

**Erratum: Alternative flow equation for the  
functional renormalization group  
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We correct the functional identity reported in our paper for the inverse two-point function, as obtained from the 2PI effective action. The original conclusions are otherwise unaffected. The 2PI effective action is convex with respect to the variables  $\phi'_x \equiv \phi_x$  and  $\Delta'_{xy} \equiv \hbar\Delta_{xy} + \phi_x\phi_y$ . As such, the partial functional derivatives with respect to  $\phi$  that appear in Eqs. (19) and (20) of our paper are at fixed  $\Delta'$ , not fixed  $\Delta$ . We can then show that (see Ref. [1])

$$\frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi'_x\delta\phi'_z}\frac{\delta^2W}{\delta\mathcal{J}'_z}\frac{\delta^2W}{\delta\mathcal{J}'_y} + \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi'_x\delta\Delta'_{zw}}\frac{\delta^2W}{\delta\mathcal{K}'_{zw}}\frac{\delta^2W}{\delta\mathcal{J}'_y} = -\delta_{xy}^{(d)}, \quad (1a)$$

$$\frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi'_x\delta\phi'_u}\frac{\delta^2W}{\delta\mathcal{J}'_u}\frac{\delta^2W}{\delta\mathcal{K}'_{yz}} + \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi'_x\delta\Delta'_{uv}}\frac{\delta^2W}{\delta\mathcal{K}'_{uv}}\frac{\delta^2W}{\delta\mathcal{K}'_{yz}} = 0, \quad (1b)$$

$$\frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta'_{xy}}\frac{\delta^2W}{\delta\phi'_u}\frac{\delta^2W}{\delta\mathcal{J}'_u}\frac{\delta^2W}{\delta\mathcal{J}'_z} + \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta'_{xy}}\frac{\delta^2W}{\delta\Delta'_{uv}}\frac{\delta^2W}{\delta\mathcal{K}'_{uv}}\frac{\delta^2W}{\delta\mathcal{J}'_z} = 0, \quad (1c)$$

$$\frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta'_{xy}}\frac{\delta^2W}{\delta\Delta'_{uv}}\frac{\delta^2W}{\delta\mathcal{K}'_{uv}}\frac{\delta^2W}{\delta\mathcal{K}'_{zw}} + \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta'_{xy}}\frac{\delta^2W}{\delta\phi'_u}\frac{\delta^2W}{\delta\mathcal{J}'_u}\frac{\delta^2W}{\delta\mathcal{K}'_{zw}} = -\frac{1}{2}(\delta_{xz}^{(d)}\delta_{yw}^{(d)} + \delta_{xw}^{(d)}\delta_{yz}^{(d)}), \quad (1d)$$

in  $d$  spacetime dimensions, where  $\mathcal{J}' \equiv \mathcal{J}$ ,  $\mathcal{K}' \equiv \mathcal{K}/2$ ,  $\Gamma^{2\text{PI}} \equiv \Gamma^{2\text{PI}}[\phi, \Delta^{(k)}]$  and  $W \equiv W[\mathcal{J}^{(k)}, \mathcal{K}^{(k)}]$ . Using

$$\frac{\delta}{\delta\phi'_x} = \frac{\delta}{\delta\phi_x} - \frac{2}{\hbar}\phi_y\frac{\delta}{\delta\Delta'_{yx}}, \quad (2a)$$

$$\frac{\delta}{\delta\Delta'_{xy}} = \frac{1}{\hbar}\frac{\delta}{\delta\Delta_{xy}}, \quad (2b)$$

as well as the other identities listed in the third to sixth rows of Table I, Eq. (1) can be written (see Ref. [1])

