

Potential of geoelectrical methods to monitor root zone processes and structure: a review

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1 Abstract

2 Understanding the processes that control mass and energy exchanges between soil, plants and the atmosphere plays
3 a critical role for understanding the root zone system, but it is also beneficial for practical applications such as
4 sustainable agriculture and geotechnics. Improved process understanding demands fast, minimally invasive and
5 cost-effective methods of monitoring the shallow subsurface. Geoelectrical monitoring methods fulfil these crite-
6 ria and have therefore become of increasing interest to soil scientists. Such methods are particularly sensitive to
7 variations in soil moisture and the presence of root material, both of which are essential drivers for processes and
8 mechanisms in soil and root zone systems. This review analyses the recent use of geoelectrical methods in the
9 soil sciences, and highlights their main achievements in focal areas such as estimating hydraulic properties and
10 delineating root architecture. We discuss the specific advantages and limitations of geoelectrical monitoring in this
11 context. Standing out amongst the latter are the non-uniqueness of inverse model solution and the appropriate
12 choice of pedotransfer functions between electrical parameters and soil properties. The relationship between geo-
13 electrical monitoring and alternative characterization methodologies is also examined. Finally, we advocate for
14 future interdisciplinary research combining models of root hydrology and geoelectrical measurements. This includes
15 the development of more appropriate analogue root electrical models, careful separation between different root zone
16 contributors to the electrical response and integrating spatial and temporal geophysical measurements into plant
17 hydrological models to improve the prediction of root zone development and hydraulic parameters.

18

19 **Keywords:** *electrical-properties; root zone soil moisture; root system monitoring; root zone structure, root*
20 *detection; modelling; geophysics; geoelectrical methods;*

21 **Conflict of interest:** none

22

23 **Abbreviations:** Electrical Resistivity Tomography (ERT), Electrical Capacitance Method (ECM), Electrical
24 Impedance Spectroscopy (EIS), Electrical Impedance Tomography (EIT), Electro-Magnetic Imaging (EMI), Spectral
25 Induced Polarization (SIP), Induced Polarization (IP), Time-Domain Induced Polarization (TDIP), Frequency-
26 domain Induced polarization (FDIP), Computed Tomography(CT), Ground Penetrating Radar (GPR), Electrical
27 capacitance(EC), Waxman- Smits model (WS), Time Domain Reflectometry (TDR), Water Content (WC), Soil
28 water content (SWC), Root water uptake (RWU).

29 1 Introduction

30 Root zone is a term used to describe the region of soil that is directly influenced by plant roots and all its inher-
31 ent physicochemical processes. It links directly to human activity; for example, agriculture is typically based on
32 anthropic interactions with the root zone. In addition to its economic importance, studying the root zone provides
33 the tools to protect and to nurture a sustainable environment. In order to understand soil-plant interactions, a
34 detailed appreciation is essential of processes such as: root water uptake, growth of micro-organism communities,
35 nutrient fixation, carbon sequestration and soil structure. This requires the development and routine use of well-
36 defined investigation and quantification methods in order to translate the measurable observations into meaningful
37 soil and root parameters, including hydraulic conductivity, porosity, root length, root biomass or soil respiration.
38 Assessment of root zone processes can take place in-situ or ex-situ, with both experimental settings serving different
39 purposes. Laboratory studies allow the creation of a controlled environment with defined media where experimen-
40 tal parameters are carefully planned and adjusted. This can help understand soil processes on a specific, localized
41 scale (typically sub-metre). By contrast, field surveys facilitate the study of processes in an undisturbed setting.
42 In addition, they provide the necessary benchmarks for translating laboratory results into the real environment.
43 They allow evaluation of methods for monitoring natural and man-made inputs to the root zone system, including
44 agricultural strategies such as inter-cropping or crop rotation, which can only be tested at the field scale (100s of
45 metres) (Garré et al., 2012).

46 Over recent decades, a range of assessment methods for the root zone has been developed. These can be split
47 into invasive/destructive and minimally/non-invasive approaches. Invasive methods disturb the integrity of the
48 soil in order to determine soil (moisture content, calcium content, pH) and root (elongation, mass) properties.
49 Examples include the core-break method (Moreno et al., 2005; Escamilla et al., 1991; Bland, 1989) and the use of
50 minirhizotron tubes (Hendrick and Pretigzer, 1996; Garré et al., 2011). Whilst the results obtained in this way
51 are accurate, useful and do not require ground-truthing, they reflect conditions at the test locality only. Achiev-
52 ing meaningful experimental coverage therefore requires many sampling points, which can be time-consuming and
53 laborious. Furthermore, altering the soil properties through sampling reduces the opportunities for continuously
54 monitoring the soil-plant system.

55 The literature offers many examples of minimally-invasive methods such as TDR (Michot et al., 2001) and non-
56 invasive methods, including X-ray Computed Tomography (CT) (Peyton et al., 1992), Neutron Probe Imaging
57 (Vrugt et al., 2001) or Magnetic Resonance Imaging (MRI) (Segal et al., 2008). These methods provide important
58 insights concerning soil structure (Peyton et al., 1992) or soil water transport (Amin et al., 1996) and more recently
59 they have allowed imaging of the plant root architecture in situ (Mooney et al., 2012). Even though these technolo-
60 gies provide high resolution 3D results, they are expensive to deploy and maintain. Also, at the current state of
61 technology, they restrict the user to a laboratory environment. The exception is TDR, which is frequently employed
62 in field surveys. However, the spatial coverage and resolution achievable with TDR and other non-invasive methods

63 based on point sensors is comparatively poor.

64 Geoelectrical tomography represent a relatively recent, but fast growing set of tools for soil assessment and monitor-
65 ing. In particular, efficient methods for investigating soil-plant interaction are increasingly in demand. Geoelectrical
66 methods are minimally invasive and involve the use of sensors that penetrate the soil surface only (top 10 cm),
67 thus not disturbing the integrity of the volume under investigation. Well-established methods include: Electrical
68 Resistivity Tomography (ERT), Electrical Impedance Tomography (EIT), Electrical Capacitance Method (ECM)
69 and Induced Polarization (IP) with some conceptual overlap between them. A significant body of research has
70 focused on ERT, due to its robustness and ease of use, particularly in the field. Geoelectrical techniques facilitate
71 both in-situ and ex-situ assessments of soil. The methodology allows comparatively rapid data acquisition which
72 enables near real-time measurements (Loke et al., 2013; Samouëlian et al., 2005). It also allows practically continu-
73 ous measurements over time, which provides an important capability for the long-term monitoring of soil processes.
74 The physical principles governing this family of methods involves electrical current signals driven into the soil
75 through electrodes and subsequent recording of differences in electrical potential associated with the subsurface
76 current flow. Larger arrays of multiple electrodes are typically used to acquire geoelectrical data, with individ-
77 ual measurements made consecutively on small subsets of electrodes. Electrical parameters such as conductivity,
78 polarization or capacitance are measured. The systematic collation of datasets with multiple point measurements
79 allows the application of tomographic imaging techniques, which can generate 2, 3 or even 4 dimensional images
80 of the subsurface distribution of electrical properties. This enables quantification of spatial and temporal property
81 variations within soils.

82 Whilst many factors can influence soil electrical properties (e.g. porosity, density, clay content), a particularly
83 useful application is their use as a proxy for soil water content (SWC; Michot et al. (2001)). SWC quantification is
84 critically important for most soil studies. Firstly, it is indicative of plant water availability (Denmead, 1961) and
85 secondly, it is a major factor controlling soil respiration (Davidson et al., 1998) or soil aggregates stability (Haynes
86 and Beare, 1997). Geoelectrical monitoring is able to quantify temporal variations in SWC, and has been used to
87 monitor plant water uptake in the laboratory (Werban et al., 2008) and in the field (Michot et al., 2003), as well as
88 to monitor soil water availability (Brillante, 2016; Srayeddin and Doussan, 2009).

89 A direct correlation has been found between electrical permittivity and root biomass (Dalton, 1995). Therefore, root
90 presence and activity can be quantified directly from electrical measurements. Moreover, organic matter has the
91 ability to polarize electrical current (Schwan, 1957). Researchers have exploited this for assessing the architecture
92 of root systems by measuring not only conductivity (Amato et al., 2009), but also chargeability (Mary et al., 2017).
93 In this study we review the main opportunities for geoelectrical monitoring in root zone research and discuss the
94 key questions that may be addressed in this way. We also seek to highlight the information each method delivers
95 to the user and appraise the state of the art in terms of geoelectrical instrumentation and methodology for root
96 zone research. Current gaps in knowledge and research needs are identified, covering issues such as the variability
97 of pedotransfer functions, the use of a-priori information to constrain the geoelectrical result and the advantages of

98 complementing geoelectrical information with GPR or EMI data in a joint field surveying strategy. We conclude
99 with an outlook to future research opportunities within the experimental observation and conceptual modelling
100 of the root zone. Therefore, with a view to advancing our understanding of root zone processes, we suggest the
101 root system requires a more comprehensive electrical analogue representation, the contributors to the geoelectri-
102 cal response need to be appropriately separated and a coupled research framework aimed to improve root zone
103 parametrization which jointly includes geoelectrical measurements and simulations of plant growth and hydraulic
104 properties.

105 **2 Geoelectrical monitoring - General principles**

106 **2.1 Electrical properties of soils and their variability**

107 The application of geoelectrical methods in root zone research aims at determining the electrical properties of soils,
108 namely, conduction and polarization. Electrical conduction represents the movement of electrically charged particles
109 through liquid and solid phases of the soil medium. Their flow will depend on the amount of available charge, the
110 distribution of conducting paths and the charge mobility. Electrical polarization represents the redistribution of
111 positive and negative charges when exposed to an exterior electric field. In consequence, this will determine regions
112 of charge accumulations across the soil medium.

113 Variability in soil electrical properties can be caused by either inorganic or organic constituents of the soil system.
114 Soil electrical conduction is generally determined by pore fluid and mineral surface conductivity. Soil electrical
115 polarization is determined by the pore architecture and water-mineral interface capacity of ion aggregation (Everett,
116 2013). Therefore, a number of properties intrinsic to the soil (i.e. its inorganic constituents) have a direct effect
117 on the electrical response. Further essential contributors to the electrical response are components of the root zone
118 with an organic origin, such as decomposed plant material, collectively known as humus, and plant root systems.

119 **2.1.1 Inorganic constituents**

120 **Pore fluid.** Electrical conduction in soils is mostly electrolytic, ions in the pore fluid being the charge carriers
121 (Everett, 2013). The amount of charges increases with fluid ionic concentration or the volumetric water content
122 given a constant fluid conductivity.

123 When an electrolyte comes in contact with a charged surface of a soil particle, an electrical double layer (EDL)
124 forms and ions are adsorbed onto the solid surface (Revil and Glover, 1997), therefore affecting ion mobility which
125 gives rise to electrical polarization (Lyklema et al., 1983).

126 **Solid soil.** Generally, the solid matrix acts like a semi-conductor with some exceptions such as the surface of clay
127 minerals. Their inherently negative surface charge constitutes another electrical conduction pathway. Also, soils
128 with a predominantly clay texture tend to exhibit a larger specific surface area than soils consisting primarily of sand
129 (Pennell, 2016). Therefore, clay content implies a larger conductive particle surface which leads to an important

130 contribution to the soil electrical conductivity (Fukue et al., 1999).

131 **Air Filled pore space.** The volume (porosity) and connectivity of the pore network determine a soil's water
132 holding capacity, which in turn affects the bulk soil electrical conduction. Also, the tortuous nature of the pore
133 system generates complex patterns of fluid flow which can determine electrically conductive and non-conductive
134 regions. As for polarization, due to the formation of EDLs, narrow pore channels may cause charge accumulation
135 and localized disequilibria in ionic concentration (Revil, 1999).

136 **Temperature.** An increase in pore fluid temperature causes a decrease in pore fluid viscosity, which in turn
137 increases the ion agitation in the solution. Alternatively, in freezing conditions, molecules of salt are rejected into
138 unfrozen pore water, thus changing the concentration of the pore solution (Banin and Anderson, 1974). Superficial
139 soils are exposed to diurnal and seasonal fluctuations in temperature, therefore neglecting such variability may lead
140 to serious errors in geoelectrical data interpretations (Samouëlian et al., 2005).

141 2.1.2 Organic constituents

142 **Organic matter (OM).** The capacity of the soil to retain ions (or ion exchange capacity) is a measure of soil
143 surface charge (Zelazny et al., 1996). A considerable proportion of soil cation exchange capacity (CEC) is associated
144 with soil organic matter. Interactions between OM and soil minerals result in a decrease in ion mobility, and thus
145 a decrease in polarization (Schwartz and Furman, 2015).

146 **Plant roots.** The living root system has a very complex electrical response that depends on root characteristics,
147 such as: mass, length, structure, type (woody or herbaceous) or tortuosity. Woody root tissue does not contain
148 charge carriers therefore their presence in the soil system will reduce the overall bulk electrical conductivity (Van-
149 derborgh et al., 2013). However, electrical current will flow through the root xylem as the fluid contains electrical
150 charges. EDLs form both at the contact between the outer and inner root surface, therefore the magnitude of root
151 polarization relates to their overall surface area (Weigand and Kemna, 2018).

152 2.2 Methods of measuring soil electrical properties

153 A range of geoelectrical methods is available to measure soil properties. In this section we aim to provide a short
154 introduction to the physical and functionality principles governing these methods.

155 2.2.1 Complex electrical impedance

156 In practice an electrical measurement on soil involves a measurement of the complex impedance \hat{Z} of the material,
157 a frequency f dependent function expressed as:

$$\hat{Z} = (Z'(\omega) + iZ''(\omega)), \quad (1)$$

158 where i is the imaginary unit, $\omega = 2\pi f$, Z' and Z'' are the real and imaginary parts of the impedance respectively.
159 This can in turn be translated into effective material properties by taking into account the dimensions and spatial

160 geometry of the measurement, represented through the geometric factor K . Therefore we can obtain an expression
 161 for the 'apparent' complex conductivity $\hat{\sigma}_a$ and its inverse, complex resistivity $\hat{\rho}_a$, which describe how well a material
 162 conducts electrical current flow:

$$\hat{\sigma}_a = (K * \hat{Z})^{-1} = \sigma' + i\sigma'' = |\rho_a| * e^{-i\phi}, \quad (2)$$

163 where the real part σ' quantifies conduction and σ'' quantifies polarization. ϕ is the phase angle that represents the
 164 phase shift between the injected current and measured voltage.

