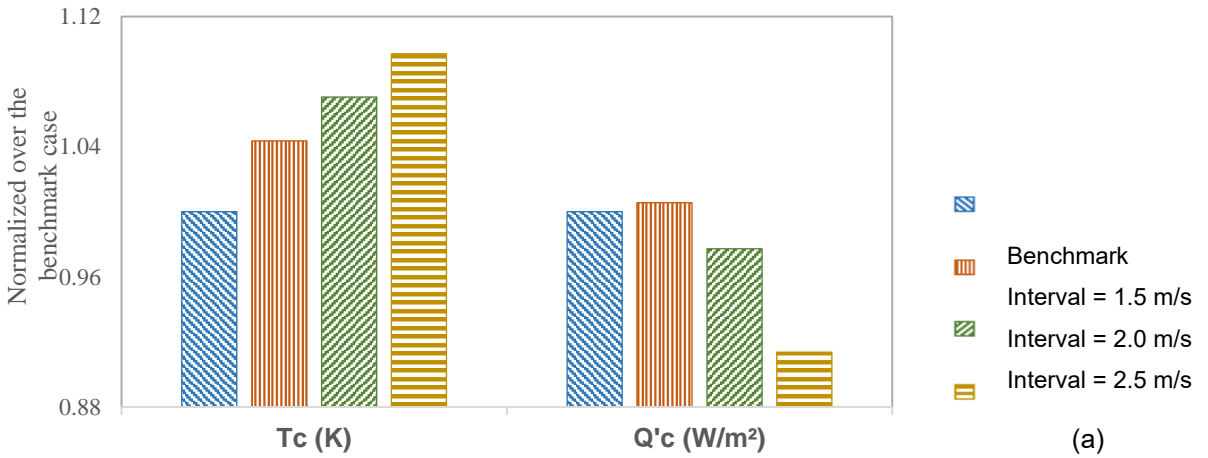
Normalized values over the results of the benchmark case were used to illustrate the sensitivity analysis. Therefore, the normalized PV cell temperature (T_c) and surface convective heat flux (Q'_c) for the benchmark case were defined as unity as seen in Figure 6. It is clear that the deviation of the normalized value of tested cases over unity is increasing with the interval growth of the tested variable when compared to the benchmark case. For example, in Figure 6a, deviations of 0.04 and 0.01 of T_c and Q'_c , respectively, were found for the case with a same PV position, similar solar irradiance and relative wind angle to the benchmark case although with having a different wind speed with a gap of 1.5 m/s. When increasing the interval to 2.5 m/s, the differences of T_c and Q'_c elevated to 0.1 and 0.09, respectively. A critical interval value was defined as the deviation of a case over the benchmark case equal or slightly less than 0.05 in accordance with the margin error of the sampling procedure. It is noteworthy that the increase of the critical interval contributes to the reduction of strip amount for each variable in the specific range and thus further leads to a smaller population size for the simulations. Thereby, the critical interval of wind speed was determined as 1.5 m/s.

Similarly, the critical interval for the solar irradiance was found to be 30 W/m² considering the change of Q'_c as shown in Figure 6b. As for the relative wind angle, seen in Figure 6c, both normalized T_c and q_c difference for cases with interval of 11.25° and 22.5° met the sensitivity requirement. To reduce the population size, 22.5° was then selected as the critical interval for the variable θ . Therefore, the minimum required numbers of strips for the solar irradiance, wind velocity and relative wind angle were calculated as 38, 13 and 9, respectively. Adding three installations of the BIPV, the sampling population size was identified as 13,338 while the minimum sample size was found as 374 according to Eq. 21.

3.2. Simulation results of sample population

Steady state simulations of all 374 sample cases were conducted until their convergences were guaranteed. The value of each variable (including wind speed, solar irradiance, relative wind angle and PV position) was unique throughout all the samples as

360 selected by Latin Hypercube Sampling method. This implies that there was no two samples
 361 with the same exact value for each variables. Therefore, comparisons were provided for
 362 samples to investigate the impact of different variables through a parametric study that values
 363 of the controlled variables were similar rather than same (only with differences less than 5 %
 364 or within the range of critical interval). For example, to explore the impact of solar irradiance,
 365 samples # 51 and #108 were selected with very different tested variable of G_t as 293 W/m^2
 366 comparing to $1,131 \text{ W/m}^2$, respectively. For the rest of variables, PI is the same ($PI = 0.25$
 367 for both samples) as a parametric study required; however, variable U is 3.98 m/s and
 368 3.95 m/s and θ is 46° and 53° for both samples, respectively due to sample limitation. The
 369 comparisons were performed through the temperature distribution plot as seen in [Figure 6-8](#).



