

1 **The ecology of wildlife disease surveillance: demographic and prevalence**
2 **fluctuations undermine surveillance**

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22 **Running title: The ecology of wildlife disease surveillance**

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24

25 **Summary**

26 1. Wildlife disease surveillance is the first line of defence against infectious disease. Fluctuations in
27 host populations and disease prevalence are a known feature of wildlife disease systems.
28 However, the impact of such heterogeneities on the performance of surveillance is currently
29 poorly understood.

30 2. We present the first systematic exploration of the effects of fluctuations' prevalence and host
31 population size on the efficacy of wildlife disease surveillance systems. In this study efficacy is
32 measured in terms of ability to estimate long-term prevalence and detect disease risk.

33 3. Our results suggest that for many wildlife disease systems fluctuations in population size and
34 disease lead to bias in surveillance-based estimates of prevalence and over-confidence in
35 assessments of both the precision of prevalence estimates and the power to detect disease.

36 4. Neglecting such ecological effects may lead to poorly designed surveillance and ultimately to
37 incorrect assessments of the risks posed by disease in wildlife. This will be most problematic in
38 systems where prevalence fluctuations are large and disease fade-outs occur. Such fluctuations
39 are determined by the interaction of demography and disease dynamics. Although particularly
40 likely in highly fluctuating populations typical of fecund short-lived hosts, such fluctuations
41 cannot be ruled out in more stable populations of longer-lived hosts.

42 5. *Synthesis and applications.* Fluctuations in population size and disease prevalence should be
43 considered in the design and implementation of wildlife disease surveillance and the framework
44 presented here provides a template for conducting suitable power calculations. Ultimately
45 understanding the impact of fluctuations in demographic and epidemiological processes will
46 enable improvements to wildlife disease surveillance systems leading to better characterization
47 of, and protection against endemic, emerging and re-emerging disease threats.

48 **Key-words:** wildlife disease systems, wildlife ecology, disease surveillance, demographic
49 fluctuations, wildlife populations, disease transmission models, stochastic population models

50 **Introduction**

51 Surveillance is the first line of defence against disease, whether to monitor endemic cycles of
52 infection (Ryser-Degiorgis 2013) or to detect incursions of emerging or re-emerging diseases (Kruse,
53 Kirkemo & Handeland 2004; Lipkin 2013)). Identification and quantification of disease presence and
54 prevalence is the starting point for developing disease control strategies as well as monitoring their
55 efficacy (OIE 2013). Knowledge of disease in wildlife is of considerable importance for managing risks
56 to humans (Daszak, Cunningham & Hyatt 2000; Jones *et al.* 2008) and livestock (Gortázar *et al.*
57 2007), as well as for the conservation of wildlife species themselves (Daszak, Cunningham & Hyatt
58 2000).

59

60 Recent public health concerns e.g. Highly Pathogenic Avian Influenza (Artois *et al.* 2009b) , Alveolar
61 Echinococcosis (Eckert & Deplazes 2004) and West Nile Virus (Brugman *et al.* 2013)), have led to a
62 growing recognition that current approaches need to be improved (Mörner *et al.* 2002). For
63 example, there is no agreed wildlife disease surveillance protocol shared among the countries in the
64 European Union (Kuiken *et al.* 2011). Furthermore several authors have identified the need for
65 improvements to the structure, understanding and evaluation of wildlife disease surveillance (Bengis
66 *et al.* 2004; Gortázar *et al.* 2007).

67

68 Much current practice for wildlife disease surveillance (Artois *et al.* 2009a) is based on ideas
69 developed for surveillance in livestock, including calculation of sample sizes needed for accurate
70 prevalence estimation (Grimes & Schulz 1996; Fosgate 2005) and detection of disease within a
71 population (Dohoo, Martin & Stryhn 2005). A common feature of these methods is that they assume
72 constant host populations and disease prevalence. These assumptions lead naturally to sample size
73 calculations (for both disease detection and prevalence estimation) which are based on a binomial
74 distribution and associated corrections for populations of finite size, such as the hyper-geometric
75 distribution (Artois *et al.* 2009a). Fosgate (2009) reviewed current approaches to sample size

76 calculations in livestock systems and emphasized the importance of basing analyses on realistic
77 assumptions about the system under surveillance.

78

79 Although constant population size and prevalence may often be reasonable assumptions for the
80 analysis of livestock systems, they are considerably less tenable in wildlife disease systems, which
81 are typically subject to much greater fluctuations in host population density and disease prevalence.

82 Both sampling practicalities and changes in population density make it much harder to obtain a
83 random sample of hosts of the desired sample size in wildlife disease surveillance programmes
84 (Nusser *et al.* 2008), compared with livestock systems. It is not uncommon for wildlife disease
85 surveillance to extend over several years and to test only a small fraction of the at-risk population.

86 For example, McGarry and co-workers report overall prevalence of zoonotic helminths in 42 brown
87 rats *Rattus norvegicus* captured in a programme of active surveillance carried out in an urban area in
88 England between 2008 and 2011 (McGarry *et al.* 2014). These authors also present comparable
89 results from several studies in Europe and North America while another of the same host species
90 conducted over a two year period across a broad area of north-western England captured just 133
91 individuals (Pounder *et al.* 2013). A notable example of passive surveillance i.e. the testing of found
92 dead individuals, is that for zoonotic West Nile Virus (WNV) in wild birds across the whole of Great
93 Britain during 2002–2009 in which only 2072 individuals representing 240 species were tested
94 (Brugman *et al.* 2013).