165 2.2.2 ERT

166 For this review we selected 72 articles spanning across 22 years (1996-2018) which feature the application of geo-
 167 electrical methods in root zone research (Complete list in Appendix A and B). ERT is one of the most extensively
 168 used near surface geophysical methods and is also extremely popular for the study of soil-plant interaction. 65% of
 169 the studies reviewed for this paper employed ERT as the primary method of imaging soil-plant interaction. ERT
 170 applications inject DC or low-frequency current into the soil and tend to measure the magnitude $|\hat{Z}|$ of the electrical
 171 impedance only. Provided that the geometric factor K is known, the bulk resistivity of the soil can be calculated
 172 according to Ohm's law:

$$\rho = K * \frac{\delta V}{I}, \quad (3)$$

173 where δV is the observed potential difference and I is the injected current. the primary concern is with the strength
 174 of the received signal, rather than its phase relationship. A standard procedure is to use a pair of electrodes for
 175 current injection and separate pair of electrodes to record the potential difference. After making multiple spatially
 176 distributed measurements the recorded data is used to generate a tomographic image of the subsurface, in order to
 177 determine the spatial distribution of soil electrical properties. These are interpreted in the context of a heterogeneous
 178 subsurface structure. Inverse modelling is used to fit an earth model to the measured dataset. The inversion
 179 procedure uses adjustments to the predicted model parameters to achieve convergence between the measured and
 180 predicted datasets. A typical approach is to change the model until the misfit reaches a minimum. The model
 181 is build upon a mesh (dimensionality is case dependent) which follows a pre-defined discretisation of the target
 182 geometrical space and other constraints (e.g. limit values, smoothing factor, boundary conditions). The model cells
 183 have corresponding cartesian coordinates and a parametric value associated, in this case a geoelectrical parameter
 184 (e.g. resistivity, phase). Additional a-priori information about the environment (e.g. soil structure, temperature,
 185 topography) will significantly improve the inversion result. However, inherent problems with geoelectrical inversion
 186 are:

- 187 1. Non-linearity. The relation between parameters and data is often non-linear, therefore a linear approximation is
 188 required to help solve the system of equations.
- 189 2. Solution stability. A small perturbation in the initial conditions can cause very different outcomes.

190 3. Non-uniqueness. Multiple models fit the data to the same degree of accuracy, hence choosing the "correct" model
 191 is a challenge both conceptually and practically. These limitations of geoelectrical inversion apply to all geoelectrical
 192 techniques that employ tomographic reconstruction of the data.

193 2.2.3 IP

194 In the absence of polarization, a sudden switch off of the current injected in the target medium should cause the
 195 voltage between a pair of potential electrodes to drop from an initial value V_0 instantaneously to 0. However, if the
 196 soil exhibits polarization, a gradual decay of the voltage can be observed over a finite time period, which is known
 197 as the IP effect (Everett, 2013). In practice, this behaviour can be measured both in the time-domain and in the
 198 frequency domain.

199 **Time-domain IP.** The acquisition principle here is technically similar to the one used for ERT. From the IP
 200 recorded discharge curve we can obtain measurable quantities such as apparent polarizability η (Equation 4) or
 201 partial chargeability m (Equation 5):

$$\eta = \frac{V(T)}{V_0}, \quad (4)$$

202 where V_t is the voltage measured at time T after current switch off.

$$m = \frac{1}{V_0} \int_{t_1}^{t_2} V(t) dt, \quad (5)$$

203 where t_1 and t_2 are the two limits of a time window during the voltage decay (Everett, 2013).

204 **Frequency domain IP.** FDIP is often referred to as SIP or EIS and uses a range of (typically discrete) frequencies
 205 for current injection. The complex resistivity in both magnitude and phase is a function of the frequency of the
 206 injected current signal. Polarization effects cause a phase shift between injected and recorded currents, therefore in
 207 addition to ERT, FDIP method is able to measure the IP effect through its phase angle.

208 Empirical models such as Debye (Debye, 1929) or Cole-Cole (Equation 6) (Cole and Cole, 1941) have been developed
 209 to describe the complex resistivity frequency dependence.

$$\rho^*(\omega) = \rho_0 \left[1 - m \left(1 - \frac{1}{1 + (i\omega\tau_0)^c} \right) \right], \quad (6)$$

210 Fitting the Cole-Cole model parameters to experimental data yields values for the chargeability m , relaxation
 211 time τ_0 and frequency exponent c . It is worth mentioning this model can also be applied in the time-domain on
 212 chargeability curves (Pelton et al., 1978) in order to extract corresponding parameters.

213 **EIT.** EIT is a method which uses the measurement principles of IP, and therefore used to determine complex
 214 resistivity, but in addition incorporates a tomographic reconstruction capability, such as ERT (Zimmermann et al.,
 215 2008). Therefore, EIT brings together information about the signal strength, shape and timing. Ultimately, it uses
 216 the data to construct a tomographic distribution.

217 For soil research purposes the method is still in the incipient stages. It was successfully applied previously for

218 detecting electrical phase differences (Kelter et al., 2015), the low-polarizability of a water submerged root system
 219 (Weigand and Kemna, 2017) and changes in polarization due to diurnal cycles and gradual nutrient deprivation
 220 (Weigand and Kemna, 2018).

221 **2.2.4 ECM**

222 Chloupek (1972) found a direct correlation between root parameters, such as dry mass and surface area, and the EC
 223 of root systems. The basic measurement procedure involves the connection of an LCR (Inductance-Capacitance-
 224 Resistance) meter between an electrode attached to the base of the plant stem and another one inserted into the soil.
 225 Previous studies established such correlations at a single measurement frequency (Dalton, 1995; Ellis et al., 2013)
 226 or using a broader range of frequencies (Ozier-lafontaine and Bajazet, 2005). Primarily, the measured quantity for
 227 ECM is still complex impedance. However, the impedance measurements are interpreted in terms of an analogue
 228 electrical circuit. Dalton (1995) envisioned root segments as capacitor-resistance pairs connected in parallel. The
 229 root segment capacitor has three components: xylem as an internal electrode, soil nutrient solution surrounding
 230 the root as a second electrode and a poorly conducting plant tissue acting as a dielectric. Therefore, the complex
 231 impedance can be expressed in terms of the equivalent root system capacitance C and resistance R as:

$$\hat{Z}^{-1} = \frac{1}{R} + i\omega C = \frac{1}{R} + i\omega \frac{\epsilon A}{4\pi r_2 \ln\left(\frac{r_2}{r_1}\right)}, \quad (7)$$

232 where ϵ is the dielectric constant, A is the geometrical surface area of the root tissue, r_1 and r_2 are the radius of
 233 the inner root xylem channel and the root segment, respectively.

234 **2.2.5 Relationship between geoelectrical methods**

235 Considering what was previously enunciated, one may reach the conclusion that there is a certain degree of inter-
 236 connectivity between all the geoelectrical methods. The main common denominator is the measurement of complex
 237 electrical impedance, but different methods have different ways of mathematically expressing the recorded data,
 238 such as the magnitude of complex impedance (ERT), polarizability and chargeability (IP) or electrical permittivity
 239 (ECM). Secondly, methods differentiate by the type of current they use (DC or AC) or the domain they operate
 240 in (time-domain or frequency-domain). In Figure 1 we formulated a summary diagram describing the relationship
 241 between different methods and their corresponding measured quantities. This will potentially serve as an aid to
 242 better understand how the geoelectrical methods were used to resolve parameters of the root zone in the studies we
 243 review in the following section 3.

244 **2.3 Translating geoelectrical measurement into root zone properties**

245 It is important to note that geoelectrical methods do not quantify root zone properties directly. For this purpose an
 246 additional calibration measurement is required to allow direct translation of electrical measurements into root zone
 247 properties. This can be illustrated using the example of SWC. As mentioned, electrical measurements are sensitive

248 to changes in SWC, but the relationship is a function of multiple factors and no analytical expression is readily
249 available to describe it. Therefore, a dedicated method for estimating water content (e.g. TDR, neutron probe,
250 destructive sampling) is usually used in parallel to the geoelectrical method, in order to determine the dependency
251 of the electrical response on SWC variation by empirical means. The outcome of this exercise is a calibration curve,
252 which can subsequently be used to translate the geoelectrical measurements into SWC for the specific material and
253 under the specific circumstances. Unfortunately, a universal transfer function is unlikely to exist, due to the large
254 number of potential input factors, used to parametrize the root zone, such as porosity, saturation status or root
255 mass. Different calibration strategies have been adopted over the years. Earlier studies established simple linear
256 regression correlations between measured resistivity and SWC or root biomass, respectively (Michot et al., 2003
257 and Amato et al., 2008). However, the calibration process has recently become more systematic and new research
258 is looking into its simplification using deep learning prediction algorithms (Brillante et al., 2016).

259 **2.3.1 Resolving pedological parameters**

260 A more robust strategy involves the use of quantitative conceptual models to link electrical parameters and soil
261 properties (known as pedotransfer functions or PTFs). One of the first relationships of this kind described the
262 resistivity behavior of a brine- saturated sandstone in the context of borehole logging and was developed by Archie
263 (1942). However, Archie's law did not take into account surface conductivity, which becomes essential in samples
264 with an increased clay content. Based on Archie's relation, the Waxman-Smits (WS) model, established for shaly
265 sands, incorporates the presence of clay particles with surface conductivity effects (Waxman and Smits, 1968). More
266 comprehensive models have been developed based on both laws. The model proposed by Rhoades et al. (1989) relies
267 on the assumption of two separate electrical pathways, a continuous one through waterfilled macropores and a series
268 linked soil-liquid one. A model by Mualem and Friedman (1991) is based on the fact that the tortuosity factor
269 affecting the bulk electrical conductivity is identical to the one predicting hydraulic conductivity. Revil et al. (1998)
270 assumes surface conduction to be restricted to the part of the EDL where ions are adsorbed to the material surface
271 (Stern layer). The Linde et al. (2006) model takes into consideration the different behaviour of ions in the pore
272 space. The transport regime of anions is independent of salinity as opposed to that of cations, which have a different
273 regime for high and low salinity.

274 The decision over which model to apply is subjective for any given application, as more than one model may fit
275 the requirements. Laloy et al. (2011) compared existing pedotransfer models and suggested that the Linde model
276 performs better for a low resistivity regime ($<100 \text{ Ohm.m}$), whilst WS performs better in the high resistivity regime.
277 As one can realize from early PTSs such as Archie's law, they were not initially intended for applications in the
278 root zone but for oil exploration. Therefore, the factors describing them are strictly pedological. In order to offer
279 a more comprehensive view of how geoelectrical methods can resolve root zone properties, the following subsection
280 briefly presents research efforts of describing the root electrical signature.

281 **2.3.2 Resolving root system parameters**

282 An electrical model developed by Dalton (1995) suggested that roots can be represented by a parallel resistance-
283 capacitance (RC) circuit. More roots will imply more RC pairs connected in parallel. Therefore, the effective
284 capacitance of a root system will depend on its structure and size. Ellis et al. (2013) concluded that capacitance
285 was significantly related to root mass, length and surface area, but as a measurable quantity its predictive power is
286 poor. They also obtained the best predictions for root length, which was significantly related to the ratio between
287 capacitance and density. However, the Dalton model was tested and inconsistencies were found by both Ellis et al.
288 (2013) and Dietrich et al. (2012), questioning the validity of a linear correlation between capacitance and root mass.
289 Upon the removal of roots from a hydroponic solution it was realized that the capacitance of the solution was much
290 higher than the capacitance of the root tissue. Arguably, the studies have shown that capacitance is correlated to
291 root mass, but is not a direct means of measuring it.

292 Cao et al. (2010) also measured the electrical resistance of a root system submerged in a hydroponic solution. The
293 resistance decreased with an increasing contact surface area of the root with the solution. These measurements
294 contributed to the formulation of analogue circuits where the root system is realized as series of electrical resistors.
295 Building on these results, Cao et al. (2011) used a spectrum of frequencies to analyse the elements of the root system
296 analogue circuit. The study found that capacitance is a more useful parameter than resistance when it comes to
297 root size estimation. Regression models were used in Amato et al. (2008, 2009) in order to link root mass density
298 to resistivity measurements. The strong correlations led to the formulation of a logistic-growth model which later
299 gave accurate predictions on field data acquired by Rossi et al. (2011).

300 **3 Monitoring processes and resolving structure in the root zone**

301 Geoelectrical methods are able to (1) monitor processes in near real time and (2) resolve structure, which is important
302 for the study of soil-plant interactions because of the high significance of water content changes (Samouëlian
303 et al., 2005) for these interactions and the presence of root organic matter (Amato et al., 2008) in the medium
304 of investigation. Given that access to water plays a key role in plant survival, quantitative monitoring of water
305 dynamics is helpful for defining the requirements and constraints, such as water availability, influx access points,
306 transport parameters, flow pathways and for characterizing the environmental conditions, including soil texture,
307 soil porosity, root characteristics, climate, geological setting and others. Detecting and quantifying root activity
308 is crucial for understanding the extent of plant development and their reactions to stimuli (Mooney et al., 2012).
309 Root architecture development is a visible indicator of the quality of the impact root system has on the plant's
310 health and productivity, or on surrounding plants. The following subsections present an overview of the current
311 state-of-play in geoelectrical monitoring research in three main application areas, namely (1) water dynamics (2)
312 the detection of root organic matter and (3) the modelling of root zone processes.

313 **3.1 Root zone water dynamics**

314 Much geoelectrical research is focused on monitoring root water dynamics. a considerable body of literature focuses
315 on monitoring root water dynamics underlining its importance for soil studies.

316 **3.1.1 Ex-situ studies**

317 We examine studies performed ex-situ (in a laboratory environment), many of which were undertaken to try to illus-
318 trate the suitability of geoelectrical methods for monitoring solute transport in soils, or to determine soil properties
319 in a controlled experiment, which would not be possible on a larger scale. The majority of studies have adopted
320 a similar experimental set-up, whereby the soil volume of interest is surrounded by electrodes in order to enable
321 electrical current flow throughout the sample (Figure 2).

322

323 **3.1.1.1 The signature of rootless soil**

324 It is important to acknowledge that the studies mentioned here focus on the soil as a medium which does not
325 contain a root system, disregarding the effect such a system has on neighbouring physicochemical properties. The
326 existence of roots in soil adds a further layer of complexity to the geoelectrical attempt of monitoring hydrodynamic
327 processes. Therefore, we present an initiatory body of literature that aims to decipher the contribution of rootless
328 soil separately before expanding to applications which take roots into consideration.

329 Binley et al. (1996) used a dye staining experiment to show the ability of ERT to reconstruct flow pathways in
330 soil. Olsen et al. (1999) used ERT in conjunction with X-ray CT for the purpose of solute transport characterisation.
331 A rapid transport mode was detected through geoelectrical monitoring and was explained by the properties of the
332 macropore system detected by X-ray tomography. However, macropores could not be directly related to the electrical
333 tomogram because of the gap in spatial resolution, hence a causal link between the two observations could not be
334 established. Similarly to Binley et al. (1996), Koestel et al. (2007) demonstrated the benefits of using dye as a tracer
335 for electrical conductivity monitoring experiments. This was extended to a two-step tracer infiltration experiment
336 through a cylindrical soil column (Koestel et al., 2008), in which bulk electrical conductivity was translated to solute
337 concentrations. Figure 3 shows the evolution of concentration illustrating the ability of ERT to track the dynamics
338 of solute injection and transport at the laboratory scale. However, this type of observation was only possible when
339 a hydraulic steady-state existed and there was no spatial variation in the saturation states of the soil. Cassiani
340 et al. (2009) used SIP for the purpose of monitoring organic pollutants in soils, looking at DC and chargeability
341 responses from samples at different levels of water saturation obtained after the injection of air and a non-aqueous
342 phase liquid (NAPL). The study observed differences between the NAPL and air samples, which were attributed to
343 phase distributions across the samples and not to chemical interaction between solutes and surrounding liquid/solid
344 phases.