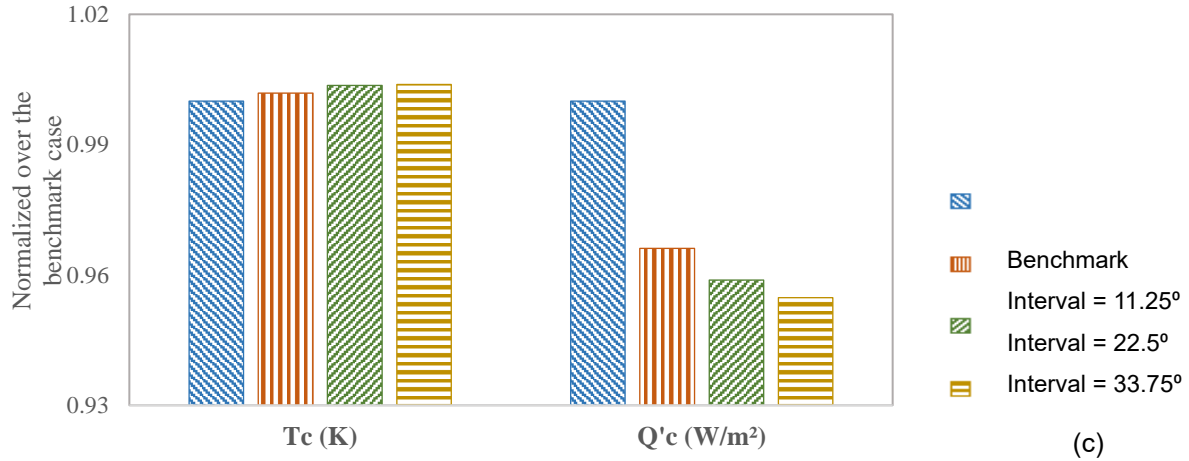


Figure 6 Normalized PV cell temperature (T_c) and surface convective heat flux (Q'_c) over the benchmark case results for the sensitivity analysis of a) wind speed of U ; b) solar irradiance of G_t and c) relative wind angle of θ

The solar irradiance (G_t) was found as the most important factor as it was similarly reflected in both existing empirical regressions (i.e. SNL and NOCT models). Based on the SNL model, the PV temperature decreases with increase of wind speed (U), however, the decreasing gradient becomes close to zero when U approaches to high values. The simulated results depicted consistent tendencies with SNL model's predictions. Figure 7 shows a comparison of the combined effect of the solar irradiance and wind speed. In these three selected samples, the highest PV temperature occurred under the scenario with a high solar irradiance and a low wind speed. The importance of parameters G_t and U can be clearly observed by comparing Figure 7a versus Figure 7b and Figure 7a versus Figure 7c.

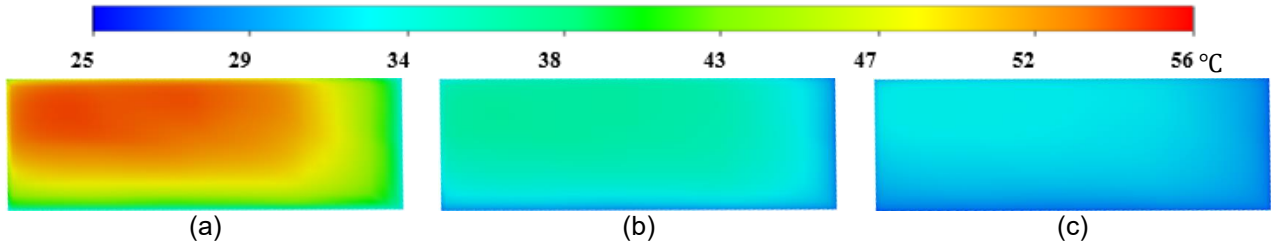


Figure 7 Temperature contour of the BIPV under scenarios of a) a high G_t with a low U ; b) a high G_t with a high U and c) a low G_t with a low U