95

96 The importance of temporal (Renshaw 1991; Wilson & Hassell 1997), spatial (Lloyd & May 1996;
97 Tilman & Kareiva 1997) and other forms of heterogeneity (Read & Keeling 2003; Vicente *et al.* 2007;
98 Davidson, Marion & Hutchings 2008) in population ecology has long been recognized (Anderson
99 1991; Smith *et al.* 2005), along with their role in the dynamics and persistence of infectious disease
100 (Fenton *et al.* 2015). Detailed field observations have provided valuable insights into the temporal
101 dynamics of wildlife disease systems. For example a study (Telfer *et al.* 2002) of cowpox virus in two

102 rodent host species at two sites over a four-year period reveals strong temporal fluctuations in both
103 population size and disease prevalence including disease fade-out (local extinction and re-
104 emergence). Fade-outs are also observed in wildlife populations of longer lived mammals as shown
105 by a six-year study (Hawkins *et al.* 2006) of Devil Facial Tumour Disease in *Sarcophilus harrisii*
106 Tasmanian devil. One of the longest running and most intensive studies of disease in wildlife is the
107 surveillance from 1982 to the present of TB in badgers at Woodchester Park, England where around
108 80% of the population is trapped tested and released annually (Delahay *et al.* 2000). These long-
109 term observations have revealed important insights into the dynamics of TB in badgers e.g. that
110 infection within social groups is persistent whereas transmission between social groups is limited
111 (Delahay *et al.* 2000). Parameter estimates derived from this study are used as a reference point for
112 the simulation studies conducted below.

113

114 Despite these theoretical and empirical studies of temporal heterogeneities in wildlife disease
115 systems, such effects have yet to be systematically accounted for, either in the design of surveillance
116 programmes for wildlife disease systems, or in the analysis of the data obtained from them. Here
117 we address this gap by using a non-spatial simulation model of a wildlife host population, subject to
118 demographic fluctuations and pathogen transmission, in order to explore the impact of stochastic
119 fluctuations in host demography and disease dynamics on the performance of surveillance. Two
120 measures of surveillance performance are considered; estimation of long-term prevalence and the
121 ability (probability) to detect disease. Our results show that temporal fluctuations in wildlife disease
122 systems limit the ability of surveillance to achieve both.

123

124 **Materials and methods**

125 We develop a generic modelling framework that represents key features of surveillance in wildlife
126 disease systems including essential aspects of demography, disease dynamics and surveillance
127 design. This framework is described below along with three simulation studies that enable us to

128 explore the performance of surveillance across a wide range of scenarios representative of real
129 world systems.

130 Stochastic modelling framework

131 The model represents a host population subject to demographic fluctuations (births, deaths and
132 immigration) and the transmission of a single pathogen. At each point in time t , the state-space
133 represents the total population size $N(t)$, with $I(t)$ of these infected and $S(t) = N(t) - I(t)$
134 susceptible. The prevalence is then given by $p(t) = I(t)/N(t)$.

135 **Demography.** The birth rate of individuals is logistic, $rN(1 - N/k)$, with intrinsic growth rate r and
136 carrying capacity k , reflecting the assumptions that population growth is resource-limited.
137 Individuals have a per capita death rate μ and immigration occurs at a constant rate ν .

138 **Disease dynamics.** A proportion γ of immigrants are infected, but otherwise all individuals enter the
139 population (through birth or immigration) as susceptible, since we assume vertical and pseudo-
140 vertical transmission are negligible. Susceptible individuals become infected at rate $\beta_0 S(t)$ through
141 primary transmission (contact with infectious environmental sources including individuals outside
142 the modelled population) and at rate $\beta S(t)I(t)$ by secondary transmission (contact with already
143 infected individuals from within the population).

144 **Disease surveillance.** During a single period of surveillance (*surveillance bout*), individuals are
145 captured at per capita rate α , tested and released, and both the total number, and the number of
146 infected individuals caught are recoded. Perfect diagnostic tests are assumed although limited
147 sensitivities and specificities could be accounted for. A surveillance bout continues until a defined
148 sample size m is obtained or some upper time limit has been reached. Such surveillance is most
149 naturally considered in the context of active capture campaigns but could also be adapted to
150 samples obtained from hunting and passive surveillance by accounting for the losses and sources of
151 bias associated with such surveillance methods (see e.g. McElhinney *et al.* 2014).

152

153

154 **Model implementation.** The model framework is summarized in Table 1. Reported results are
155 temporal averages (e.g. expected mean $E[M]$ and variance $\text{Var}[M]$ in population size) based on long
156 run simulations following a burn-in period to allow the population to reach equilibrium where the
157 effects of initial conditions are negligible. Within each run repeated surveillance bouts are simulated
158 and the probability of detection PD is estimated as the proportion of bouts where disease is
159 detected. The mean $E[\hat{\rho}_{surv}]$ and variance $\text{Var}[\hat{\rho}_{surv}]$ of the prevalence estimates averaged over
160 repeated bouts are also recorded. We consider a continuous state-space implementation simulated
161 by numerically integrating a set of stochastic differential equations (SDEs) and a discrete state-space
162 implementation using the Gillespie algorithm (see Appendix S1 in Supporting Information for
163 details).

164 Simulation studies

165 **Study 1** (results shown in Fig.1 and Fig.3) uses the SDE implementation and is designed to explore a
166 generic but representative range of wildlife disease systems. Simulations were run for four values
167 (0.01, 0.04, 0.1, 1.0) of the secondary transmission rate β . In each case the population death rate μ
168 was varied over a wide range between 0.1 and 0.5, with the intrinsic growth rate set at $r=0.5$ so
169 that, at the upper end of this range, populations are highly unstable. This gives rise to typical
170 population sizes of 10–40 (see Fig.1a) and a wide range of disease prevalence. Similar results are
171 obtained from simulations (not shown) where β is varied for a set of fixed values of μ where
172 mortality rates span the interval $(0, r)$. Simulations not included here show that our results
173 generalize, holding for transmission rates relative to a recovery rate (governing an additional
174 transition from I to S) and death rates relative to birth rate, r . Different intensities of surveillance
175 were simulated using four capture rates α (0.01,0.1,1.0, 10), for a sample size $m=10$. Full
176 parameterizations for Fig.1 and Fig. 3 are shown in Tables S3 and S6 respectively.

177 **Study 1a** (results shown in Fig. 2) explores the effect of surveillance design using a subset of the
178 parameter sets considered in study 1, namely $(\beta, \mu)=: (1.0, 0.43); (1.0, 0.4);$ and $(0.1, 0.43)$. For
179 each, a range of capture rates $\alpha =0...10$ (with $m=10$) and a range of sample sizes $m=1, \dots,$

180 10000 (with $\alpha=0.1$) are considered. The values of all model parameters used are shown in Tables
181 S4 and S5.