345 **3.1.1.2 The signature of the root zone**

346 By periodically irrigating a ginkgo tree, Wu et al. (2013) detected spatial and temporal variations in capacitance
347 with increasing water content. Also, the tomographic images provided visual representation of the process of
348 saturation and subsequent drying. Werban et al. (2008), in a pot experiment containing a *Lupinus* plant grown in
349 fine sand, set out to monitor spatial heterogeneity of water movement. Diurnal variations were found, which were
350 assumed to be a manifestation of RWU triggered by plant transpiration. Building on this, Garré et al. (2011) used
351 a 3D ERT to quantify water content changes in soil due to RWU and evapotranspiration. Resistivity variations
352 were correlated here with minirhizotron measurements of root development. Newill et al. (2014) demonstrated
353 the feasibility of using capacitive coupling insulated electrodes whose purpose is to reduce corrosion and avoid
354 polarization of the probes. The study presented a more efficient acquisition system for measuring impedance, which
355 resulted in the technique being able resolve water content fraction changes of up to 20%. However, it is important to
356 note that their study measured the magnitude of the complex impedance only, without consideration of polarization
357 effects.

358 **3.1.2 In-situ studies**

359 In an industrialized world with a rising demand for food in both quantity and quality, effective soil management for
360 agriculture is becoming increasingly critical. The majority of in-situ root studies have therefore focused on water
361 dynamics exhibited by agricultural crops. In this kind of setting it is difficult to separate the effect of rootless
362 soil as it was previously done for ex-situ studies. This underlines the necessity of laboratory trials that attempt
363 to understand and parametrize the more localized behavior of the root zone, which will subsequently support and
364 serve as reference for field trials.

365 One of the first studies that assessed the effectiveness of the ERT method in an agricultural context was by Panissod
366 et al. (2001). It revealed the existence of high resistivity patches under cover crops, and these patches were inferred
367 to be linked to plant water uptake. In the absence of appropriate pedotransfer functions, which create the link
368 between water content and electrical resistivity, the water distribution could not be estimated. Also, no ground
369 truth was available for comparison. The study was able to map anomalies in the resistivity distribution, thus
370 showing the potential of the ERT method, but the causal link between resistivity variation and water content
371 depletion remained an assumption. Michot et al. (2001) presented a more robust experimental design using TDR
372 measurements in parallel with ERT. Resistivity variations with time were observed under crops similar to the ones
373 identified by Panissod et al. (2001). Moreover, a wetting front was localized from the electrical tomogram and
374 preferential flow directions were identified. Michot et al. (2003) subsequently conducted a very similar field trial.
375 The resistivity-estimated water content was compared to that obtained from TDR. The %RMS (Root Mean Square)
376 error was less than 5 and the correlation factor around 0.8, which suggests good agreement between both techniques.
377 Consequently, the work proves the suitability of ERT to monitor soil available water reserves on the field scale.
378 One of the reference works for root zone water dynamics was presented by Srayeddin and Doussan (2009), who

379 conducted a field monitoring study of water uptake under sorghum and maize fields subjected to different watering
380 regimes. The study showed heterogeneous patterns of water depletion in the moderated and poorly irrigated fields.
381 Direct field water content measurements were used to calibrate the resistivity results. The water uptake was found
382 to have a quantitative (and not just qualitative) relationship with resistivity.

383 The field studies follow a similar experimental set-up to the studies mentioned in section 3.1.1. Figure 4 shows an
384 example of a typical survey arrangement on a linear profile. 2D resistivity images resulting from such an acquisition
385 scenario are presented in Figure 5. They demonstrate the extent to which ERT resolved the spatial distribution of
386 resistivity. Here, both the lateral and the vertical variability was likely caused by the plant water uptake.

387 Celano et al. (2011) compared two different soil management regimes, tillage and cover cropping, and found a
388 significant water reserve in the soil beneath the cover crops. The authors used laboratory derived calibration
389 curves between soil moisture and resistivity. The correlation coefficients between resistivity-estimated and directly
390 measured water content was found to be stronger than that observed by Srayeddin and Doussan (2009). However,
391 the latter measurements were carried out in situ, whereas the former ones were undertaken ex situ, which typically
392 requires additional experimental time and effort. All applications of geophysical monitoring represent a trade-off
393 between time, effort and data quality.

394 Nijland et al. (2010) presented a case study that used geoelectrical methods to quantify water availability in a
395 Mediterranean soil ecosystem. The study highlighted the power of the roots to penetrate the fractured bedrock
396 to reach water. Robinson et al. (2012) underlined the ease of use and convenience of data collection that an ERT
397 survey provides. They conducted a 3D survey to monitor moisture content in an oak-pine forest, which suggested
398 moisture stability in tree-covered areas and moisture instability in open areas. Beff et al. (2013) monitored WC
399 under a maize field through a joint assessment of ERT and TDR. The latter was used to achieve spatial coverage and
400 the former to achieve temporal coverage. The resistivity distributions reflected the maize row arrangements in the
401 field. Garré et al. (2013) monitored resistivity changes in mixed cropping systems showing a smaller depletion depth
402 for chili cultures compared to maize and *Leucaena*. Also, a higher depletion was detected close to the intercrop
403 hedges which implied a competition for water between different crop species. Garré et al. (2012) used semivariogram
404 interpretation of WC spatial distribution indicating moisture variability is highly influenced by soil heterogeneity.
405 Kelly et al. (2011) monitored water migration beneath crops. The resulting resistivity tomograms were compared
406 with WC values obtained using a capacitance probe. Moreover, the study recommended that ERT monitoring
407 should be integrated into irrigation programs.

408 ERT monitoring was also used by Musgrave and Binley (2011) to characterize the stratigraphy of a wetland
409 site. The 2D characterization with ERT was performed in combination with GPR. The study highlighted the
410 suppression of temporal changes in resistivity, which was explained by the occurrence of groundwater recharge,
411 providing a means of identifying such recharge areas.

412 **3.2 Root structural and functional properties**

413 **3.2.1 Woody roots**

414 **3.2.1.1 Correlating root properties and geoelectrical measurements**

415 Amato et al. (2008) and Rossi et al. (2011) found a strong positive correlation between resistivity measurements
416 and root biomass. Rossi et al. (2011) also observed a dominating effect of the root biomass over other root zone
417 properties, such as root length density (root length per unit volume), which raised the concern that this has to be
418 taken into account by future studies to avoid bias.

419 In an in-situ experiment, Čermák et al. (2006) successfully estimated tree root absorption surface area with resistivity
420 measurements. Also, the study showed a positive correlation between stem area and root absorption area. In
421 addition, Mares et al. (2016) used ERT to capture the spatiotemporal variability in an active sapwood, which
422 reflects the sapflow upscaling. Guyot et al. (2013) attempted to estimate sapwood area with the use of resistivity
423 monitoring. However, the R^2 correlation between resistivity derived estimates and actual area was low. Jones et al.
424 (2009) used ERT as a means of visualizing tree-induced subsidence. Leveling data indicating subsidence and ERT
425 profiles were in agreement, both being influenced by climatic conditions. As the study did not include quantitative
426 models to accompany and fit the resistivity datasets, the correlations are qualitative.

427 **3.2.1.2 Mapping tree root systems**

428 Mary et al. (2018) showed the potential of ERT and the Mise-à-la-masse (MALM) technique for mapping woody
429 root system distribution in soil. The concept of MALM measurements is to inject electrical current into a conductive
430 body and make surrounding measurements of voltage. Based on these measurements the extent of the body can be
431 calculated. The assumption is made that the roots are the conductive body and that the current injected through
432 the plant stem will eventually be passed into the subsoil through the root terminations (root hairs). Another
433 study by Zenone et al. (2008) combined ERT reconstruction and GPR sections for the purpose of root detection.
434 Figure 6 shows the level of performance that can be expected from ERT when imaging root architecture. The root
435 system is not resolved accurately, but the potential to localize roots is undeniable and the overall shape of the root
436 system is captured well. The study also concluded that combining electrical resistivity with GPR data is useful in
437 the investigation of root shape and behavior. It was shown that the contemporaneous use of multiple geophysical
438 methods improves the quality of the results. GPR was successful for identifying the distribution of the roots in
439 the subsoil, whereas ERT was useful for estimating the root volumes. Leucci (2010) used ERT, GPR and seismic
440 refraction to produce 3D images of tree-root distribution. GPR revealed the extent of the root system, seismic
441 refraction delineated the subsurface layers and ERT distinguished the roots from an old pipe system. The study
442 reinforced the utility of the methods for this application emphasized the benefits of combining the techniques.

443 **3.2.1.3 Root polarization**

444 Zanetti et al. (2011) observed the complex conductivity signature of multiple samples of dead roots in three
445 different soil textural environments dominated by gravel, sand and silt, respectively. Additionally, the methodology

446 was able to indicate the presence, type, size and orientation of buried material. However, measurements were limited
447 to 1D, hence no information about the spatial distribution of the buried samples could be obtained. Polarization
448 effects have also been observed by Martin (2012) when studying wood, suggesting that the methodology was able
449 to identify infection damage in wood cells, which could add significant value to the technique.

450 Mary et al. (2016, 2017) demonstrated the feasibility of using IP for root detection, whilst performing in-situ
451 experiments. Mary et al. (2016) concluded that a dry soil medium is more appropriate for IP measurements as
452 the contrast between the response from roots and surrounding soil is higher. Mary et al. (2017) concluded that, at
453 low frequencies (1 Hz chosen as adequate), significant effects of polarization are dependent on root per soil volume
454 ratio and are sensitive to root orientation. Furthermore, Mary et al. (2017) suggests root WC is proportional to
455 the amplitude of polarization. These results suggest that there is an increasing prospect of using this method in
456 the study of soil-plant interactions.

457 3.2.2 Herbaceous roots

458 Aulen and Shipley (2012) identified a significant relationship between root mass and capacitance. Unfortunately
459 this was too weak without prior species specific calibrations ($R^2 = 0.3$). Ellis et al. (2013) confirmed a weak
460 predictive power of ECM ($R^2 = 0.21 - 0.31$), but suggest an empirical model as a reasonable predictor of root
461 length ($R^2 = 0.56$). Amato et al. (2009) tested the ability of resistivity tomography to detect low-density root
462 systems. They concluded that, although promising for more developed root systems, the resistivity contrast is not
463 sufficient for a low-density regime.

464 Sabo et al. (2016a,b) proposed the use of capacitance tomography to assess the difference between healthy and dead
465 roots by their ability to absorb water containing nano-particles of iron. Healthy roots showed capacitive readings
466 that were up to three times lower than diseased ones. A series of pot experiments demonstrated the capability of
467 capacitance measurements to monitor root system properties (e.g. dimensions, mass, root surface) when subjected
468 to herbicide aceochlor (Cseresnyés et al., 2012), mycorrhizal fungal colonization (Cseresnyés et al., 2013), different
469 RWU rates (Cseresnyés et al., 2014; Cseresnyés et al., 2016) and SWC changes together with mycorrhizal activity
470 under field conditions (Cseresnyés et al., 2018). The latter study concluded that EC dependency on SWC is plant
471 species dependent, which underlines the importance of root system architecture through its impact on RWU rate of
472 change. Weigand and Kemna (2017) applied EIT to monitor the root activity of oil seed plants, which were grown
473 in hydroponic conditions. The study discovered a low-frequency polarization response associated to root presence,
474 and the methodology was able to delineate the extension of the root system. The study also observed changes in
475 electrical properties due to root physiological stress imposed by nutrient deprivation.

476 3.3 Root zone conceptual models

477 Root zone processes and structure are vastly complex. Formulating both conceptual and quantitative models of the
478 root zone is important to help develop our understanding of their complexity. Improved root zone models may help

479 fulfill the long-term ambition to be able to predict future states of the soil-plant system. However, existing root
480 zone models are not universally valid and dependent on locally derived parameters, such as soil texture, porosity,
481 temperature fluctuations ,root mass and others.

482 Geoelectrical monitoring can help improve root zone modelling. As discussed in sections 3.1 and 3.2, geoelectrical
483 methods have demonstrated their capability to assess root water dynamics and root structure. The recorded
484 variation in electrical properties reflects root functions (e.g. water uptake) or root-system structural indicators (e.g.
485 mass, length, density). In this section we discuss how this information was in turn used as a basis for models of
486 the root zone in order to 1. estimate the water balance determined by the soil-vegetation interaction 2. estimate
487 effective water uptake in order to optimize irrigation practices and 3. improve conversion between electrical data
488 and crop-scale root zone parametrization. A list of cited articles and corresponding models used can be found in
489 supplementary materials (Appendix A and B).

490 **3.3.1 Modelling root zone water dynamics**

491 **3.3.1.1 Interaction between vegetation cover and soil water balance**

492 Cassiani et al. (2012) used ERT in conjunction with EMI method and TDR to investigate the effect of vegetation
493 upon water dynamics. A strong correlation was found between the presence of vegetation and the variability of
494 SWC. It was suggested that spontaneously grown vegetation on the bare soil influences the degree of soil compaction,
495 which led to a slow infiltration of meteoric water in the upper layers. This is one of the few studies that have at-
496 tempted to model vegetation-soil interaction based on electrical monitoring data. This approach holds promise for
497 future research and opens the door for more comprehensive modelling which should take into account the dynamics
498 of vegetation growth. Michot et al. (2003) demonstrated the effectiveness of combining ERT and TDR, in 2D some
499 10 years prior, but Cassiani et al. (2012) undertook 3D reconstruction of SWC distribution. Whilst geoelectrical
500 methods alone are capable of providing time-lapse information, TDR can be useful for its superior temporal res-
501 olution. It is also worth noting ERT systems with permanently deployed sensor arrays and instrumentation are
502 actively being developed, providing superior repeatability and high temporal resolution from ERT measurements
503 alone (Chambers et al., 2014).

504 Boaga et al. (2014) used ERT to demonstrate flooded plants are able to create aerated layers below the flooded
505 surface when transpiration rate was high. The study found the results were in agreement with the model previously
506 developed by Tosatto et al. (2009), which solved the 2D two-phase flow equations in porous media. Ursino et al.
507 (2014) showed that in fallow plots infiltration is heterogeneous, water redistribution takes place below ground where
508 roots have access to the active volume and the root-soil interplay reduces runoff and increases evapotranspiration.
509 Their study promoted the integration of measurements of soil properties such as electrical resistivity, moisture con-
510 tent and vegetation density in order to develop a comprehensive soil-plant interaction model. However, the study
511 did not employ a meaningful quantitative translation between electrical measurements and soil properties.