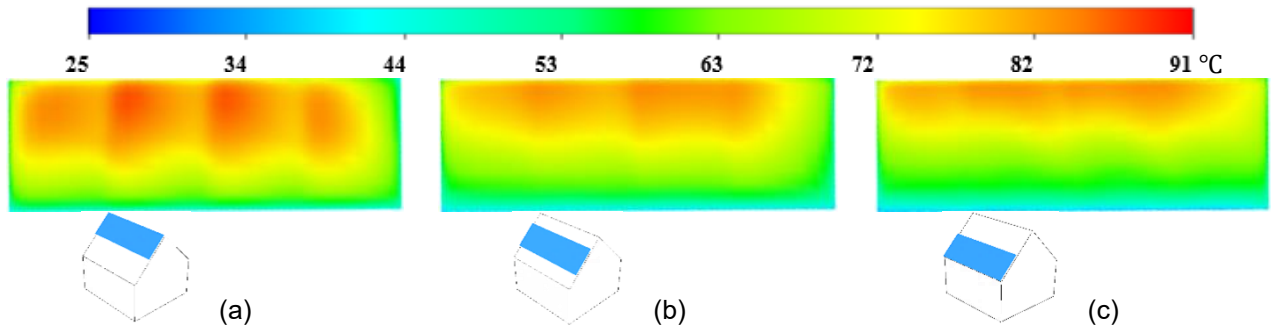


Figure 8 Temperature contour of the BIPV placed at positions of a) $PI = 0.5$; b) $PI = 0.25$ and c) $PI = 0$

Figure 8 compares the impact of different PV positions (PI) when the PV panels were exposed to a high solar radiation with a low speed wind approaching almost parallel to the direction of PV's orientation. As it can be seen, hot spot occurs at all three cases, however,

when the PV is placed closer to the top edge of the roof ($PI = 0.5$), the hot spot region becomes larger. It is noteworthy to specify that the solar irradiance in the scenario of [Figure 8a](#) (980 W/m^2) was even lower than that of for [Figure 8b](#) ($1,122 \text{ W/m}^2$) and [Figure 8c](#) ($1,151 \text{ W/m}^2$). This can be explained by the fact that the air becoming hotter when passing through the exposed hot roof surface and reaching to the top edge position.

[Figure 9](#) and [Figure 10](#) compare the impact of the relative wind angle (θ). The investigated PV panels in both figures were placed at $PI = 0$ where a clear difference in temperature contours can be observed between [Figure 9/10a](#), [Figure 9/10b](#) and [Figure 9/10c](#). Temperature gradient is more likely to be distributed in the streamwise direction in [Figure 9](#). As depicted in [Figure 10a](#), air is moving downward when wind approaches from backside ($\theta = 174^\circ$) and, therefore, a high temperature is captured at a relatively low position as seen in [Figure 9a](#). In contrast, a higher temperature can be seen at the upper part of the PV surface in [Figure 9c](#) when air is moving upward as seen in [Figure 10c](#). A higher risk of overheating is also found when wind approaches from the backside of the PV panel, which means the panels are at the leeward where surrounded by a relatively calm air. This is supported by the airflow pattern shown in the [Figure 10a](#). With a similar climatic wind speed, a lower local velocity is observed for larger relative wind angles (e.g., $\theta = 174^\circ$ compared to $\theta = 99^\circ$ or $\theta = 4^\circ$). Moreover, a complex hybrid impact of the relative wind angle and PV index can be seen in [Figure 9](#), which is further discussed in [Section 3.3](#).