182 *Relevance to real wildlife disease systems.* The intrinsic annual growth and death rates for badgers
183 have been estimated as $r=0.6$ and $\mu=0.4$ (Anderson & Trewhella 1985). Rescaling for $r=0.5$ as used
184 in simulation study 1 corresponds to a rescaled $\mu=0.33$. In addition the secondary transmission rate
185 for TB in badger populations was been estimated by the same authors to be $\beta=0.06-0.08$ assuming
186 a density of badgers necessary for disease persistence is ~ 5 badgers km^{-2} (Anderson & Trewhella
187 1985). The population size considered in simulation study 1 therefore corresponds to a surveillance
188 area of around 8 km^2 . The range of parameters considered in study 1 places badgers towards the
189 stable end of the spectrum. More fecund and shorter-lived species would be expected to be less
190 stable e.g. have higher mortality and secondary transmission rates. As noted earlier surveillance of
191 badgers at Woodchester Park is relatively intensive leading to an annual probability of capture of
192 around 80% corresponding to capture rates of $\alpha=1.6-2.2$ (Delahay *et al.* 2000). The population of
193 *Sarcophilus harrisii* Tasmanian devil discussed earlier consisted of between 20–60 individuals and
194 was subject to annual capture rates between 0.5 and 1.7 (Hawkins *et al.* 2006). Estimates of capture
195 rates are not available for the larger-scale studies referred to in the introduction (Brugman *et al.*
196 2013; Pounder *et al.* 2013; McGarry *et al.* 2014), but given the sample sizes obtained and the
197 temporal and geographic scales involved it seems reasonable to assume that they are considerably
198 lower. Simulation study 1 encompasses a wide range of real world wildlife disease surveillance.

199 **Study 2** (results shown in Fig. 4) is designed to test the robustness of study 1 by exploring a wider
200 range of scenarios: with intrinsic growth rates in the range (0,23); mortality rates in the range
201 (0.25,14), carrying capacities in the range (0,36) and secondary contact rates in the range (0.01,5).
202 Focussed on disease detection, results are conditioned on the presence of disease and simulations
203 based on the Gillespie implementation, which explicitly handles the discrete nature of small
204 populations. The values of all model parameters used in Fig. 4 are shown in Table S7.

205 **Results**

206 **Estimating prevalence**

207 In order to develop an understanding of the properties of wildlife disease surveillance using the
208 above model, we developed expressions describing prevalence estimates obtained by continuous
209 surveillance, i.e. continuously deployed effort resulting in per capita capture rate α .

210

211 Consider the interval $[0, T]$ during which the population history is $\mathcal{H}[0, T] = \{(N(t), p(t)) : t \in [0, T]\}$,
212 where $N(t)$ and $p(t)$ represent the population size and disease prevalence at time $t \in [0, T]$
213 respectively (see above). Let n_T represent the total number, and i_T the number of infected
214 individuals sampled during this time interval. Conditional on the history $\mathcal{H}[0, T]$, the expectations of
215 these quantities are:

216

217 $E[n_T | \mathcal{H}[0, T]] = \int_0^T \alpha N(t) dt$ and $E[i_T | \mathcal{H}[0, T]] = \int_0^T \alpha N(t) p(t) dt$.

218

219 The surveillance estimate of disease prevalence is simply the ratio $\hat{p}_{surv}(T) = i_T/n_T$. Since
220 immigration prevents extinction of the population and disease then the long time limit of this
221 estimate can be equated with its expectation over all histories as follows:

222 $\lim_{T \rightarrow \infty} \hat{p}_{surv}(T) = E[\hat{p}_{surv}] = \lim_{T \rightarrow \infty} \frac{\frac{1}{T} \int_0^T N(t) p(t) dt}{\frac{1}{T} \int_0^T N(t) dt} = \frac{E[N(t)p(t)]}{E[N(t)]}$.

223

224 This can be re-expressed in the more suggestive form:

225

226
$$E[\hat{p}_{surv}] = E[p(t)] + \frac{Cov[N(t), p(t)]}{E[N(t)]} \quad (\text{eqn 1})$$

227

228 Thus, when the covariance $Cov[N(t), p(t)] = E[N(t)p(t)] - E[N(t)]E[p(t)]$ between the
229 population size and the prevalence is non-zero, the surveillance estimate of prevalence is a biased

230 estimate of the true prevalence, $E[p(t)]$. Since $Cov[N(t), p(t)]$ will be zero when either $N(t)$ or $p(t)$
231 are constant, we conclude that demographic fluctuations and stochasticity in disease dynamics
232 undermine the efficacy of surveillance.

233 *Effect of host demography and disease dynamics*

234 Fig. 1 is based on simulation study 1 (see Materials and methods) and illustrates how population
235 fluctuations and disease dynamics in the host–pathogen system affect the bias and variance of
236 estimated prevalence. These results are generated by simulating the system, in each case until it
237 reaches equilibrium, for a range of values of the death rate μ , with other parameters fixed. As the
238 death rate increases, the equilibrium-expected population size decreases and the relative size of the
239 population fluctuations increase as measured by the coefficient of variation. For a given rate of
240 disease transmission β , increasing the death rate reduces expected prevalence, and therefore
241 simulating for different values of μ generates the range of prevalence values shown. The resulting
242 relationship between demography and expected prevalence for particular disease characteristics
243 (here a fixed transmission rate, β) is illustrated in Figs 1a & 1b. These figures show increasing
244 population size and lower demographic fluctuations as expected prevalence increases (i.e. as μ
245 decreases).