512 **3.3.1.2 Contributing towards irrigation efficiency**

513 Boaga et al. (2013) used ERT for temporal monitoring in order to characterize water balance exchanges in the
514 subsoil under an apple orchard. Root growth was closely connected to the geometry of the irrigation system as roots
515 developed in a shallow area, and were aligned with the irrigation lines. Cassiani et al. (2016) built on this approach
516 by developing a model of the unsaturated zone flow using 3D Richard's equations. This revealed the potential of
517 the method for monitoring and possibly predicting the time at which fresh irrigated water replaced saline water
518 already present in the soil.

519 Cassiani et al. (2015) used a 3D ERT system to monitor the root zone of an orange tree. Other measurements of sap
520 flow, eddy covariance and evapotranspiration were used in combination to develop a 1D model based on Richard's
521 equation, which described the water dynamics of the monitored soil volume. This calibration was successful and
522 predicted a much smaller water volume than the resistivity derived estimation. The implication was that over
523 50 % of irrigated water was not taken up by plants, illustrating the importance of quantitative modelling to help
524 interpret electrical monitoring data. Furthermore, Consoli et al. (2017) monitored and compared the impact of
525 full versus partial irrigation, based on a reduction of water input by 50%. The study showed that water efficiency
526 and fruit yield increased when a partial irrigation regime was used, which also implied that overirrigation affected
527 productivity.

528 **3.3.1.3 Enhancing the pedotransfer calibration**

529 In an effort to avoid site-specific calibrations and to make the irrigation process more efficient, Brillante et al.
530 (2014) developed a pedotransfer function to estimate WC from ER data. The function is obtained through the use
531 of a learning algorithm and estimated soil water wetness. It performed moderately well, showing a correlation of
532 0.67 between measured values and resistivity derived estimates of WC. Nonetheless, the methodology holds promise
533 due to its potential to reduce laboratory effort to calibrate the resistivity results.

534 Moreno et al. (2015) used a model of water flow and solute transport to differentiate between the contribution
535 of state variables (WC and salinity) to resistivity. Other studies discussed above have focused on plant inputs
536 (Cassiani et al., 2015; Ursino et al., 2014), whereas their study was aimed at improving the quantification of
537 non-plant related inputs to bulk resistance values. Both approaches are necessary in future modelling efforts.
538 Plant physiological measurements were combined with ERT measurements by Brillante et al. (2016), in a study of
539 grapevine. The work revealed that variability in the water uptake regimes was highly dependent on plant water
540 stress as striking differences between regimes during night and day were found. Brillante (2016) fitted two models
541 to predict soil water variation with the aid of field measurements of electrical resistivity. Instead of using absolute
542 values of electrical resistivity for model fitting, this study used their variations as predictors. They also used several
543 machine-learning techniques to tune the model parameters in order to avoid over-fitting. For the current datasets,
544 the gradient boosting machine method outperformed the others. Finally, the model results were compared to TDR
545 measurements reaching to a satisfactory agreement (RMSE 22.6%).

546 **3.4 Other applications**

547 **3.4.1 Resolving pedological parameters**

548 Morari et al. (2009) combined resistivity imaging, EMI and geostatistics and concluded that conductivity correlated
549 positively with coarser textural soil components and negatively with finer components. Furthermore, this approach
550 served as a basis for mapping subregions of the field within which crops are similarly affected by seasonal differences
551 in weather and soil management. Celano et al. (2010) conducted a survey with the aim of establishing a correlation
552 between pedological parameters, calculated through field sampling measurements, and electrical resistivity mea-
553 surements. As resistivity measurements are sensitive to differences in salinity, ERT proved efficient in detecting salt
554 accumulation in soil. Electrical monitoring was used to distinguish between different tillage systems in Basso et al.
555 (2010). Soil properties such as bulk density or water storage are affected by tillage, therefore resistivity profiles
556 showed significant differences between the soil practices. Future studies on this subject should consider correlating
557 the variation in the electrical response with soil structure appraised by higher resolution imaging methods (e.g.
558 X-ray CT). Kowalczyk et al. (2015) attempted to identify peat horizons through application of ERT, however, the
559 heterogeneity of the soil made the inversion results inconclusive. The inversion generalized the resistivity values
560 associated with the organic layers and treated them as parts of a sand layer, a result confirmed by a forward model
561 based on geological units determined by drilling. It would seem that, identifying soil peat horizons in this manner
562 is currently below the ability of the ERT method alone due to the length scales involved.

563 **3.4.2 Plant phenotyping**

564 Plant phenotyping is an emerging research area concerned with quantitative measurement of the structural and
565 functional properties of plants. Lu et al. (2018) compared root zeta potential for 17 types of crops using streaming
566 potential measurements whereby an electrical potential is generated when an electrolyte passes through a porous
567 plug with charged surfaces. The study only found distinctive differences between legumes and non-legumes, due to
568 a higher concentration of functional groups in the former. Combined ERT and EMI measurements were used to
569 phenotype roots in the field by Whalley et al. (2017). The result of their study suggested that by comparing the
570 shifts in patterns of soil moisture content, genotypes may be differentiated. Genotypic differences, more obvious
571 in dry conditions, were observed in depth of water uptake and in the extent of surface drying. This result is very
572 important for the economics of agricultural practices as the geophysical approach potentially saves time and effort
573 spent on root excavation for direct measurements. The effect of soil physicochemical properties on the discrimination
574 power of this method has yet to be investigated. Therefore, the first step is to test the phenotype discrimination
575 methodology under different agropedoclimatic conditions and subsequently verify which factors enhance or diminish
576 it.

577 4 Discussion and future outlook

578 4.1 Geoelectrical methodology and capabilities

579 4.1.1 Choice of geoelectrical method

580 The majority of geoelectrical methods are concerned with measurements of electrical impedance (Section 2.3). The
581 main distinction between the nature and complexity of information resides in the information extracted from such
582 measurements. Firstly, we can distinguish between single-frequency and multi-frequency acquisition strategies.
583 Multi-frequency measurements offer additional information about polarization processes, but extracting electrical
584 parameters, such as chargeability or relaxation time across a frequency spectrum is not straightforward and requires
585 more acquisition time. However, methodology (Weigand and Kemna, 2017), instrumentation (Zimmermann et al.,
586 2008) and sampling strategies (Weigand and Kemna, 2016) associated with spectral methods are rapidly developing
587 and are likely to replace the more extensively used single-frequency or DC methods, such as ERT, for root zone
588 monitoring applications.

589 One of the overarching themes of this review is root detection. There is clear evidence for a strong correlation
590 between the imaginary resistivity component and root parameters (Chloupek et al., 1972; Ellis et al., 2013; Weigand
591 and Kemna, 2017), but several studies have also found a correlation between the real part and root parameters
592 (Cermak et al., 2006; Amato et al., 2008; Rossi et al., 2011). However, electrical resistivity was only correlated to
593 root biomass and failed to reflect other root physical parameters such as root length density. In addition, resistivity
594 studies showed greatest success when investigating woody roots, and further studies indicated that the resistivity
595 contrast generated by low-density herbaceous roots is indistinguishable from the effect of other root zone features
596 such as WC or grain size (Rossi et al., 2011). Furthermore, methods that include measurements of polarization have
597 the potential of resolving not only root physical parameters, but characteristics of root activity such as interactions
598 with fungi colonies (Cseresnyés et al., 2013) and reaction to physiological stress (Weigand and Kemna, 2017) or even
599 root health (Sabo et al., 2016a). In summary, measurements of imaginary impedance have proven more conclusive
600 for root investigation and offer a broader range of applications.

601 Figure 7 shows the increase in research articles featuring geoelectrical applications in the root zone, which highlights
602 the rising interest in the use of such methods. It also shows that the use of classical ERT is in decline compared
603 with other methods, whereas the use of ECM and SIP is growing. In addition, our analysis shows that the number
604 of laboratory studies in this area has grown over time. This clearly reflects the increased effort dedicated to method
605 development, especially for advance geoelectrical methods beyond ERT. These tend to require significantly more
606 sophisticated instrumentation and greater care to obtain good quality measurements. So far they have therefore
607 mostly been employed ex-situ, although field applications are likely to increase once the methodology development
608 has reached a greater level of maturity.

609 4.1.2 Acquisition set-up and inversion algorithm

610 The dimensionality aspect of geoelectrical investigation is not to be treated lightly in the context of root zone
611 monitoring. Previous research makes a clear distinction between the appraisal of a finer discretized model monitoring
612 a singular root system, usually at lysimeter scale, and coarser models, usually at field scale. In addition, field
613 surveys obtain a 3D properties distribution either by collating multiple 2D acquisition lines of superficial electrodes
614 (Leucci, 2010) or by using a square array of acquisition with borehole electrodes (Cassiani et al., 2016). Using
615 just one acquisition line, for 2D surveys, implies an easier set-up and quicker repetitive measurements. However,
616 an agriculture field-site displays spatial heterogeneity, which this type of set-up fails to capture. A 3D survey by
617 multiple superficial electrodes will provide the data coverage required, but will imply an expense in resolution. In
618 contrast, using borehole electrodes allows higher resolution (especially in depth) but limits the user to a confined
619 field sub-volume of investigation (1-2 m^3).

620 We mentioned previously (section 2.3) that the tomographic model mesh of the subsurface is discretized according
621 to the specific volume of investigation. However, the inversion problem becomes increasingly delicate when one
622 attempts to obtain a model of the root zone. Firstly, there is a question of scale which closely matches the
623 acquisition options described above. A lower resolution survey (depending on electrode arrangement) will imply
624 coarser mesh discretization. Secondly, there is a question of electrical property variability. The root, rootles soil
625 and the volume surrounding their interface (i.e. the rhizosphere) can be considered as electrically distinct areas,
626 which in consequence can be constrained differently. As we have demonstrated, knowledge about each of these areas
627 exists individually. However, the challenge for future research is to collate this information into one electrical model
628 and further refine inversion strategies around this parametrization. For example, providing one has information
629 about the extent of the root system, this volume can be also meshed, disconnected and assigned a different smoothing
630 factor from the rest of the surrounding soil.

631 4.1.3 Electrical response from woody versus herbaceous roots

632 The two categories of roots display different electrical responses. Essentially, the difference in size, not the root
633 functionality, appears to account for the distinction. The larger woody root, with a higher density and surface area,
634 showed higher correlations with electrical resistivity and had a bigger impact on its change than finer roots found
635 in the same system (Rossi et al., 2011). In terms of polarization, other soil properties, such as WC, are important
636 in order to obtain a good response (Mary et al., 2016,2017). Furthermore, both types of roots show polarization,
637 but not necessarily at the same frequencies. Weigand and Kemna (2017) reported a strong polarization at 70 Hz
638 for herbaceous roots and Mary et al. (2017) reported 1 Hz to be suitable for woody roots. The distinct polarization
639 frequencies could prove to be important for root classification if future research considers the analysis of larger scale
640 root systems, which contain both kinds of roots.

641 4.2 Knowledge gaps in pedophysical relationships

642 It is a common observation in the literature that none of the previously developed pedophysical relationships
643 (pedotransfer functions for geoelectrical data) is perfectly adapted to the specific site conditions (e.g. soil texture,
644 porosity, organic matter content) under investigation (Laloy et al., 2011). Therefore, calibration is usually required
645 in order to empirically determine new functional parameters corresponding to each individual site.

646 4.2.1 Formulating pedophysical relationships in the lab

647 When considering a rootless soil calibration, most of the studies that have employed pedophysical calibration for field
648 measurements have used soil samples repacked ex-situ. It is extremely difficult to recreate the chemical composition
649 of the pore water (Furman et al., 2013) and a sample's natural pore structure under laboratory conditions. Working
650 with disturbed samples disregards the effect of pore tortuosity, considered essential when evaluating conductivity
651 pathways and consequently bulk resistivity measurements (Rhoades et al., 1989). Also, agricultural soils are quite
652 frequently subjected to anthropic interactions, which generate spatial and temporal variations which can effect
653 soil compaction. The latter is known to be a direct control on resistivity (Romero-Ruiz et al., 2018). In these
654 circumstances a well suited approach is performing calibration measurements on undisturbed soil samples or to be
655 attempted in-situ (Srayeddin and Doussan, 2009; Michot et al., 2003).

656 We previously mentioned (section 2.2 and 3.1.1) the distinction some of the studies make between analysing electrical
657 properties of the rootless soil, the root system or the root zone as a whole. We consider each has its own merit and
658 corresponding relationships between root zone properties and electrical parameters important for future research.
659 Currently, many studies referenced in our review (Srayeddin and Doussan, 2009; Celano et al., 2011; Garré et al.,
660 2013) are interested in the observation of root activity (e.g. suction), therefore being able to translate electrical
661 measurements to WC balance of the target volume is crucial. In this case one would not be able to depict the
662 outline of root system itself, but only delineate the impact on the surrounding soil. However, one can expand this
663 methodology and determine root suction variability under different climatic, nutrient availability or soil textural
664 conditions. This will contribute to our knowledge of plant health and yield potential. Also, plant phenotyping
665 represents a promising potential application of geoelectrical research as suggested (Whalley et al., 2017). However,
666 the methodology needs to be proven suitable in different environments before its effectiveness can be demonstrated.
667 Furthermore, one may be interested in quantifying root development, therefore firstly would require the derivation
668 of a clear electrical response from the rootless soil. Any variation from the base electrical spectrum would imply root
669 mass development or root activity. The rate of development obtained as such could determine a plant's medium
670 adaptability or its interaction with other elements of the ecosystem.

671 4.2.2 On the variability of pedophysical relationships

672 Garré et al. (2011) underlined the necessity for horizon-specific calibrations for an undisturbed soil column. Also,
673 Furman et al. (2013) acknowledged climate seasonal variations in climate cause not only changes in WC, but also salt

674 accumulations, thus making concentration of solutes in the water-filled pore spaces variable with time. Ultimately,
675 for an accurate description of soil properties it is desirable to include high spatial and seasonal temporal variability.
676 We have mentioned above the effect of roots on bulk resistivity measurements, which is caused by the electrically
677 conductive pathways they form (created by the nutrient solution absorbed through the xylem) and EDLs both at
678 the exterior and interior surfaces of the root. The literature offers examples of empirical relationships between root
679 biomass and resistivity (Amato et al., 2008), therefore we recommend future studies should include this aspect
680 in the formulation of pedotransfer functions. Also, root system development alters the soil structure and its
681 chemical properties, invariably changing the electrical properties of the surrounding soil. Future research should
682 therefore consider combining existing numerical simulations of root architecture and its impact on soil hydraulic
683 properties (Postma et al., 2017) with geoelectrical numerical models in order to achieve a more realistic pedophysical
684 calibration.