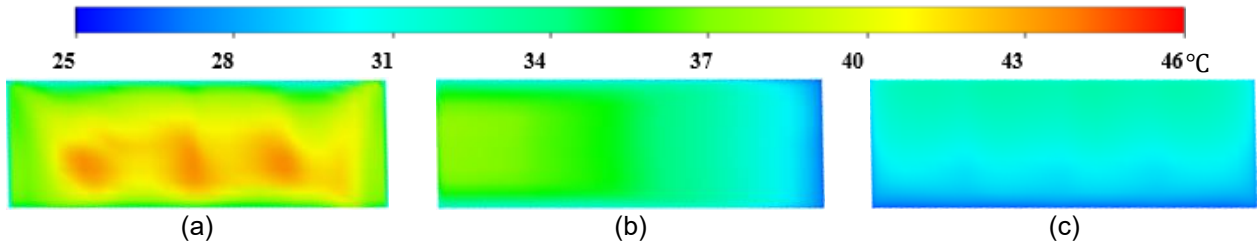


Figure 9 Temperature contour of the BIPV under scenarios of a) $\theta = 174^\circ$; b) $\theta = 99^\circ$ and c) $\theta = 4^\circ$

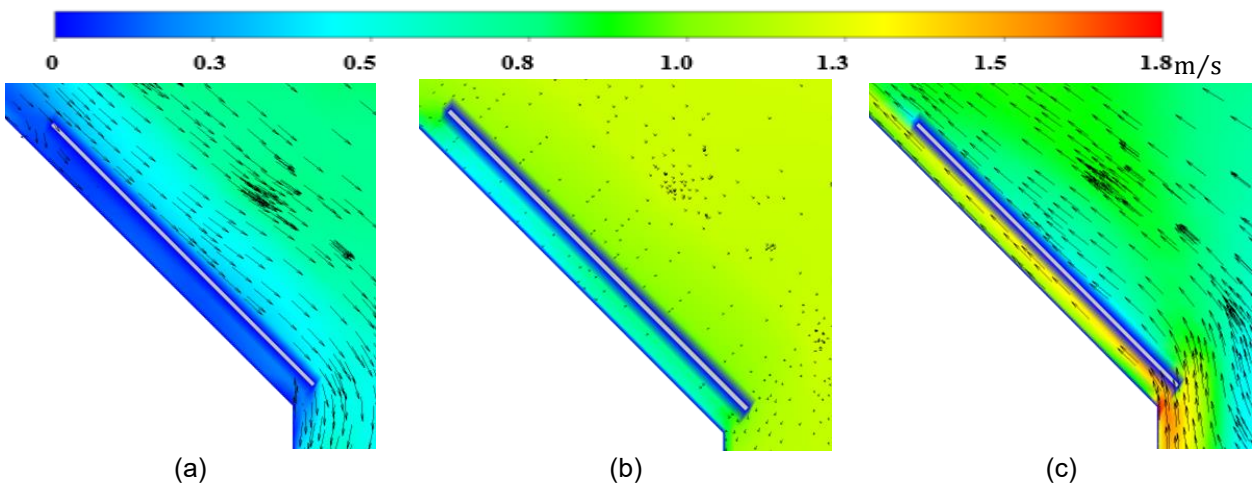


Figure 10 Velocity contour and vector plot of the airflow around BIPV under scenarios of a) $\theta = 174^\circ$; b) $\theta = 99^\circ$ and c) $\theta = 4^\circ$

3.3. New regression equation from simulations

As mentioned in [Section 2.2](#), the PV cell temperature was reported to be linearly related to the air temperature in all previous models. Hence, the new regression model was developed to predict temperature difference between T_c and T_a . Considering the tendency of temperature difference influenced by each variable, solar irradiance (G_t) was found as the most critical factor consistent with the expectations whilst the weighting of the PV position index (PI) was observed to be the lowest. The format of the new regression model was thus proposed as:

$$T_c - T_a = a_1 G_t^{a_2} \cdot e^{(a_3 U^{a_4} + a_5 U + a_6 \theta + a_7 PI)} + a_8 \theta \cdot PI + a_9 \quad (27)$$

where a_n are the constant coefficients and after optimization by NLINFIT function in MATLAB were found as $a_1 = 0.2743$, $a_2 = 0.8989$, $a_3 = -0.9832$, $a_4 = 0.5777$, $a_5 = 0.181$, $a_6 = 0.0018$, $a_7 = -0.0118$, $a_8 = -0.0424$, $a_9 = -0.9566$.