246

247 Fig. 1c shows the bias in the surveillance estimate of prevalence $E[\hat{p}_{surv}] - E[p(t)]$ obtained from the
248 same set of simulations. Results shown are based on 10^6 surveillance bouts with sample size $m =$
249 10. The bias predicted by continuous sampling theory (which does not account for sample size) is
250 also shown, and in this case accurately predicts simulated bias. Fig. 1c shows the bias in surveillance
251 estimates of prevalence for four different transmission rates. For a given prevalence, populations
252 associated with higher transmission rate (β) are more variable than those with lower transmission
253 rate and therefore Fig. 1c shows that such variability increases the bias of surveillance estimates of
254 disease prevalence. Fig. 1d shows the standard deviation in surveillance estimates of prevalence
255 obtained from the same set of simulations. Comparison with the variability in prevalence estimates

256 expected under the zero fluctuation assumption reveals that fluctuations in our simulated wildlife
257 disease system reduce the precision (increase the variance) of estimates obtained by surveillance.
258 The variability of these estimates also increases with demographic fluctuations. Thus, in terms of
259 prevalence estimation, the dynamics of the host–pathogen interaction are integral in determining
260 the efficacy of surveillance. Assessment for a given system would require parameterization of
261 demography and disease dynamic, but the bias and variance in prevalence estimates shown in Fig. 1
262 are representative of a wide range of wildlife disease systems (see Materials and methods).

263

264 Additional studies shown in Appendix S2 confirm the qualitative impact of fluctuations in population
265 and prevalence seen in Fig. 1 are robust to sample and population size and mode of secondary
266 transmission. Fig. S1 shows analogous results with sample size 100, where environmental variability
267 drives fluctuations in a population around 100 times larger than considered above. Fig. S3 shows
268 results for simulation study 1 but where secondary transmission is frequency- (as opposed to
269 density) dependent. Fig. S5 and Fig. S6 show results from simulation study 1 with sample sizes 20
270 and 50 respectively.

271

272 *Surveillance design*

273 Based on simulation study 1a, Fig. 2 shows how the bias and variance of the estimate of prevalence
274 changes as the intensity of surveillance (measured by the capture rate α) increases for fixed sample
275 size (Figs 2a & 2c), and as the sample size, m , increases for a fixed capture rate (Figs 2b & 2d). For
276 low capture rates, as $\alpha \rightarrow 0$ (and based on a fixed sample size), the continuous sampling estimate
277 given in eqn 1 provides an accurate prediction for the level of prevalence estimated from
278 surveillance. As shown above, this is a biased estimate of the true prevalence $E[p(t)]$. However,
279 increasing the capture rate reduces bias, and as α increases, this bias tends to zero. In addition, for
280 large capture rates, the precision of the surveillance estimate of prevalence matches the variability
281 of the underlying wildlife disease system (see Fig. 2c). Thus for low capture rates, the bias in

282 surveillance estimates of prevalence is well described by continuous sampling theory (eqn 1).
283 However, for larger capture rates, the properties of the surveillance estimate of prevalence
284 increasingly reflect both the expected true prevalence (i.e. bias reduces), and the variability in the
285 prevalence of the underlying disease system. In contrast, increasing sample size improves precision,
286 but not bias (Fig. 2b). In comparison to the predictions from the standard binomial approach (which
287 neglects fluctuations), these have lower precision, and improve less quickly with increasing sample
288 size (see Fig. 2d). Additional simulation results (not shown) indicate that as the sample size
289 increases, the capture rate required to obtain unbiased estimates increases. However, even for
290 large sample sizes, when sampling is instantaneous (i.e. $\alpha \rightarrow \infty$), the bias is zero and the standard
291 deviation in the surveillance estimate of prevalence corresponds to that of the underlying wildlife
292 disease system as shown above.

293

294 We previously noted that capture rates for relatively intensely monitored populations (Delahay *et al.*
295 2000; Hawkins *et al.* 2006) were between 0.5 and 2.2 with those of larger-scale studies (Brugman *et al.*
296 *et al.* 2013; Pounder *et al.* 2013; McGarry *et al.* 2014) lower still. Therefore, the results of Fig. 2 suggest
297 fluctuations will lead to bias in surveillance-based estimates of prevalence for a wide range of
298 wildlife disease systems. However, the size of these effects will be dependent on the details of host
299 species demography and disease dynamics.

300

301 **The probability of detection**

302 If prevalence is assumed constant and equal to the long-term average prevalence $E[p]$ of the wildlife
303 disease system, then the probability that disease is detected in a sample of size m is given by:

304

$$305 \quad PD^{Bin} = f(E[p], m) = 1 - (1 - E[p])^m \quad (\text{eqn 2})$$

306

307 This formula, based on simple binomial arguments, and variants that also assume constant
308 prevalence, are the standard basis for sample size calculations (see e.g. Fosgate 2009). However, if
309 prevalence fluctuates PD^{Bin} is a misleading estimate of the probability of detection.

310

311 When conducting surveillance prevalence will vary between the times when each of the m samples
312 are collected, but we assume prevalence within a given surveillance bout is constant, and denote p .
313 Fig. 3a indicates that accounting only for fluctuations between surveillance bouts is an accurate
314 approximation. Therefore, the expected probability of detection for sample size m is defined as

315

$$316 \quad PD = E[f(p, m)] = E[1 - (1 - p)^m] \quad (\text{eqn 3})$$

317

318 where the expectation is over the between-bout prevalence distribution $P(p)$ which accounts only
319 for prevalence fluctuations between surveillance bouts. For a single sample $m = 1$, eqn 3 reduces
320 to a linear form, so that $PD = PD^{Bin} = E[p]$. However, if $m > 1$, then eqn 3 is non-linear, and
321 therefore $PD \neq PD^{Bin}$. Further analysis of eqn 3 e.g. suggesting $PD < PD^{Bin}$, is shown in Appendix
322 S4.

323

324 *Effect of host demography and transmission dynamics*

325 The results shown in Fig. 3 demonstrate the effect of host demography, transmission dynamics and
326 surveillance design on the probability of detection. These results are obtained from the simulations
327 described in Fig. 1, except for those in Fig. 3d where these simulations are rerun for different values
328 of the capture rate (see study 1a in Materials and methods).