685 **4.2.3 Computational approaches in pedophysical calibration**

686 A different way of approaching the translation is emerging from the field of data science, including 'big data' analytics
687 and parameter prediction methods based on machine learning. Rather than attempting to develop a universal
688 analytical transfer function, a more adequate result might be obtained by calculating an 'educated estimate' based
689 on prior knowledge from existing data. Provided a sufficiently large input dataset exists, deep learning algorithms
690 can be utilized to predict an effective representation of the desired output parameter. Examples of work in this
691 direction have already appeared in the literature (Brillante, 2016). An emerging trend in data science is convolutional
692 neural networks (Pound et al., 2017). These computational systems, inspired by natural neuronal architectures,
693 have the capability of developing a learned strategy that extracts the relevant characteristics from an existing
694 series of inputs. When presented with a new input, the neural networks are able to identify in the new input
695 the characteristics previously learned (based on the learned model) and subsequently classify or make a prediction
696 from it. These kinds of algorithms are now widely used in image processing and pattern recognition. In soil
697 science applications, a neural network could be used to predict moisture content, provided it was 'trained' with a
698 large enough dataset containing other soil parameters including electrical data. Future opportunities will lie in the
699 potential of such networks to transfer between domains. This implies that a network trained on a wide range of
700 different experimental conditions could capture a more general model of the transformation which in turn could be
701 tuned to new conditions by additional training with a comparatively small amount of data. Attempts to use such
702 networks in soil and rock physics have already been reported in the literature (e.g. Pachevski and Timlin, 1996;
703 Koekkoek and Booltink, 1999). Also, different machine learning methods are already being employed in an effort
704 to enhance the fit between models of soil water balance and electrical resistivity data (Brillante, 2016).

705 4.3 Enhancing the geoelectrical characterization of the root zone

706 The tomographic imaging capability of geoelectrical methods offers unique quantitative information about the
707 spatial variability of soil properties. Especially for field investigations it is desirable to be able to obtain large scale
708 images of the subsurface. However, geophysical inversion is ill-posed and requires regularization, ideally combined
709 with additional (a-priori) information in order to create an accurate model of the subsurface. The constraints are
710 often unsatisfactory when inversion is applied to geoelectrical data alone. In this section we discuss strategies to
711 reduce the uncertainty in the geoelectrical images.

712 4.3.1 Use of complementary datasets

713 In Section 3.1 and 3.2 we have discussed studies that simultaneously employed ERT together with other electromag-
714 netic methods for synergetic monitoring and characterization of soil moisture. Complementary techniques include
715 TDR (Beff et al., 2013, Boaga et al., 2013, Michot et al., 2003) GPR (Musgrave and Binley, 2011; Leucci, 2010) or
716 EMI (Cassiani et al., 2012; Morari et al., 2009; Whalley et al., 2017).

717 The most commonly used method that provides complementary data is TDR. It measures the dielectric permittivity
718 of the soil which is subsequently converted into SWC (Topp et al., 1980). TDR probes position usually follows the
719 electrode arrangement used for geoelectrical surveying (Figure 2). This offers the advantage of directly comparing
720 results without the need for correction for spatial distribution, scale or mesh discretization. Therefore, in the con-
721 text of geoelectrical research, TDR data is mainly used for ground truth and can help isolate the contribution of
722 SWC to the bulk resistivity response. Given the prevalence of TDR measurements in the literature, it could easily
723 be assumed that TDR is sufficient for monitoring soil moisture variability. However, whilst TDR does provide good
724 temporal resolution, is restricted to single point measurements, and therefore offers only limited spatial coverage.

725 In contrast to TDR, the output of GPR and EMI is an image of the subsurface, therefore they generally provide
726 good spatial coverage. GPR offers a high spatial resolution and is primarily used to delineate zones with different
727 lithology. Due to the physics of low frequency electrical flow, it is difficult to obtain sharp lithological boundaries
728 (including soil horizons) from ERT images (e.g. Figure 5), but GPR data has the potential to enhance this (Mus-
729 grave and Binley, 2011). Due to the nature of the instrumentation, EMI provides a very fast and effective way of
730 determining the spatial distribution of soil electrical conductivity and resolving lateral contrasts on a large (field-)
731 scale. However, EMI is faced with intrinsic challenges such as the lack of vertical resolution. When combined with
732 ERT, it is possible to obtain comprehensive field-scale models of conductivity variation both laterally and vertically.
733 Joint interpretation of this kind has proved successful for aquifer characterization (Linde et al., 2006) or estimating
734 field scale soil hydraulic conductivity (Farzamian et al., 2015). Previous authors have highlighted the capabilities
735 of a combination of EMI and ERT for root zone imaging and soil moisture characterization (al Hagrey, 2007).

736 Other complementary methods involve measuring soil parameters destructively. A number of studies presented in
737 this review (Amato et al., 2008; Rossi et al., 2011; Celano et al., 2010; Zenone et al., 2008) quantified root length
738 density (RLD) or root biomass (RMD) by collecting all the roots in the analysed sample and measuring their length

739 and weight, before correlating this information to electrical results. This procedure is perhaps useful for proof
740 of concept, but a fully non-invasive strategy is clearly more desirable for practical applications, particularly for
741 monitoring processes in the root zone over time.

742 **4.3.2 A-priori information about the root zone**

743 Soil structural details are an example of the kind of highly relevant additional information required and represent
744 a good source of a-priori knowledge. Alternative methods of tomographic imaging from other fields of science are
745 well developed, including X-ray CT, MRI or neutron imaging. These are able to provide details of soil structure at
746 high resolution (down to $1\ \mu\text{m}$). There is significant future research potential in conducting joint experiments that
747 include the synergetic application of geoelectrical methods and high-resolution structural imaging methods, both
748 appraising the same soil volume. Early attempts were made by Olsen et al. (1999) and Cassiani et al. (2009) using
749 X-ray information to explain patterns in the electrical response, but conclusions were qualitative and a quantitative
750 link is currently missing. Three-dimensional reconstruction of the pore architecture to a high resolution allows the
751 calculation of pore network parameters (e.g. pore diameter, connectivity). On this basis, subvolumes of the pore
752 space that account for fluid percolation in the soil sample can be identified (Koestel et al., 2018). This information
753 can in turn be used to constrain geoelectrical inversion results, e.g. by specifying regions of the soil volume with an
754 increased or decreased propensity to fluid movement. Those regions are likely to be associated with greater changes
755 in electrical properties.

756 X-ray CT is also a very effective ground-truth method for root characterization as it permits reconstruction of
757 the root system to a high spatial resolution by segmenting radiograms of the root zone (Mairhofer et al., 2016).
758 This kind of information can be parametrized accordingly and included into coupled frameworks containing both 3D
759 electrical and root architectural data. As previous laboratory polarization studies have looked at roots in hydroponic
760 solutions (Cao et al., 2010; Weigand et al., 2017,2018) this strategy can serve to develop our understanding of root
761 electrical properties in soils. The exact spatial position of every root segment can be used to modify the finite
762 element mesh of the starting model for the geoelectrical inversion. We have highlighted studies that represent the
763 root system as an electrical circuit analogue (Dalton et. al. ; Cao et al., 2011); in that context the root segment
764 contribution to electrical properties can be quantified. Subsequently this contribution can be associated with the
765 corresponding mesh element and its impact on the electrical inversion results assessed (Rao et al., 2018). Given
766 that previous research has established that preferential infiltration can happen along main root channels (Werban
767 et al., 2008), it is therefore possible to quantify the contribution of individual root segments to water uptake using
768 suitable parametrization in the geoelectrical model.

769 **4.4 Enhancing root zone conceptualisation**

770 Various authors have suggested conceptual models for the root zone, including models (complete list in Appendix
771 B) that represents root materials as resistors (Cao et al. 2010; Ellis et al. 2013), models which account for water

772 movement (Cassiani et al. 2016; Ursino et al. 2014) or a model that accounts for both, biomass and soil moisture
773 (Cassiani et al., 2012). In this section we will discuss the current state of conceptualization of the root zone and
774 propose future research opportunities from a geoelectrical perspective.

775 4.4.1 Root analogue electrical circuit models

776 According to Ozier-lafontaine and Bajazet (2005), the root zone system can be electrically divided into multiple
777 components, namely the stem-root internal medium, the soil-root interface, the soil medium and the electrode con-
778 tact with the plant/soil. Every component has a different manifestation with respect to conduction and polarization.
779 Each requires careful electrical parametrization and their contribution to the overall electrical response needs to be
780 appropriately quantified. For example, currently there is no clear distinction between the contributions from the
781 root mass and the root-soil interface to capacitance measurements.

782 The Dalton model is considered an important benchmark for the way the root system is electrically represented, as
783 multiple groups of Resistance-Capacitance (RC) pairs connected in parallel. However, inconsistencies in the Dalton
784 model have been reported (Dietrich et al., 2012; Ellis et al., 2013), forcing a rethink in the way the soil-root system
785 is electrically interpreted. One can regard the Dalton model as an oversimplified analogue, and in fact a more
786 comprehensive model includes a combination of series and parallel RC groups Cao et al. (2010). Furthermore, for
787 hydroponic systems, both Dietrich et al. (2012) and Cao et al. (2010) suggest that the root tissue above the solution
788 surface is the main contributor to capacitance and resistance. The analogue circuit model architecture and relative
789 contribution of individual components are key concepts that will guide the future quest for more effective models
790 of the root zone.

791 4.4.2 Separating contributors to the electrical response

792 Recent studies have attempted to develop models which simulate the soil system water balance and use them as
793 a substitute for collecting field data, highlighting the effectiveness of an accurate model (Cassiani et al., 2012).
794 Frequently, soil electrical conductivity changes are solely attributed to variations in WC, but in fact multiple con-
795 tributors can be responsible, including levels of salinity or organic content and distribution. Therefore, quantitative
796 models require a clear separation between such contributors when computing electrical conductivity. It is also im-
797 portant that model boundaries take into account the open nature of the system being studied, as energy and mass
798 are exchangeable with the medium surrounding the modeled system. Many models lack robustness from the poor
799 definition of boundary fluxes (Garré et al., 2011). Therefore, better mathematical expressions of such exchanges
800 are required, reflecting evapotranspiration, rain water influx, groundwater movement and others.

801 Future laboratory studies should firstly focus on the rootless electrical response to water content variation and
802 only secondly introduce roots into the system once the medium is appropriately parametrized. Furthermore, the
803 presence of roots will undoubtedly change their surrounding medium. How much the different resulting elements,
804 such as: a modified soil structure, the suction power of root, mucilage formation or the presence of organic material
805 itself contribute to such change remains an unknown and must be explored.

806 4.4.3 Integrating plant hydrology models and geoelectrical measurements

807 The current state of computational technology allows the simulation and visualization of reasonably complex root
808 zone processes in four dimensions. Elucidating the impact of root architecture on root zone hydraulics is of increasing
809 interest especially for practical purposes, such as sustainable irrigation (Green et al., 2006). As different components
810 of the root system have different hydraulic properties (Javaux et al., 2013) the ability to simulate and quantify this
811 structural effect is essential for an accurate interpretation of monitoring root-water uptake. Access is already
812 available to models that can simulate root-growth for different plant types (e.g. CRootBox; Schnepf et al. (2017))
813 and even models that couple root growth with water or nutrient uptake simulations (e.g. OpenSimRoot; Figure
814 8). However, as underlined by Draye et al. (2010), it is still unknown if the soil or the plant is the main driver of
815 water flow, or indeed where the greatest barrier to water flow resides (e.g. root-soil interface, in the soil, in the
816 root). As geoelectrical data provide a proxy for imaging changes in WC, there is potential in developing a coupled
817 hydrological model of the root zone. From a plant research perspective, a useful review focused on plant biological
818 models across scales is given by Hill et al. (2013), who discusses the interplay between root biology and surrounding
819 soil system from cellular to crop level. The authors emphasize the need for monitoring quantitative changes in
820 root biology (e.g. hormones, water status, nutrients), a need that could potentially be fulfilled by geoelectrical
821 monitoring, as there is evidence that geoelectrical techniques are sensitive to root functional stress (Weigand and
822 Kemna, 2017). Hill et al. (2013) also argue for bridging the gap between genetic and environmental regulation. In
823 that context we believe that field scale geoelectrical surveys could provide an appropriate assessment of changes in
824 water dynamics, root activity or even root growth.

825 In the light of this, there is significant future research potential in developing a coupled multidisciplinary framework
826 for characterizing and monitoring root zone hydraulics (Figure 9). This framework comprises both a hydraulic and
827 an electrical model of the root zone. It will undertake forward simulations of root zone hydraulics and translate
828 the results to electrical properties via appropriate pedotransfer functions. The results will then be compared
829 with simulated electrical measurements acquired on the same soil volume. In Stage 1 we establish the baseline soil
830 medium and root network properties. This is followed by flow process modelling, expressing how does the properties
831 determined in the previous stage affect root nutrient/water uptake (Stage 2), mapping prior obtained parameters on
832 an appropriate mesh (Stage 3) and finally translating the model results into geoelectrical parameters (Stage 4). A
833 disagreement between both sets of results (measured and modelled geoelectrical parameters) would imply a shortfall
834 either in the way flow processes are implemented in the model or in the conversion between hydraulic and electrical
835 root zone properties (Figure 9 stage 2-3). The simulations could be iteratively repeated until the discrepancy is
836 minimized hence providing an opportunity to determine the value of unknown parameters which lead to the initial
837 misfit. This overall approach should allow us to simulate the electrical response in space and time holistically as
838 a function of both soil and root properties. At present, tools are available to conduct numerical simulations of
839 this kind at the individual plant scale, for example in laboratory containers under controlled conditions. Future
840 research could follow a similar strategy for field scale simulations, although there are other external effects such

841 as climate or vegetation growth (Cassiani et al., 2012), which need to be parametrized and integrated into the
842 modeling framework.

843 **5 Conclusions**

844 We sought to highlight the potential advantages and limitations that geoelectrical methodology can bring to re-
845 search in the soil sciences and in particular to root zone studies. Geoelectrical methods offer minimally invasive
846 data acquisition, are cost effective and have the ability to monitor key physical (soil water balance), chemical (soil
847 water salinity) and biological (root growth) processes in the root zone both in space and time. A body of literature
848 has developed, which shows these methods to be very effective for the examination of root zone water dynamics and
849 the detection and characterization of root architecture. We have presented and discussed the main characteristics of
850 both established and emerging geoelectrical methodologies. Currently, ERT is one of the best established and most
851 evolved techniques, however the information it delivers is limited to a single physical parameter and not without
852 ambiguity. ERT is by far the most frequently used technique in the literature, but other methods (e.g. SIP, TDIP,
853 EIT) provide more holistic measurements including electrical polarization. These have also proven their ability to
854 determine soil properties (albeit often under more controlled laboratory conditions), and can provide superior sen-
855 sitivity to root properties (e.g. mass, length), type (woody or herbaceous) and functions (e.g. evapotranspiration,
856 nutrient absorption). Future root zone research must therefore carefully consider the choice of geoelectrical method-
857 ology in experimental design. Particularly for larger scale root zone field studies the availability of techniques and
858 instrumentation is more limited.