$$\left\{ \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi_x\delta\phi_z} - \mathcal{K}_{xz}^{(k)} - \frac{4\phi_w}{\hbar} \left[ \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi_{(x}\delta\Delta_{z)w}} - \frac{\phi_u}{\hbar} \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta_{wx}\delta\Delta_{uz}} \right] \right\} \Delta_{zy} - \frac{2}{\hbar} \left[ \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi_x\delta\Delta_{zw}} - \frac{2\phi_u}{\hbar} \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta_{ux}\delta\Delta_{zw}} \right] \frac{\delta^2W}{\delta\mathcal{J}_y\delta\mathcal{K}_{zw}} = \delta_{xy}^{(d)}, \quad (3a)$$

$$\left\{ \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi_x\delta\phi_z} - \mathcal{K}_{xz}^{(k)} - \frac{4\phi_w}{\hbar} \left[ \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi_{(x}\delta\Delta_{z)w}} - \frac{\phi_u}{\hbar} \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta_{wx}\delta\Delta_{uz}} \right] \right\} \frac{\delta^2W}{\delta\mathcal{J}_z\delta\mathcal{K}_{vy}} + \frac{2}{\hbar} \left[ \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi_x\delta\Delta_{zw}} - \frac{2\phi_u}{\hbar} \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta_{ux}\delta\Delta_{zw}} \right] \frac{\delta^2W}{\delta\mathcal{K}_{vy}\delta\mathcal{K}_{zw}} = 0, \quad (3b)$$

$$\left[ \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\phi_w\delta\Delta_{xy}} - \frac{2\phi_u}{\hbar} \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta_{uw}\delta\Delta_{xy}} \right] \Delta_{wz} - \frac{2}{\hbar} \frac{\delta^2\Gamma^{2\text{PI}}}{\delta\Delta_{wu}\delta\Delta_{xy}} \frac{\delta^2W}{\delta\mathcal{J}_z\delta\mathcal{K}_{wu}} = 0, \quad (3c)$$

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TABLE I. Reproduction of Table I of our paper wherein the expression for the inverse two-point function  $\Delta_{xy}^{(k),-1}$  in the 2PI case has been corrected. Note that, as in our paper, we use  $\mathcal{K}^{(k)}$  and  $\mathcal{R}^{(k)}$  interchangeably in the 2PI case.