329

330 Fig. 3b illustrates an analytic calculation of PD based on approximating the between-bout
331 prevalence distribution $P(p)$ as a gamma distribution (see Appendix S4). Although, not completely
332 successful, this does provide a more accurate prediction than PD^{Bin} . This approach could be used to

333 improve sample size calculations in situations where simulation is not possible, but information
334 about prevalence fluctuations is available. Moreover, the results of Fig. 3a show that such
335 approximations could be improved by assuming a more accurate representation of the prevalence
336 distribution $P(p)$. Crucially, these calculations support the conclusion that the true probability of
337 detection is less than that obtained when ignoring fluctuations i.e. less than PD^{Bin} . Fig. 3b also
338 shows the impact of biased prevalence estimation on disease detection for the case $\beta = 0.1$. Fig. 1
339 demonstrates that in this case, surveillance results in inflated estimates of prevalence $E[\hat{p}_{surv}] >$
340 $E[p(t)]$. Ignoring the effect of fluctuations would therefore lead to an estimated detection
341 probability greater than PD^{Bin} , which is based on the true average prevalence $E[p]$.

342

343 Fig. 3c shows the effect of interactions between disease dynamics and demography. As in the case of
344 prevalence estimation, conditioned on a given expected prevalence, larger contact rates β are
345 associated with greater fluctuations in the underlying wildlife disease system (i.e. greater
346 transmission rates are needed to sustain a given prevalence). Here larger fluctuations translate into
347 reduced probability of detection. In Fig. 3c, for $\beta = 1.0$, the probability of detection is only a little
348 above the line $PD = E[p]$; this corresponds to a single sample $m = 1$. Thus, in contrast to the zero
349 fluctuation approximation PD^{Bin} , fluctuations reduce the effective sample size, for the $\beta = 1.0$ case
350 from $m = 10$ to close to $m = 1$. Results not shown indicate that the reduction in effective sample
351 size increases with sample size (and see Fig. 4). Fig. 3d shows the effect of capture rate on the
352 probability of detection; counterintuitively, more intense surveillance effort actually reduces the
353 probability of detection. This is consistent with the above observations regarding β ; less intense
354 effort means that the required sample size takes longer to gather, which reduces between-bout
355 fluctuations in prevalence.

356

357

358

359 *Limits to disease detection in wildlife disease systems*

360 The nature of host demography and disease dynamics in wildlife disease systems will often be poorly
361 understood especially in cases of emerging disease. Fig. 4 is based on simulation study 2 (see
362 Materials and methods) and shows the probability of detection associated with surveillance subject
363 to demographic and disease fluctuations and the zero fluctuation approximation PD^{Bin} . This is done
364 for two different sampling levels, and across a broader range of wildlife disease systems than
365 considered above, each represented by one of the points on the graph. Depending on the level of
366 fluctuations in the system, the effective sample size can range from the actual number of samples
367 taken to $m \approx 1$. These results suggest that, when designing surveillance, ignoring the effect of
368 fluctuations could lead to studies that are underpowered in their ability to detect disease. These
369 results are consistent with those of Fig. 3 based on the SDE implementation.

370

371 **Discussion**

372 This paper represents the first systematic exploration of the impact of pathogen transmission
373 dynamics and demographic aspects of host ecology on wildlife disease surveillance efficacy. We have
374 introduced a framework within which surveillance design is characterized by the capture rate (α), in
375 addition to the standard sample size (m). In this extended framework, the performance of
376 surveillance is assessed in light of the ecology of the wildlife disease system of interest i.e. for
377 particular population and disease parameters. The framework introduced here can thus serve as a
378 template for performing power calculations that account for fluctuations in populations and disease
379 prevalence for specific hosts and pathogens.

380

381 Our results show that surveillance design (choice of m and α) can have a large impact on bias and
382 precision of prevalence estimation, and on the power to detect disease. With more unstable
383 populations and greater fluctuations in disease, bias in prevalence estimates increases, and the
384 precision of such estimates decreases. Such bias can be reduced by increasing capture rate, but for

385 fixed sample size this also reduces the ability to detect disease. However, results suggest that even
386 in the most intensive wildlife disease surveillance programs (Delahay *et al.* 2000; Hawkins *et al.*
387 2006) typical capture rates are not sufficient to eliminate bias. In contrast, increasing sample size
388 does not affect bias, but does improve statistical power in terms of both precision of prevalence
389 estimates and disease detection. However, as sample size increases, such improvements in power
390 are not as fast as would be expected if fluctuations were ignored, as they are in current surveillance
391 design and analysis (Grimes & Schulz 1996; Dohoo, Martin & Stryhn 2005).

392

393 Surveillance is a critical prerequisite for defining and controlling wildlife disease risks, and our results
394 suggest that ignoring significant temporal fluctuations in the design of wildlife disease surveillance
395 generates inadequate assessments of risk. Moreover, the ecology of many wildlife species and the
396 pathogens to which they are exposed lead to significant temporal fluctuations in both population
397 size and disease prevalence (Anderson & May 1979; Anderson 1991; Renshaw 1991; Wilson &
398 Hassell 1997; Telfer *et al.* 2002; Hawkins *et al.* 2006). The studies reported here were designed to
399 explore these effects in a wide range of scenarios representative of actual surveillance in wildlife
400 disease systems (see Materials and methods), and suggest that such issues are likely to be
401 widespread. A key aspect not accounted for in the work presented here is disease-induced mortality
402 which preliminary results (not shown) suggest is likely to accentuate the effects shown here.
403 Moreover, frequency-dependent transmission and fluctuations driven by environmental variation,
404 studied only briefly here, also reduced the efficacy of surveillance. The framework presented could
405 also be extended to account for known extrinsic sources of bias, such as imperfect disease
406 diagnostics, variation in habitat quality (Nusser *et al.* 2008; Walsh & Miller 2010) and biased capture
407 rates (Tuytens *et al.* 1999) including aspects associated with passive surveillance.