859 Our evaluation of previous research has highlighted the difficulty of determining robust pedophysical relationships
860 (i.e. pedotransfer functions for geoelectrical data), which are required for meaningful property translation and
861 experimental calibration. We expect future research to take into account their variability in space and time and to
862 consider emerging trends in data science, including convolutional neural networks. Furthermore, due to the inherent
863 limitations in the spatial resolution of geoelectrical methods, we highlight the value of synergetic studies with other
864 soil assessment methods (e.g. TDR, EMI, GPR). Such a strategy is suitable for field scale characterizations of the
865 root zone and offers the potential of including high resolution soil and root structural information into geoelectrical
866 inversion models. Finally, we have demonstrated the benefits of geoelectrical information in root zone conceptual
867 modeling. We call for improvements to the analogue circuit representation of the root system components, under-
868 lining the need for separating the main contributors to the electrical property variations when constructing a model
869 and propose a coupled multi-disciplinary characterization and monitoring framework incorporating simulations of
870 plant growth-hydrological parameters and geoelectrical measurements.

871 These results underline the potential this methodology has to monitor and characterize vadoze zone hydraulic pro-
872 cesses. However, this study concerned rootless soil only, therefore the natural step forward would be to visualize and
873 appraise undisturbed soil volumes which contain roots. By monitoring how roots impact the hydraulic processes of
874 soil could offer new insights about root development, root health or even root-soil adaptability.

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Figure captions:

1136 Figure 1. Diagram of key theoretical characteristics associated to geoelectrical methods described. The dotted line
1137 connects the scheme branch with the corresponding geoelectrical method.

1138 Figure 2. Laboratory set-up of a geoelectrical soil column monitoring experiment A) Soil column lateral view B)
1139 Horizontal Cross-section view. Adapted from Garré et al. (2011), (Koestel et al., 2007).

1140 Figure 3. Three dimensional solute concentration distribution in 6 stages of infiltration. Corresponding time-steps
1141 are listed in the top-left corner. Extracted from Koestel et al. (2008).

1142 Figure 4. Field acquisition pseudosection line used for ERT surveys. Electrodes are grouped in a Dipole-Dipole
1143 sequence.

1144 Figure 5. 2D ERT field resistivity distribution variation with time under crops of Maize left and Sorghum right.
1145 Extracted from Srayeddin and Doussan (2009).

1146 Figure 6. Resistivity increment percent differences overlapped on 3D rendering of laser-scan point cloud of Pinus
1147 Pinea root system. a) 3D view b) 25 cm below surface c) vertical section. Extracted from Zenone et al. (2008).

1148 Figure 7. Bar chart indicating number of published articles which use Geoelectrical monitoring methods for the
1149 study of root zone processes.

1150 Figure 8. Schematic representation extracted from Postma et al. (2017) representing the model used that couples
1151 evapotranspiration, xylem transport and soil water dynamics. a) Soil pedon with the hydraulic head indicated in
1152 pseudo-color (left) and three barley root systems (right) taking up water from that column. b) Penman– Monteith
1153 equation was used for the simulation of transpiration and evaporation. c) Section of the simulated root network
1154 showing its edges and vertices d) Network model used for the simulation of water flow through the roots (Alm et al.,
1155 1992) e) Water transport in three dimensions in the soil was simulated by solving the Richards equation, which
1156 combines Darcy's law with mass conservation, using the finite element method.

1157 Figure 9. Stages of an interdisciplinary strategy to perfect root zone geoelectrical monitoring and corresponding
1158 conceptual models. In blue: Main steps of the strategy flowchart; In green: Existent auxiliary methods or models
1159 that can be used; In orange: Mathematical algorithms needed; Black arrow: Indicates the step succession; Dashed
1160 double arrow: Underlines the need of consistency between the two steps; Orange double arrow: Implies a comparison
1161 between the results.