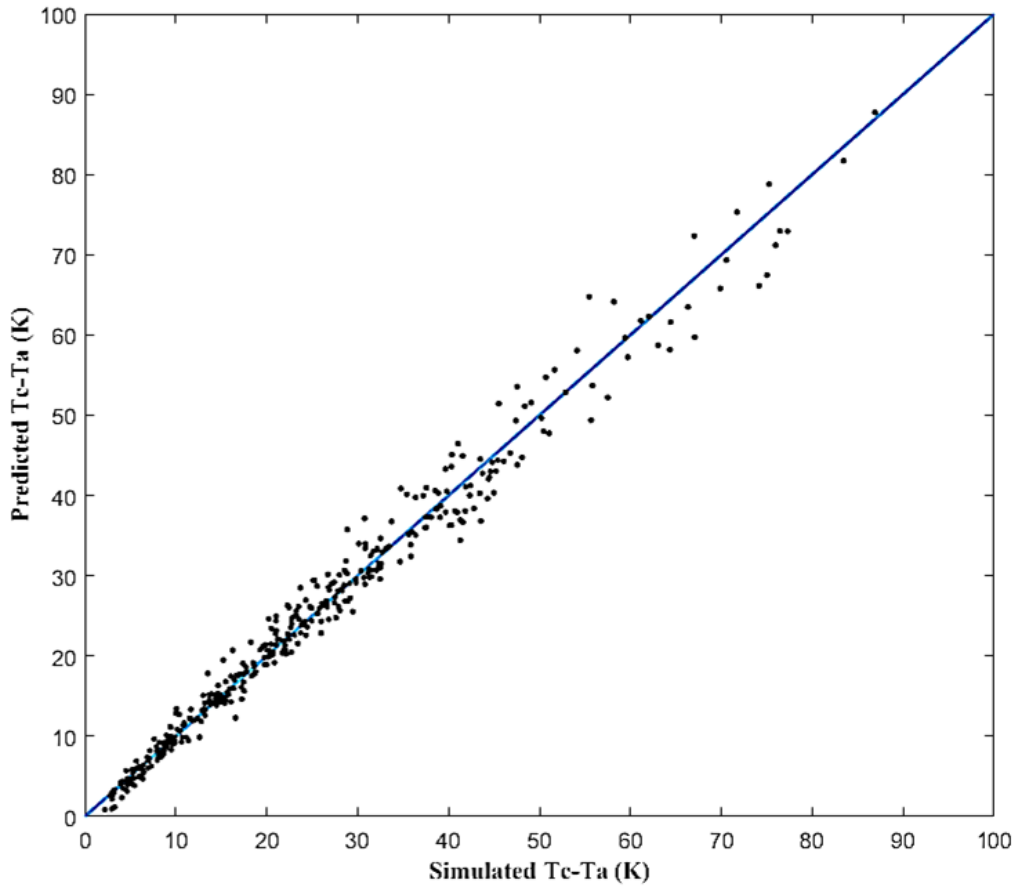


Figure 11 Prediction of $T_c - T_a$ by the proposed regression model (black dots) and simulation results (blue line)

The validity of the proposed regression model has been evaluated as displayed in [Figure 11](#). The predicted results distribute evenly around the blue straight line (with a gradient of unity), indicating the simulated values. The goodness of fitting evaluated from [Eq. 22-24](#) was reported as $R^2 = 0.9813$, $Adjusted R^2 = 0.9809$ and $RMSE = 2.3674$. Therefore, a high fitting quality was concluded from a high Adjust R^2 of 0.9809. As RMSE has the same unit as the

430 dependent variable, the value of 2.3674 K can be regarded as a small value in accordance
 431 with the range of $T_c - T_a$ defined between 0 K and 100 K.