408

409 There is much current interest in quantifying risks from wildlife disease (Daszak, Cunningham &
410 Hyatt 2000; Jones *et al.* 2008), and this is stimulating debate on the need to improve wildlife disease

411 surveillance (Bengis *et al.* 2004; Butler 2006; Gortázar *et al.* 2007; Béneult, Ciliberti & Artois 2014).
412 This paper will help to further inform this debate, highlighting the need to consider the ecology of
413 wildlife disease systems when designing or analysing surveillance programs (Béneult, Ciliberti &
414 Artois 2014). This assessment emphasizes the importance of accounting for temporal
415 heterogeneities induced by population fluctuations and disease dynamics. Further research is
416 needed to assess the impacts of ecology on wildlife disease surveillance including alternative and
417 complimentary heterogeneities such as intrinsic and extrinsic forms of spatial heterogeneity, and
418 other population structures. There is a wealth of literature describing the effects of such
419 heterogeneity in ecology and epidemiology (Lloyd & May 1996; Tilman & Kareiva 1997; Keeling,
420 Wilson & Pacala 2000; Read & Keeling 2003; Keeling 2005; Vicente *et al.* 2007), and our results
421 suggest that these are likely to have important, but as yet unexplored, impacts on the efficacy of
422 wildlife disease surveillance.

423

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429 significantly improve the manuscript.

430

431 **Data accessibility**

432 Model code is available at: DRYAD entry doi:10.5061/dryad.s6518

433

434 **Supporting Information**

435 Additional Supporting Information may be found in the online version of this article :

436 **Appendix S1:** Model implementation.

- 437 **Appendix S2: Parameterisations used.**
- 438 **Appendix S3:** Additional scenarios.
- 439 **Appendix S4:** Analysis of disease detection probability.
- 440

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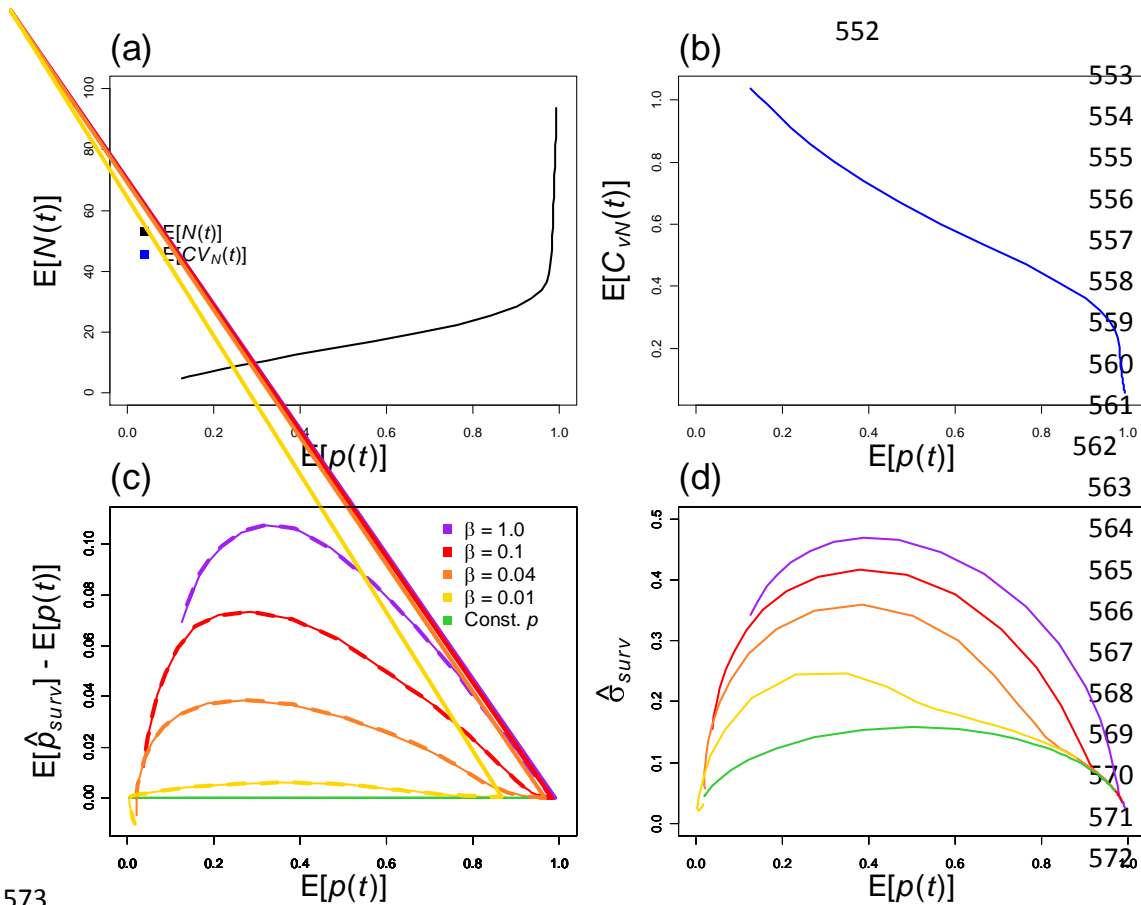
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545

546 **Table 1: Model structure.** Event, Rate and Effect on the State Space of the model. Conceptually the
 547 effect of each event affects an individual and this is reflected in the discrete nature of the
 548 corresponding changes in the state space. However, given this underlying conception of the model
 549 there are a number of different implementations which can be considered including via the Gillespie
 550 algorithm and stochastic differential equations (see text for details).

551

Event	Rate	Effect
Birth	$rN(1 - N/k)$	$S \rightarrow S + 1$
Death of Susceptible	μS	$S \rightarrow S - 1$
Death of Infected	μI	$I \rightarrow I - 1$
Susceptible Immigration	$(1 - \gamma) \nu$	$S \rightarrow S + 1$
Infected Immigration	$\gamma \nu$	$I \rightarrow I + 1$
Primary Transmission	$\beta_0 S$	$S \rightarrow S - 1$ $I \rightarrow I + 1$
Secondary Transmission	βIS	$S \rightarrow S - 1$ $I \rightarrow I + 1$
Susceptible Active Capture and Release	αS	$S \rightarrow S$
Infected Active Capture and Release	αI	$I \rightarrow I$



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575 **Figure 1: Effect of host demography and disease transmission.** Data are shown for a range of values

576 of the death rate μ which controls the stability and size of the population, and thus determines

577 disease prevalence for a given transmission rate, β . For $\beta=1$ plot (a) shows that expected population

578 size increases with expected prevalence $E[p(t)]$ (i.e. as μ decreases) whilst (b) shows that the

579 coefficient of variation of the population size decreases. For the four values of β indicated and

580 fixed sample size $m=10$, (c) shows the bias $E[\hat{p}_{surv}] - E[p(t)]$, and (d) the standard deviation in

581 surveillance estimates of prevalence, versus the expected value of true disease prevalence in the

582 system, $E[p(t)]$. Results shown are based on 10^6 surveillance bouts using the stochastic differential

583 equation implementation of the model using the set of parameter values described in Appendix S2.