1162 Note. Colour should be used for all the figures in print.

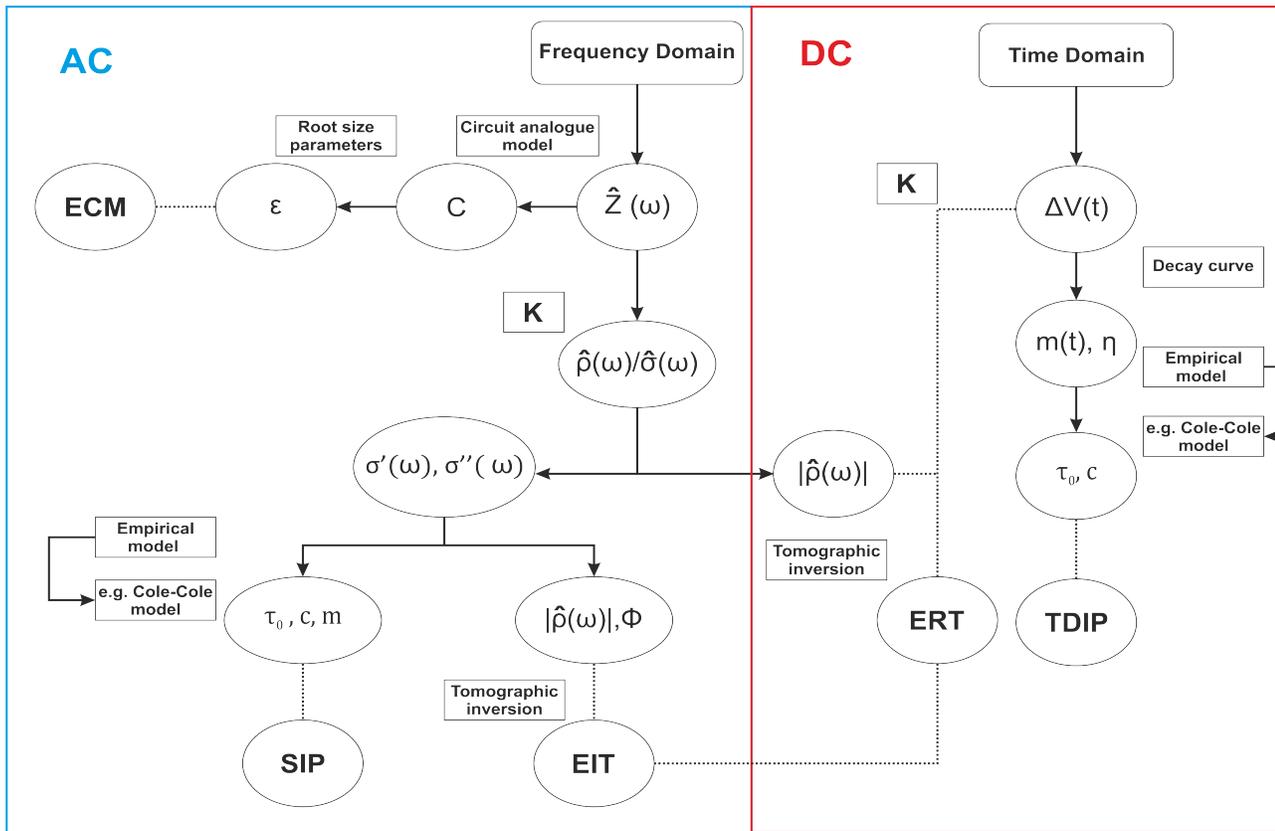


Figure 1

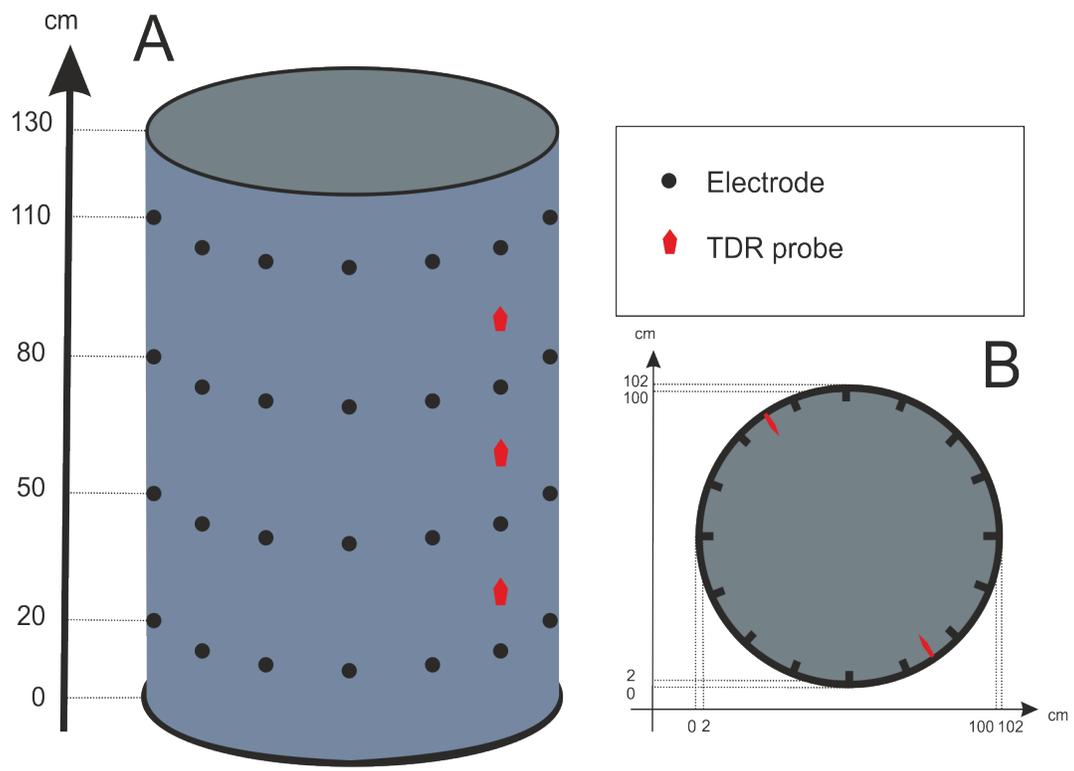


Figure 2

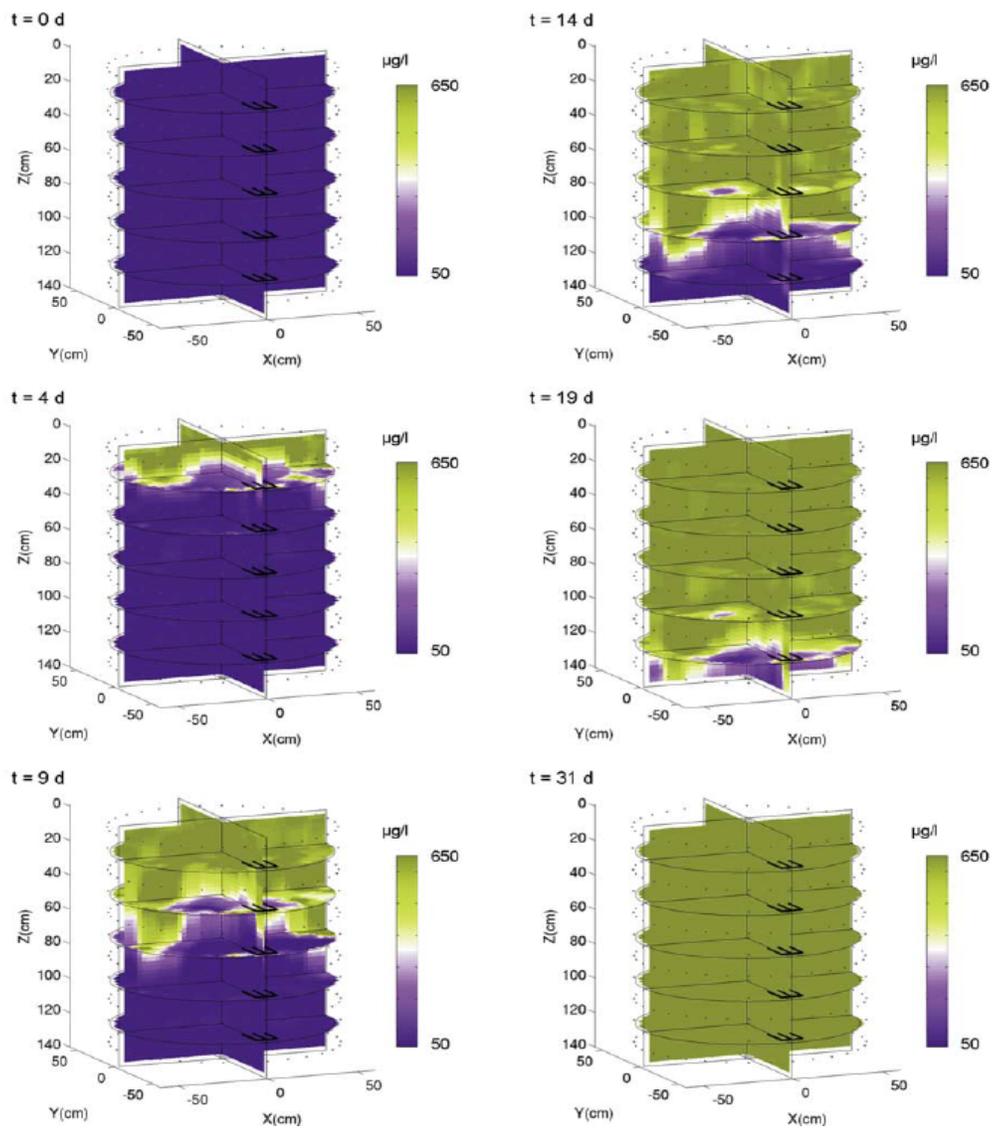


Figure 3

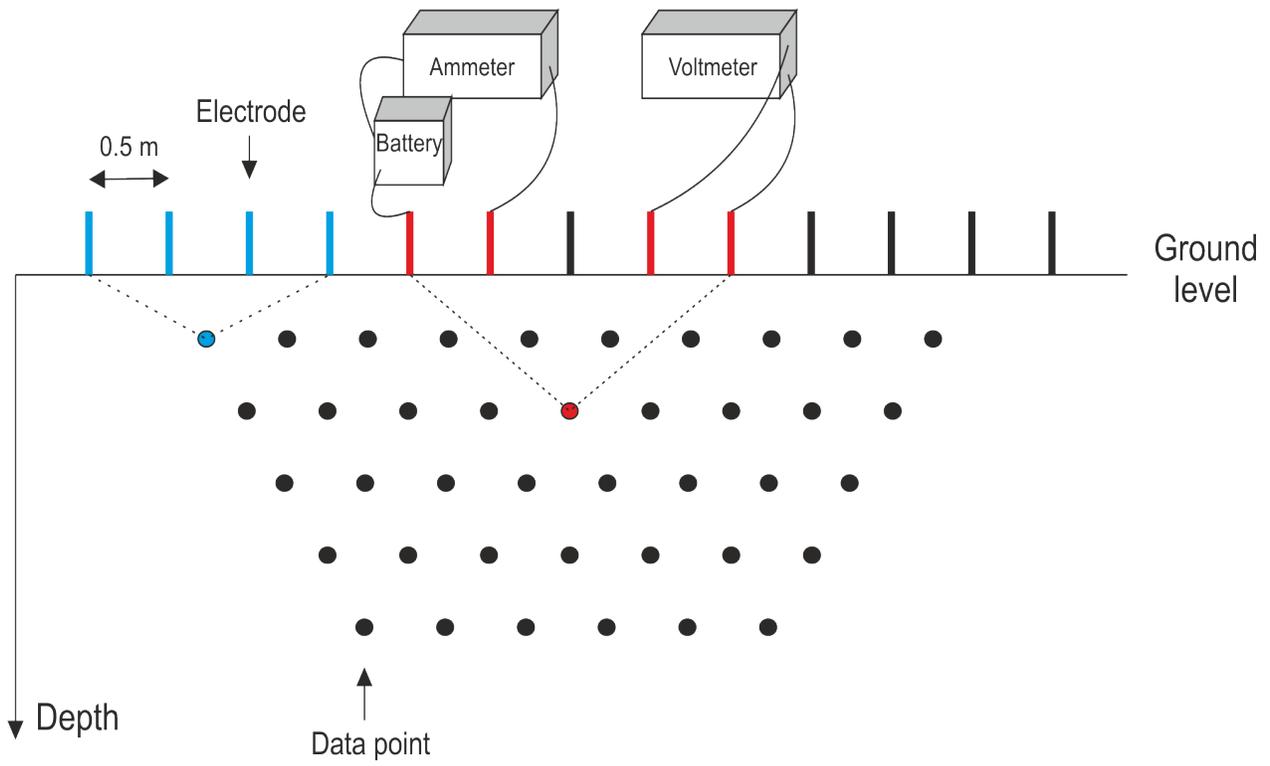


Figure 4

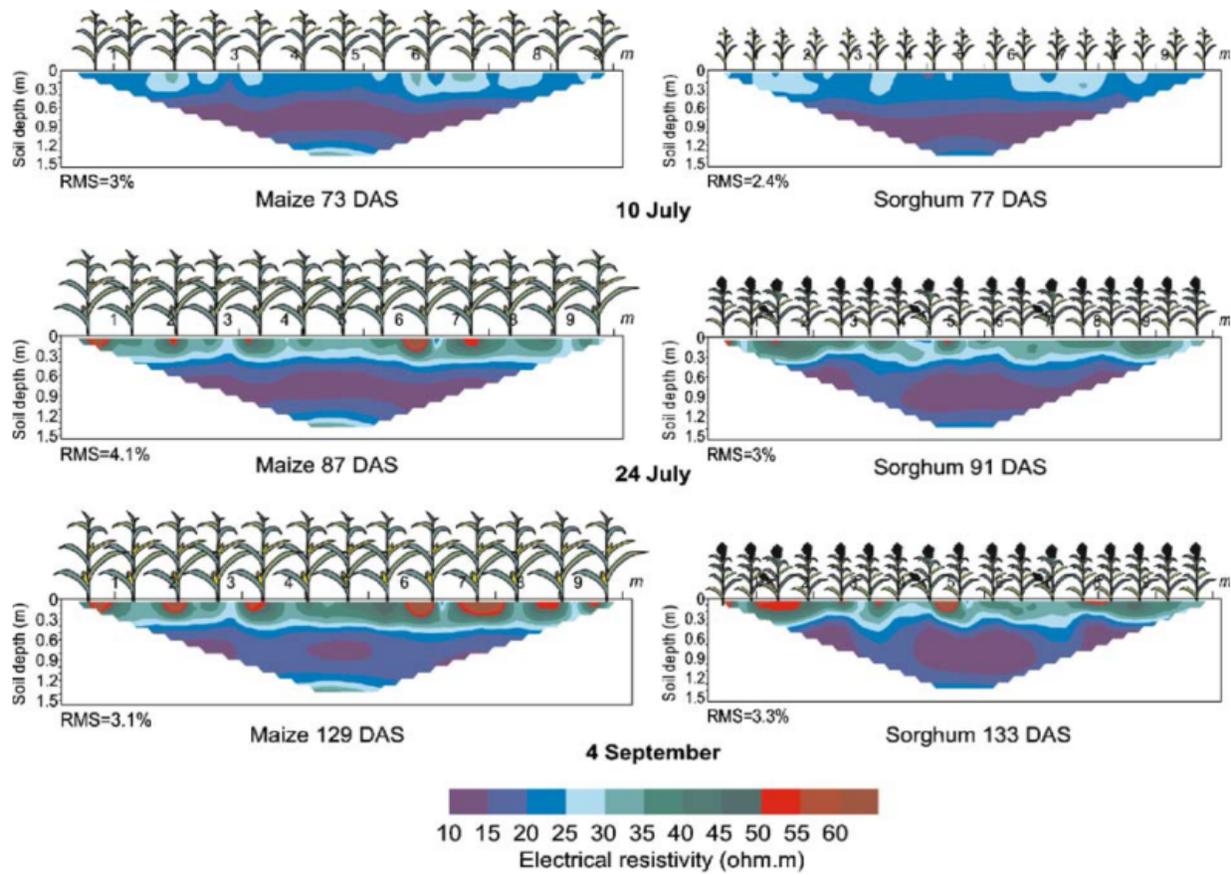


Figure 5

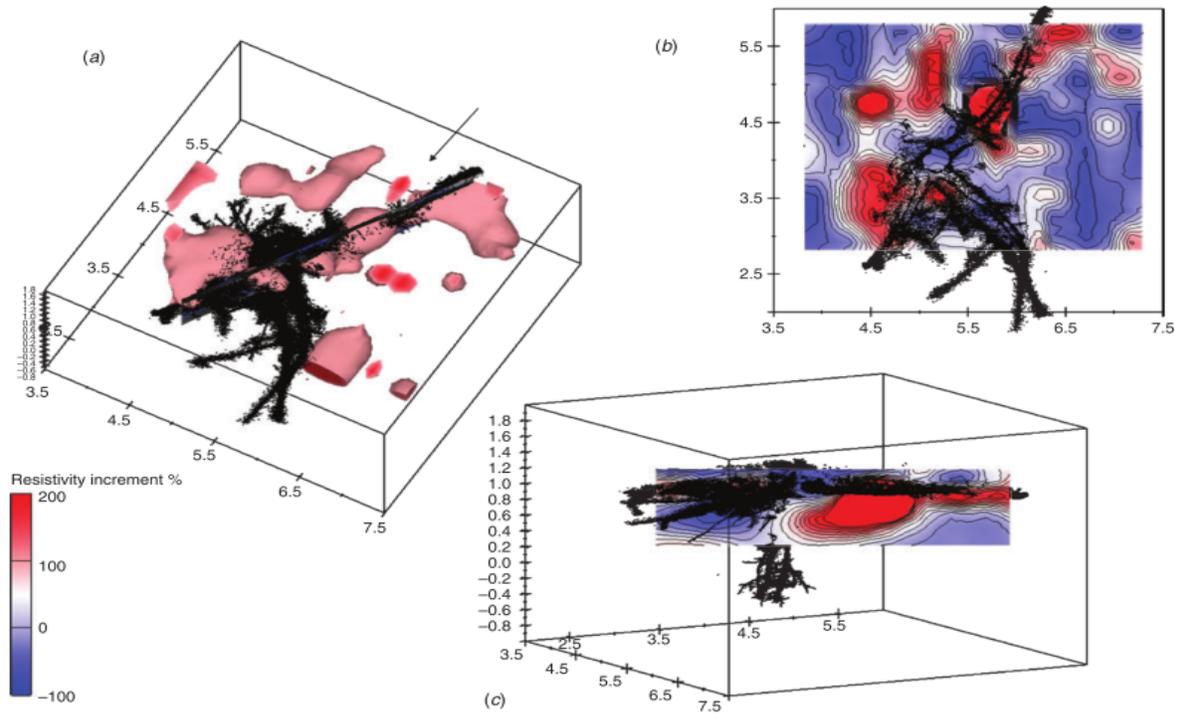


Figure 6

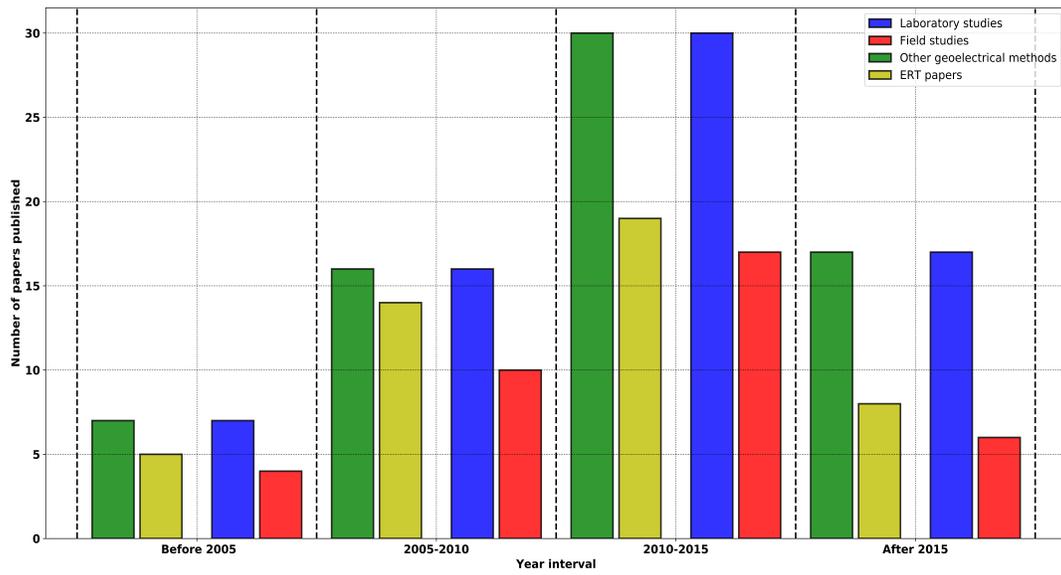


Figure 7

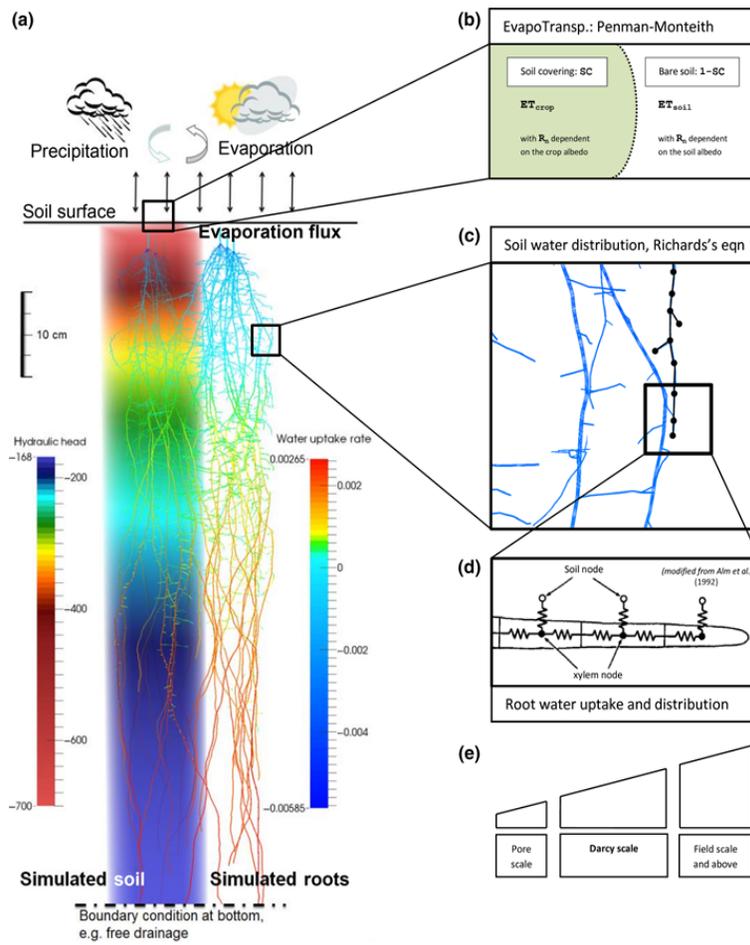


Figure 8

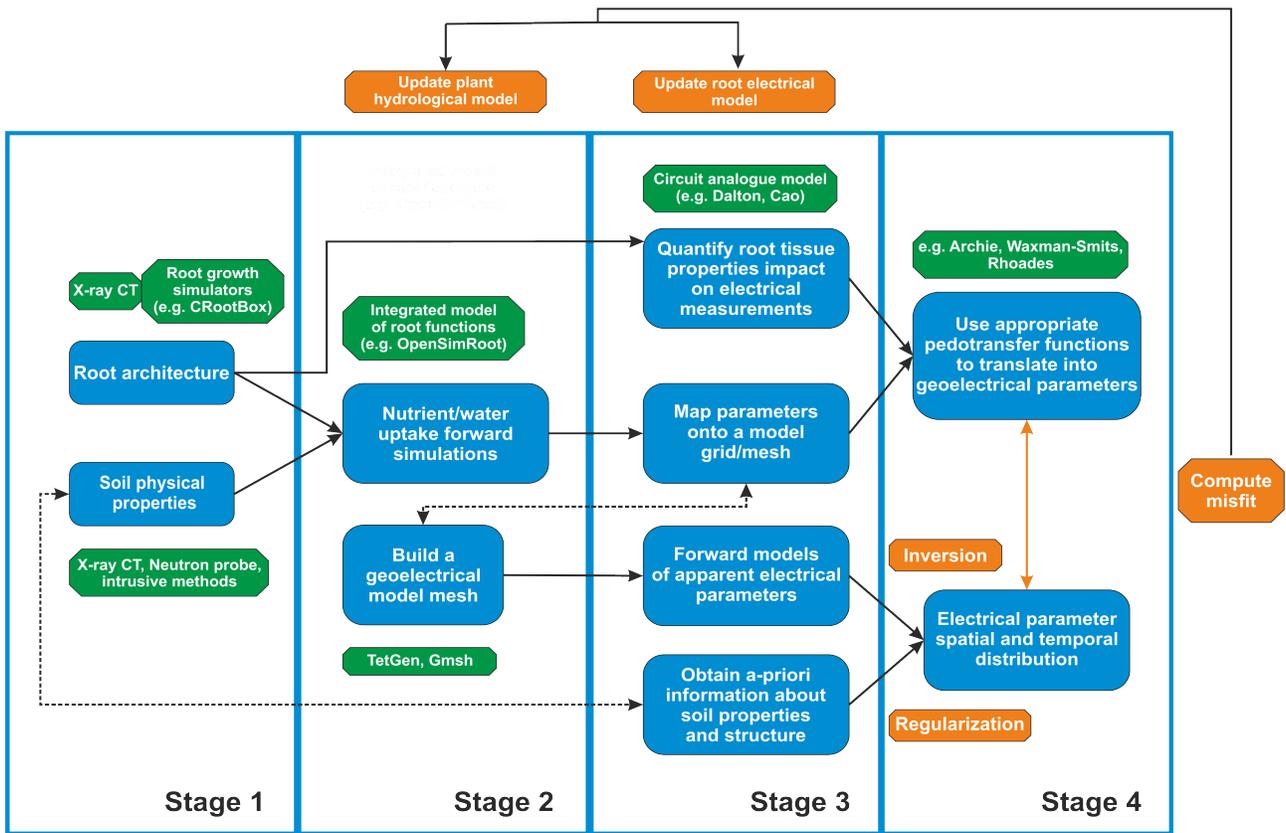


Figure 9

1163 Appendix A

Authors, year	Study environment	Geoelectric method	Dimensionality	Acquisition equipment/ Inversion algorithm	Complementary method
Amato, 2008	Field	ERT	2D	Geostudi Astier / Occam's inversion	Destructive samples
Amato, 2009	Laboratory	ERT	3D	Iris Syscal Pro ten-channel receiver / Occam's inversion	Destructive samples
Aulen and Shipley, 2012	Laboratory	EC	1D	BK Precision 879	Destructive samples
Basso, 2010	Field	ERT	2D	Iris instruments / Tomolab inversion	soil resistance to penetration data
Beff, 2013	Field	ERT	3D	SYSCAL Pro instrument / BERT Günther et al. (2006)	TDR
Binley, 1996	Laboratory	ERT	3D	UMIST Mk1b/Inversion algorithm explained in article	-
Boaga, 2014	Field	ERT	2D	IRIS Syscal Pro / R2T code Binley (2018a)	tensiometer
Boaga, 2013	Field	ERT	3D	IRIS Syscal Pro 72 / R3T Binley (2018b)	TDR
Brillante, 2014	Field	ERT	3D	Syscal Junior Switch 48 / RES2DINV	TDR
Brillante, 2016 a	Field	ERT	2D	Syscal Junior Switch 48 / RES2DINV Loke (2018a)	TDR, Pre-dawn leaf water potential
Brillante, 2016 b	Field	ERT	3D	Syscal Junior Switch 48 / RES2DINV	TDR, Pre-dawn leaf water potential
Cao, 2010	Laboratory	ER	1D	Fluke 8022A Multimeter / -	-
Cao, 2011	Laboratory	EIS	1D	SI1260/-	-
Cassiani, 2016	Field	ERT	3D	IRIS Syscal Pro / R3T	TDR
Cassiani, 2015	Field	ERT	3D	- / R3T	Sap flow and evapotranspiration

Cassiani, 2012	Field	ERT	2D	- / Occam inversion R,R2,R3T	EMI, TDR
Cassiani, 2009	Laboratory	SIP	1D	ZELSIP04/-	X-ray micro CT
Celano, 2011	Field	ERT	2D	Iris Syscal Pro / TomoLab/	Soil sample analysis
Celano, 2010	Field	ERT	2D	Iris Syscal Pro / TomoLab/	Soil sample analysis
Cermak,2006	Field	ER	1D	Megger/-	
Consoli, 2017	Field	ERT	3D	Iris Syscal Pro Switch 72 / Occam R3T	Sap flow
Cseresnyés, 2012	Laboratory	EC/EI	1D	HP 4284A LCR bridge/-	-
Cseresnyés, 2013	Laboratory	EC/EI	1D	HP 4284A LCR bridge/-	-
Cseresnyés, 2014	Laboratory	EC	1D	GW-8101G precision LCR instrument/-	-
Cseresnyés, 2016	Laboratory	EC	1D	GW-8101G precision LCR instrument/-	-
Cseresnyés, 2018	Laboratory/ Field	EC	1D	Agilent U1733C handheld LCR meter/-	TDR
Dietrich, 2012	Laboratory	EC	1D	Passive Component LCR Meter Extech Instruments/-	-
Ellis, 2012	Laboratory	EC	3D	MOTECH YMT-4080D/-	Destructive samples
Fan, 2015	Field	ERT	2D	SYSCAL Pro Switch / RES2DINV	TDR
Garré, 2013	Field	ERT	2D	Syscal Pro resistivity meter /	TDR
Garré, 2012	Field	ERT	2D	Iris Syscal Pro/ Gimli code	TDR
Garré, 2011	Laboratory	ERT	3D	RESECS prototype / Occam inversion	TDR, minirhizotrons
Guyot, 2013	Laboratory	ERT	2D	Picus TreeTronic / Picus Software	Macroscopic analysis of wood moisture an wood density
Jones, 2009	Field	ERT	2D	Campus Tigre 32/64 / RES2DINV	Levelling stations, neutron probe monitoring
Kelly, 2011	Field	ERT	2D	ABEM SAS 4000 Terrameter system / RES2DINV	C-probe
Kelter, 2015	laboratory	EIT	3D	Equipment and inversion developed in Zimmermann et al. (2008)	-

Koestel, 2007	Laboratory	ERT	3D	-/inversion by Binley (1995)	TDR
Koestel, 2008	Laboratory	ERT	3D	GeoServe RESECS/Occam inversion	TDR
Kowalczyk, 2015	Field	ERT	2D	ABEM system / RES2DINV	RCPT sounding
Kuhl, 2018	Laboratory	ER	1D	-/Joined hydrogeophysical inversion algorithm	Hydrological modelling, Plant parameter modelling
Leucci, 2010	Field	ERT	2D/3D	Iris Syscal R1 / RES3DINV Loke (2018b)	GPR, seismic refraction tomography
Lu, 2018	Laboratory	Zeta potential	1D	-/-	CEC;Surface charge measurements
Mares, 2016	Field	ERT	3D	IRIS Syscal Pro Switch 96/R2	Sap flow measurements
Martin, 2012	Laboratory	SIP	1D	SIP 256C / -	-
Mary, 2016	Laboratory	IP	2D	Lippmann Geophysical instrument and Terrameter / RES2DINV	Destructive samples
Mary, 2017	Laboratory	IP/SIP/TDIP	2D	COMSOL Multiphysics , LIPPMANN instrument / Matlab code	-
Mary, 2018	Field	ERT	3D	IRIS Syscal Pro Switch 72/R3T	MALM
Michot, 2003	Field	ERT	2D	Iris Instruments / RES2DINV	TDR
Michot, 2001	Field	ERT	2D	Iris Instruments / RES2DINV	TDR
Morari, 2009	Field	ERT	2D	Iris-Syscal Pro resistivity / ERTLlab software	EMI, sampling
Moreno, 2015	Field	ERT	2D	Syscal Pro Switch 96 / R2 software	TDT(time domain transmittance)
Musgrave, 2011	Field	ERT	2D	Geopulse Resistance meter/Occam type inversion	GPR, temperature probes
Newill, 2014	Laboratory	EIT	2D	Hewlett Packard 4192A /-	Compaction measurements
Njland, 2010	Field	ERT	2D	EarthImager2D / AGI algorithms	Soil sampling

Ozier-Lafontaine and Bajazet, 2005	Laboratory	SIP	1D	HP 4992 Impedance Analyzer/-	-
Panissod, 2001	Field	ERT	2D	- / RES2DINV	-
Rao, 2018	Laboratory	ERT	2D	EIDORS electrical modelling	WC modelling; SMARTROOT - root image analyzing tool
Robinson, 2012	Field	ERT	3D	A10 channel instrument / R3	Temperature probes
Rossi, 2011	Field	ERT	2D	Iris Syscal Pro 10 / Tomolab software	Destructive sampling
Sabo, 2016a	Laboratory	EC	1D	BK Precision 879B LCR	-
Sabo, 2016b	Laboratory	EC	1D	BK Precision 879B LCR	-
Srayeddin and Doussan, 2009	Field	ERT	2D	Terrameter SAS 4000 / RES2DINV	Neutron probe and tensiometer measurements
Thierry, 2001	Laboratory	IP	2D	LIPPMANN instrument	-
Ursino, 2014	Field	ERT	2D	- / ProfileR/R2/R	TDR
Weigand, 2017	Laboratory	EIT	2D	EIT-40 / Kemna inversion code Kemna (2000)	-
Weigand and Kemna, 2018	Laboratory	sEIT and EIS	2D	EIT40/CRTomo	-
Werban, 2008	Laboratory	ERT	2D	- / 2D FD-algorithm Loke and Barker (1995)	TDR