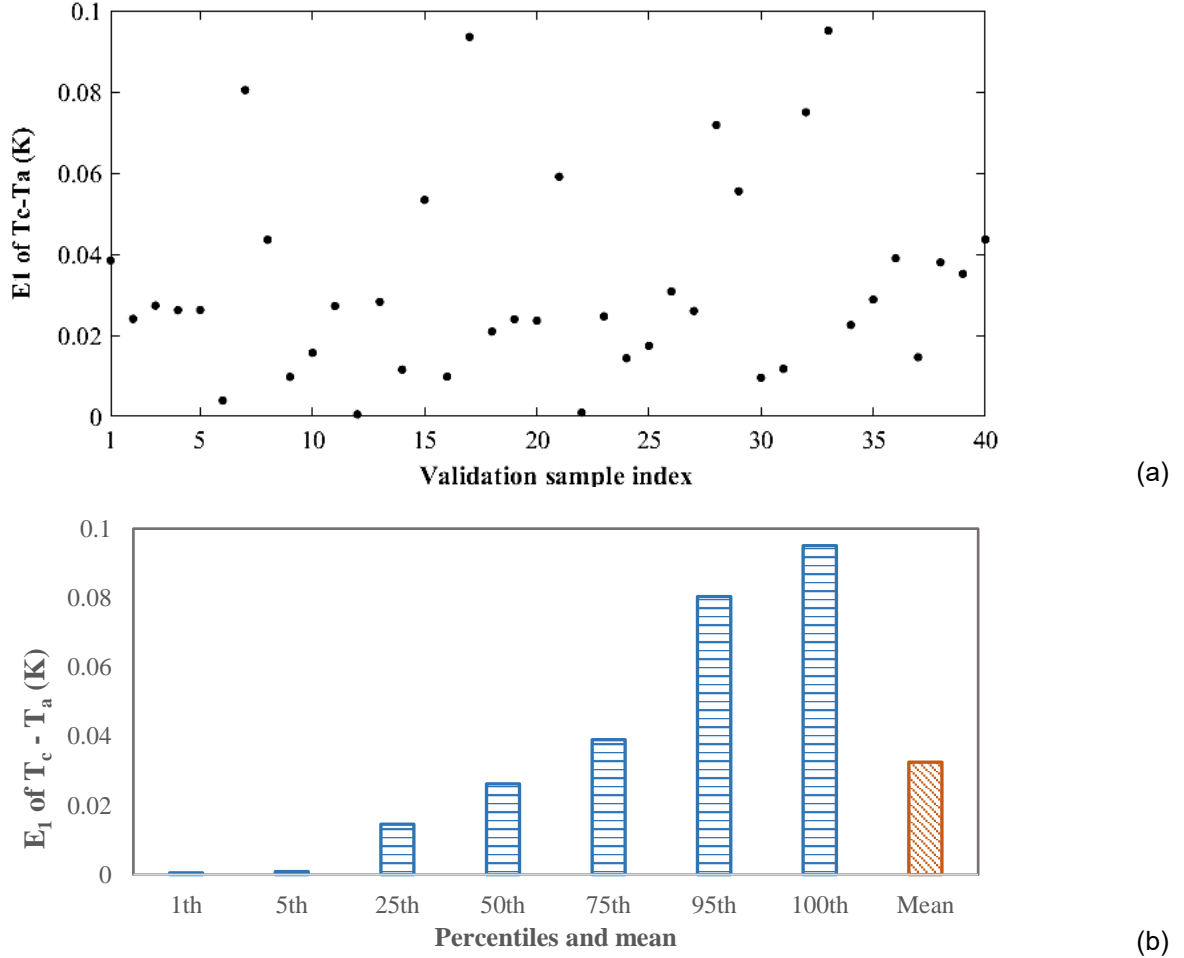


Figure 12 E_1 of $T_c - T_a$ between predictions by proposed regression model and simulations for a) each sample case and b) different percentile and the mean value

3.4. Validation of new regression

Figure 12 plots the relative gap of $T_c - T_a$ between the prediction by proposed new regression model and the CFD simulation of 40 extra sample scenarios for the validation purpose, which were not initially included in the fitting procedure. Approximately 80% of 40 cases were found to have a small gap (less than 0.05) between predictions and simulations while the 75th percentile of E_1 (see Eq. 25) was around 0.039. The mean value of E_1 was found as 0.0325, slightly higher than the median value of 0.0262. Larger E_1 occurred under the condition where a low speed wind was approaching from backside of the BIPV with a large θ while the panel was placed closer to the top edge. For example, under a scenario of $PI = 0.5$, $G_t = 201 \text{ W/m}^2$, $\theta = 174^\circ$ and $U = 0.55 \text{ m/s}$, the predicted temperature difference between the PV cell and ambient was 23.10K comparing to the simulated value of 19.49 K; E_1 was thereby calculated as 0.0749, which was relatively high among 40 sample cases. The possibility of occurrence of extreme conductions (e.g. E_1 exceeds 0.9) was within 5 %. Moreover, the $FAC2$ value (see Eq. 26) of 40 validation cases was equal to 1. Therefore, it can be concluded that the proposed regression model is highly valid to predict the simulated

cell temperature of PV panels.