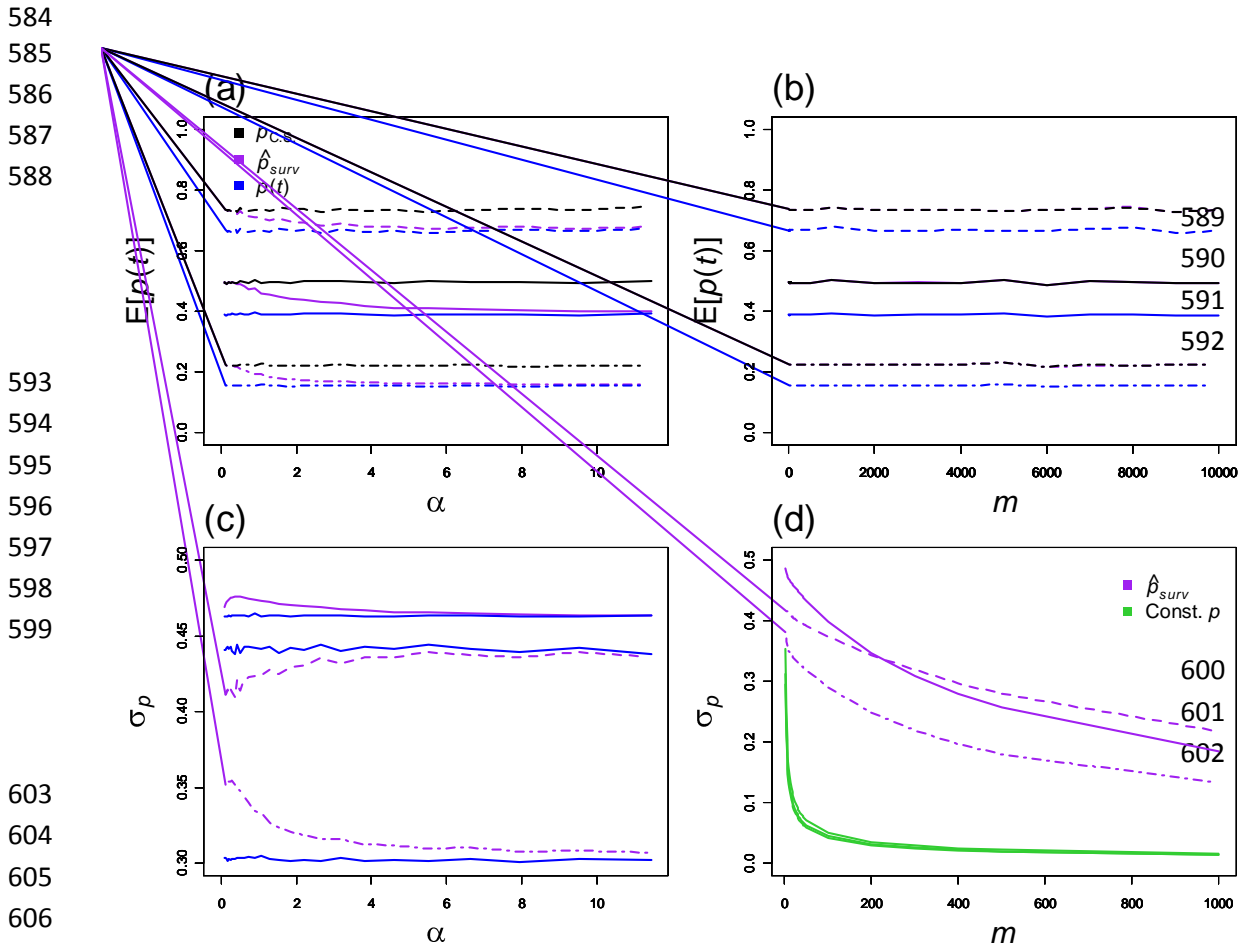
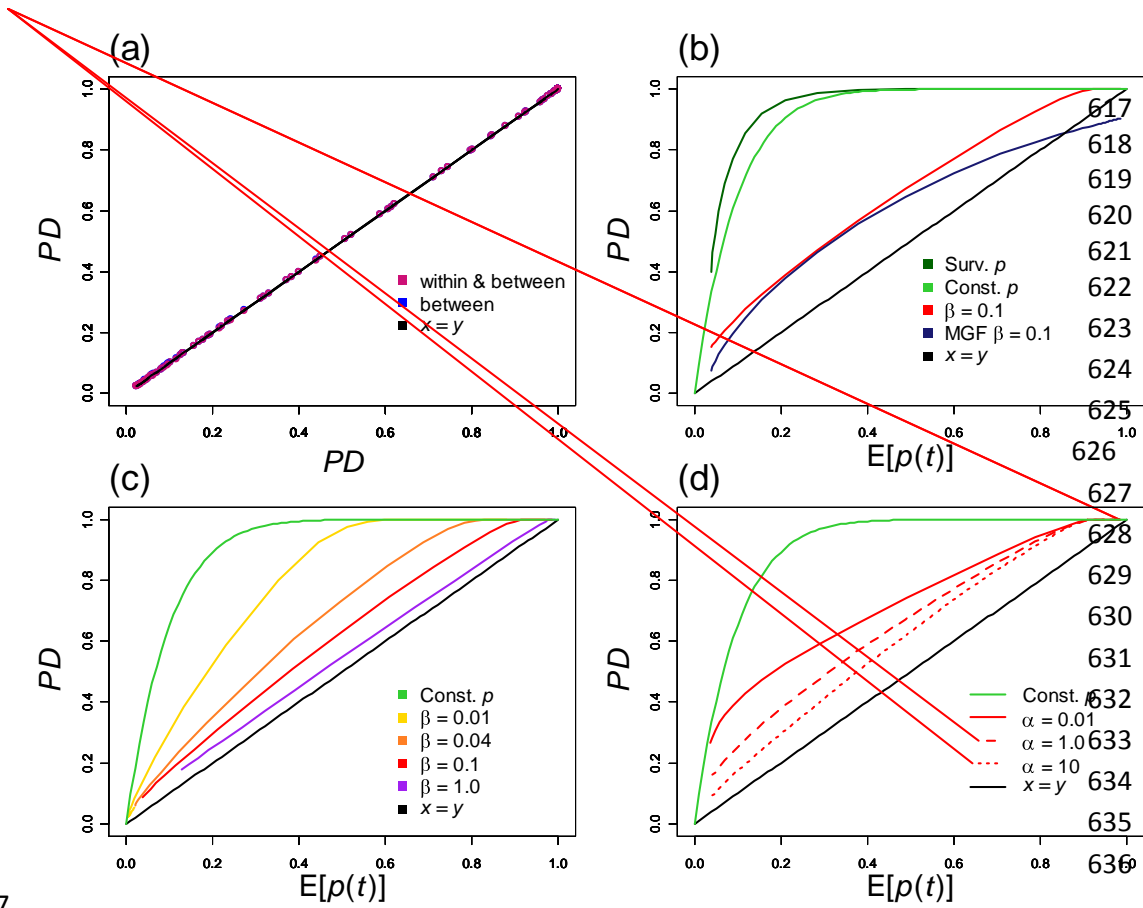