Whalley, 2016	Field	ERT	2D	Iris Syscal Pro electrical resistivity meter /inversion strategy in appendix	EMI, neutron probe, penetrometer
Wu, 2013	Laboratory	EC	2D	LCR meter/-	-
Zanetti, 2011	Laboratory	SIP	2D	SIP Fuchs equipment / -	-
Zenone, 2008	Field	ERT	3D	- / ERTLlab software	GPR
Zimmerman, 2008	Laboratory	EIT	2D	LABview and MATLAB / Kemna algorithm	-

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Authors, year	Area of focus	Pedotransfer model	Plant-soil interaction model
Amato, 2008	Plan organic material detection	No	Root mass density logistical growth model
Amato, 2009	Plant organic material detection	No	Regression model
Aulen and Shipley, 2012	Plant organic material detection	No	Regression model
Basso, 2010	Root zone water dynamics	Statistical regression model	No
Beff, 2013	Root zone water dynamics	WS	Mualen van Genuchten model (van Genuchten, 1980)
Binley, 1996	Root zone water dynamic	No	Dispersion model
Boaga, 2014	Root zone water dynamics	No	Compared with Marani et al. (2006)
Boaga, 2013	Root zone water dynamics	Archie	No
Brillante, 2014	Root zone water dynamics	Field based function	Pedotransfer model between ER and Soil volume wetness (SVW)
Brillante, 2016 a	Root zone water dynamics	Pedotransfer model obtained by machine learning methods	Soil volume wetness (SVW) available soil water (ASW) and fraction of transpirable soil water (FTSW)
Brillante, 2016 b	Root zone water dynamics	Pedotransfer model obtained by machine learning methods	ASW, FTSW, total transpirable soil water TTSW
Cao, 2010	Plant organic material detection	No	Plant system electrical circuit analogue
Cao, 2011	Plant organic material detection	No	Plant system electrical circuit analogue
Cassiani, 2016	Root zone water dynamics	Archie	Richards equation modelling
Cassiani, 2015	Root zone water dynamics	Laboratory calibration based on Archie	Van Genuchten model parametrization 1D Richards equation simulations
Cassiani, 2012	Root zone water dynamics	WS	Model of two mass balance equations: 1 for soil moisture, 1 for biomass
Cassiani, 2009	Soil contaminant dynamics	Fit to a Cole-Cole model	No
Celano, 2011	Root zone water dynamics	Laboratory calibration	No

Celano, 2010	Root zone water dynamics	No	Model relating hydraulics saturation, depth and electrical resistivity
Cermak, 2006	Root organic material detection	No	No
Consoli, 2017	Root zone water dynamics	On site calibration	No
Cseresnyés, 2012	Root organic material detection	No	No
Cseresnyés, 2013	Root organic material detection	No	No
Cseresnyés, 2014	Root organic material detection	No	No
Cseresnyés, 2016	Root organic material detection	No	No
Cseresnyés, 2018	Root organic material detection/ WC monitoring	No	Regression model
Dietrch, 2012	Plant organic material detection	No	Root electrical circuit analogue model
Ellis, 2012	Plant organic material detection	No	Compared data with Dalton model — Produced an empirical model
Fan, 2015	Root zone water dynamics	Archie	Derive capacitance model
Garré, 2013	Root zone water dynamics	WS	Hydrological model
Garré, 2012	Root zone water dynamics	WS	No
Garré, 2011	Root zone water dynamics	Simplified WS	No
Guyot, 2017	Sapwood-heartwood electrical differentiation	No	No
Jones, 2009	Tree induced subsidence	No	Tree subsidence model
Kelly, 2011	Root zone water dynamics	Revil model	No
Kelter, 2015	Laboratory soil water dynamics	No	No
Koestel, 2007	Synthetic water dynamics	Laboratory Calibration based on Revil	No
Koestel, 2008	Solute transport	Laboratory Calibration based on Revil	No

Kowalczyk, 2015	Soil peat horizon detection	No	No
Kuhl, 2018	Soil hydraulic parameters, Root parameters and Pedotransfer parameters estimation	Archie	SALUS and HYDRUS and FWD2-5D and SCE-UA
Leucci, 2010	Plant organic material detection	No	No
Lu, 2018	Differentiate between legume and non-legume roots	No	No
Mares, 2016	Root zone water dynamics	No	No
Martin, 2012	Oak impedance signature	No	Simple model based on a system with two parallel pathway for electrical charges (Marshall et al., 1959)
Mary, 2016	Plant organic material detection	No	No
Mary, 2017	Plant organic material detection	No	Cole-Cole model (Cole and Cole, 1941)
Mary, 2018	Plant organic material detection	No	Voltage forward modelling
Michot, 2003	Root zone water dynamics	Field calibration	No
Michot, 2001	Root zone water dynamics	Regression model calibration	No
Morari, 2009	Management zone delimitation	No	Linear model of coregionalisation
Moreno, 2015	Root zone water dynamics	Archie and WS	Model solute transport; separate soil WC from soil water salinity
Musgrave, 2011	Root zone water dynamics	No	No
Newill, 2014	Root zone water dynamics	No	Extend the Wang model (Wang et al., 2012)
Njland, 2010	Root zone water dynamics	Archie based calibration	No

Ozier-Lafontaine and Bajazet, 2005	Plant organic material detection	No	Root circuit analogue model
Panissod, 2001	Root zone water dynamics	No	No
Rao, 2018	Root zone water dynamics	Archie	Root zone water flow modelling
Robinson, 2012	Root zone water dynamics	No	No
Rossi, 2011	Plant organic material detection	No	Regression model — Compare with (Amato et al., 2008) model
Sabo, 2016a	Root health	No	No
Sabo, 2016b	Root health	No	No
Srayeddin and Doussan, 2009	Root zone water dynamics	In situ calibration	No
Thierry, 2001	Wood polarization effect	No	No
Ursino, 2014	Root zone water dynamics	No	Water balance model
Weigand, 2017	Plant organic material detection	No	No
Weigand and Kemna, 2018	Plant organic material detection	No	No
Werban, 2008	Root zone water dynamics	No	No
Whalley, 2016	Root phenotyping	Calibration with neutron probe measurements	No
Wu, 2013	Root zone water dynamics	No	No
Zanetti, 2011	Plant organic material detection	No	No
Zenone, 2008	Plant organic material detection	No	No
Zimmerman, 2008	Soil polarization properties	No	No

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