Figure 13 presents the predicted $T_c - T_a$ by the new regression and SNL model. For individual cases that the SNL model delivers a higher temperature difference with, the prediction given by the new regression model would also be relatively higher. In general, an obvious underestimation of T_c by the SNL model can be observed when comparing to the prediction by the new regression model. The R^2 of results by two models is approximately 0.4760, indicating rather big deviations. A potential reason of this phenomena is due to the fact that the assumption of open-rack installed PV panels with sufficient cooling in the SNL model is not always realistic. Also, as the new proposed regression model was obtained from computational simulations, the relative discrepancies from the experimental measurements should be taken into account.

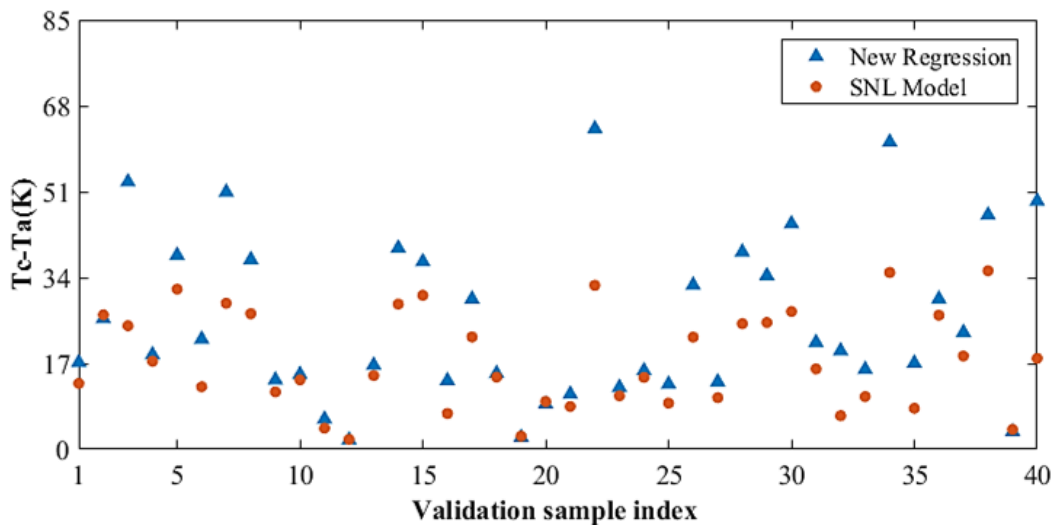


Figure 13 Predicted $T_c - T_a$ by the new proposed regression and SNL models

4. Conclusion

In summary, a new regression model for prediction of the BIPV cell temperature was proposed from a series of full-scaled BIPV CFD simulations. The ambient temperature, solar irradiance, wind speed, relative wind angle and PV position (PV position index) over the roof were taken into account as the influential parameters on the PV cell temperature. Using the sensitivity analysis and Latin Hypercube Sampling approach, the minimum size of the population and sampling size were identified as 13,338 and 374, respectively. Thus, simulations of sample cases were conducted to qualify and quantify the relationship between climatic variables, PV position and PV cell temperature. The simulation results demonstrated the following primary relationships among each variable and $T_c - T_a$:

- It was found that the solar irradiance and wind speed were of the most important factors in determining the BIPV cell temperature while the PV position was the least.
- Higher temperature differences were presented under high solar irradiances.
- The PV panel can be cooled down against strong wind conditions. However, there existed a critical value in which, if the wind speed exceeded, the growth of cooling effect would

become weak.

- The impacts of relative wind angle and wind direction were found to be complex while the possibility of a hybrid influence of two variables was observed.
- Based on the simulation results and observed phenomena, the regression model was proposed with satisfying substantial indicators of goodness-of-fit. 80 % of validation cases were found successfully predicting $T_c - T_a$ with a relative error of less than 5 %.

The main aim of this study was to provide a systematic way to predict the BIPV performance rather than using the existing empirical correlations. Thus, the future work will be focused on development of experimental measurement set ups to measure the certainty of the regression model proposed in this study.

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