Average 1PI	2PI
$\Gamma_{\text{av}}^{\text{1PI}}[\phi, \mathcal{R}^{(k)}] = W[\mathcal{J}^{(k)}[\phi], \mathcal{R}^{(k)}] + \mathcal{J}_x^{(k)}[\phi]\phi_x + \frac{1}{2}\mathcal{R}_{xy}^{(k)}\phi_x\phi_y$	$\Gamma^{\text{2PI}}[\phi, \Delta^{(k)}] = W[\mathcal{J}^{(k)}[\phi, \Delta^{(k)}], \mathcal{K}^{(k)}[\phi, \Delta^{(k)}]] + \mathcal{J}_x[\phi, \Delta^{(k)}]\phi_x + \frac{1}{2}\mathcal{K}_{xy}^{(k)}[\phi, \Delta^{(k)}](\phi_x\phi_y + \hbar\Delta_{xy}^{(k)})$
$\phi_x = -\frac{\delta W[\mathcal{J}^{(k)}[\phi], \mathcal{R}^{(k)}]}{\delta \mathcal{J}_x^{(k)}[\phi]}$	$\phi_x = -\frac{\delta W[\mathcal{J}^{(k)}[\phi, \Delta^{(k)}], \mathcal{K}^{(k)}[\phi, \Delta^{(k)}]]}{\delta \mathcal{J}_x^{(k)}[\phi, \Delta^{(k)']}}$
$\hbar\Delta_{xy}^{(k)} = -2\frac{\delta W[\mathcal{J}^{(k)}[\phi], \mathcal{R}^{(k)}]}{\delta \mathcal{R}_{xy}^{(k)}} - \phi_x\phi_y$ $= -\hbar\frac{\delta^2 W[\mathcal{J}^{(k)}[\phi], \mathcal{R}^{(k)}]}{\delta \mathcal{J}_x^{(k)}[\phi]\delta \mathcal{J}_y^{(k)}[\phi]}$	$\hbar\Delta_{xy}^{(k)} = -2\frac{\delta W[\mathcal{J}^{(k)}[\phi, \Delta^{(k)}], \mathcal{K}^{(k)}[\phi, \Delta^{(k)}]]}{\delta \mathcal{K}_{xy}^{(k)}[\phi, \Delta^{(k)}]} - \phi_x\phi_y$ $= -\hbar\frac{\delta^2 W[\mathcal{J}^{(k)}[\phi, \Delta^{(k)}], \mathcal{K}^{(k)}[\phi, \Delta^{(k)}]]}{\delta \mathcal{J}_x^{(k)}[\phi, \Delta^{(k)}]\delta \mathcal{J}_y^{(k)}[\phi, \Delta^{(k)']}}$
$\frac{\delta \Gamma_{\text{av}}^{\text{1PI}}[\phi, \mathcal{R}^{(k)}]}{\delta \phi_x} = \mathcal{J}_x^{(k)}[\phi] + \mathcal{R}_{xy}^{(k)}\phi_y$	$\frac{\delta \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}]}{\delta \phi_x} = \mathcal{J}_x^{(k)}[\phi, \Delta^{(k)}] + \mathcal{K}_{xy}^{(k)}[\phi, \Delta^{(k)}]\phi_y$
$\frac{\delta \Gamma_{\text{av}}^{\text{1PI}}[\phi, \mathcal{R}^{(k)}]}{\delta \mathcal{R}_{xy}^{(k)}} = -\frac{\hbar}{2}\Delta_{xy}^{(k)}$	$\frac{\delta \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}]}{\delta \Delta_{xy}^{(k)}} = +\frac{\hbar}{2}\mathcal{K}_{xy}^{(k)}[\phi, \Delta^{(k)}]$
$\Delta_{xy}^{(k),-1} = \frac{\delta^2 \Gamma^{\text{1PI}}[\phi, \mathcal{R}^{(k)}]}{\delta \phi_x \delta \phi_y}$ $= \frac{\delta^2 \Gamma_{\text{av}}^{\text{1PI}}[\phi, \mathcal{R}^{(k)}]}{\delta \phi_x \delta \phi_y} - \mathcal{R}_{xy}^{(k)}$ $= S_{xy}^{(2)}[\phi] - \mathcal{R}_{xy}^{(k)} + \mathcal{O}(\hbar)$	$\Delta_{xy}^{(k),-1} = \frac{\delta^2 \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}]}{\delta \phi_x \delta \phi_y} - \mathcal{K}_{xy}^{(k)}[\phi, \Delta^{(k)}]$ $- \frac{\delta^2 \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}]}{\delta \phi_x \delta \Delta_{zw}^{(k)}} \left( \frac{\delta^2 \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}]}{\partial \Delta_{zw}^{(k)} \delta \Delta_{uv}^{(k)}} \right)^{-1} \frac{\delta^2 \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}]}{\delta \Delta_{uv}^{(k)} \delta \phi_y}$ $= S_{xy}^{(2)}[\phi] - \mathcal{K}_{xy}^{(k)}[\phi, \Delta^{(k)}] + \mathcal{O}(\hbar)$
$\partial_k \Gamma_{\text{av}}^{\text{1PI}}[\phi, \mathcal{R}^{(k)}] = \frac{\delta \Gamma_{\text{av}}^{\text{1PI}}[\phi, \mathcal{R}^{(k)}]}{\delta \phi_x} \partial_k \phi_x + \frac{\delta \Gamma_{\text{av}}^{\text{1PI}}[\phi, \mathcal{R}^{(k)}]}{\delta \mathcal{R}_{xy}^{(k)}} \partial_k \mathcal{R}_{xy}^{(k)}$	$\partial_k \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}] = \frac{\delta \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}]}{\delta \phi_x} \partial_k \phi_x + \frac{\delta \Gamma^{\text{2PI}}[\phi, \Delta^{(k)}]}{\delta \Delta_{xy}^{(k)}} \partial_k \Delta_{xy}^{(k)}$