Figure 2: Effect of surveillance design. In all plots results are shown for three wildlife disease systems with (β, μ) : (1, 0.43) solid lines; (1, 0.4) dashed; and (0.1, 0.43) dot-dashed. (a) and (b) show expected values of the surveillance estimate of prevalence (purple), the true prevalence (blue) and the continuous sampling theory prediction (black). (c) and (d) show the expected standard deviation (denoted, σ_p) in both the true (blue) and the surveillance estimated (purple) prevalence. (a) and (c) are plotted against a range of values of the capture rate α , for $m = 10$, and (b) and (d) versus a range of sample sizes m for $\alpha = 0.1$. (d) also shows the constant prevalence estimate of the standard deviation based on the binomial (green). Parameter values used are as described in Table S3.



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Figure 3: Effect of host–pathogen and surveillance dynamics on probability of detection. Results

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based on simulations used for Figure 1 (for details see Table S4, Appendix S2). (d) estimated PD

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versus approximations based on modifications of eqn 3 accounting for fluctuations in prevalence (i)

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within and between bouts and (ii) between bouts only. (c) shows PD^{Bin} based on both $E[p]$ (green)

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and $E[\hat{p}_{surv}]$ (black) and (for $\beta = 0.1$) PD and the approximation (eqn 4) based on an assumed

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gamma distribution. (a) shows PD^{Bin} (green) and PD for various values of β (as shown yellow ($\beta =$

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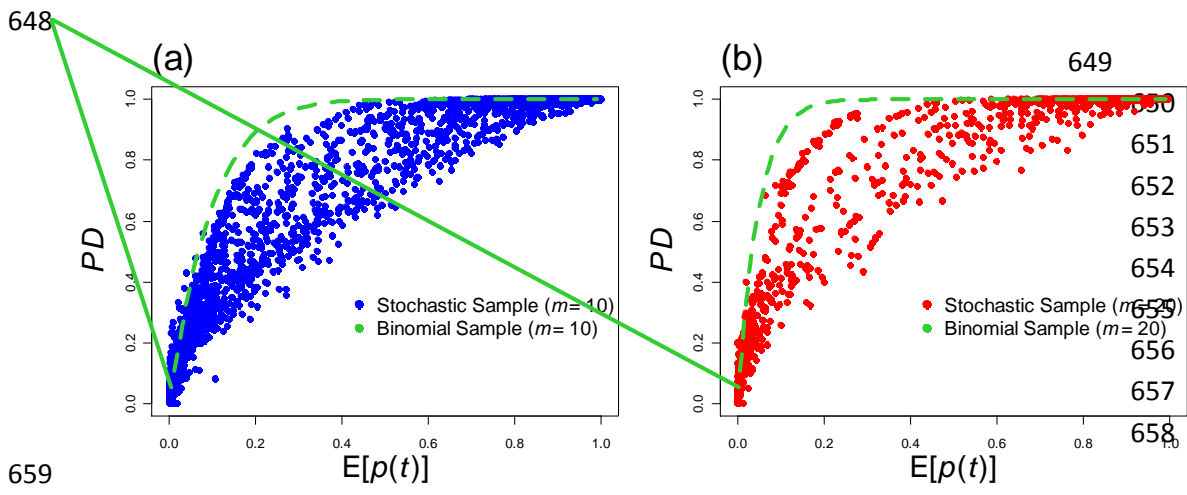
0.01); orange ($\beta = 0.04$); red ($\beta = 0.1$); purple ($\beta = 1.0$)) versus actual prevalence $E[p]$. (b) shows

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PD^{Bin} (green) and PD for $\beta = 0.1$ and the three capture rates $\alpha = 0.01, 1.0, 10$. In (a), (b) and (c)

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the black line indicates $PD = E[p(t)]$.



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Figure 4: Fluctuations reduce power to detect disease. The two panels show the probability that disease is detected (conditional on non-zero prevalence) for target sample sizes 10 and 20. Each coloured dot represents the average of 100–1000 realizations of the model implemented using the Gillespie algorithm that met the sample target for a particular combination of parameters representing a distinct host–pathogen system (for details see Table S5, Appendix S2). The green dashed line in both graphs represents PD^{Bin} the probability of detection assuming constant prevalence (see eqn 2). It can be seen that PD^{Bin} generally overestimates the power of the sample in that it predicts a larger probability of detection than is realized in the stochastic simulations.