$$\frac{2}{\hbar} \left\{ \left[ \frac{\delta^2 \Gamma^{\text{2PI}}}{\delta \phi_u \delta \Delta_{xy}} - \frac{2\phi_v}{\hbar} \frac{\delta^2 \Gamma^{\text{2PI}}}{\delta \Delta_{vu} \delta \Delta_{xy}} \right] \frac{\delta^2 W}{\delta \mathcal{J}_u \delta \mathcal{K}_{zw}} + \frac{2}{\hbar} \frac{\delta^2 \Gamma^{\text{2PI}}}{\delta \Delta_{xy} \delta \Delta_{uv}} \frac{\delta^2 W}{\delta \mathcal{K}_{uv} \delta \mathcal{K}_{zw}} \right\} = -\frac{1}{2} (\delta_{xz}^{(d)} \delta_{yw}^{(d)} + \delta_{xw}^{(d)} \delta_{yz}^{(d)}), \quad (3d)$$

as appeared (in condensed notation) in footnote 11 of Ref. [2]. Herein, we have omitted the superscript “(k)” on  $\Delta$ ,  $\mathcal{J}$ , and  $\mathcal{K}$ , and used the shorthand notation  $A_{(x)B_{(z)w}} \equiv \frac{1}{2}(A_x B_{zw} + A_z B_{xw})$  for symmetrization in coordinates. Derivatives with respect to  $\phi$  are at fixed  $\Delta$  and vice versa; derivatives with respect to  $\mathcal{J}$  are at fixed  $\mathcal{K}$  and vice versa. Note that  $\delta^2 W / \delta \mathcal{J}_x^{(k)} / \delta \mathcal{K}_{yz}^{(k)} = -\delta \phi_x / \delta \mathcal{K}_{yz}^{(k)} \neq 0$  (even though  $\partial_k \phi = 0$ ), as was erroneously assumed in our paper, leading to the incorrect identity in Eq. (21). Additionally, while the restriction on  $\mathcal{K}_{xy} \equiv \mathcal{K}_{xy}^{(k)} = \mathcal{R}_{xy}^{(k)}$  fixes  $\Delta_{xy} \equiv \Delta_{xy}^{(k)}$  to be a functional of  $\phi$  (for clarification, see Ref. [1]), the partial functional derivative of  $\Delta$  with respect to  $\phi$  at fixed  $\Delta$  remains zero by definition, and we retract the potentially misleading notation  $\Delta_{xy}^{(k)}[\phi]$  used in our paper.

By solving Eq. (3), we can show (see Ref. [1]) that the inverse two-point function is given by

$$\Delta_{xy}^{(k),-1} = \frac{\delta^2 \Gamma^{\text{2PI}}}{\delta \phi_x \delta \phi_y} - \mathcal{K}_{xy}^{(k)} - \frac{\delta^2 \Gamma^{\text{2PI}}}{\delta \phi_x \delta \Delta_{zw}^{(k)}} \left( \frac{\delta^2 \Gamma^{\text{2PI}}}{\partial \Delta_{zw}^{(k)} \delta \Delta_{uv}^{(k)}} \right)^{-1} \frac{\delta^2 \Gamma^{\text{2PI}}}{\delta \Delta_{uv}^{(k)} \delta \phi_y}. \quad (4)$$

Equation (4) replaces Eq. (21) of our paper, and the seventh row of Table I of our paper should be corrected as shown in Table I of this erratum, where we have reproduced the complete table from our paper for clarity.

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[1] P. Millington and P.M. Saffin, Benchmarking regulator-sourced 2PI and average 1PI flow equations in zero dimensions, [arXiv:2107.12914](https://arxiv.org/abs/2107.12914).

[2] J.M. Cornwall, R. Jackiw, and E. Tomboulis, Effective action for composite operators, *Phys. Rev. D* **10**, 2428 (1974).