

1 Molecular dynamics simulations of wetting behaviors of droplets on surfaces with
2 different rough structures

3
4 Yanling Chen^a, Liang Guo^{a*}, Wanchen Sun^a, Ningning Cai^b, Yuying Yan^c

5 ^a State Key Laboratory of Automotive Simulation and Control, Jilin University, Changchun 130025, China

6 ^b School of Business and Management, Jilin University, Changchun 130012, China

7 ^c Faculty of Engineering, University of Nottingham, Nottingham NG7 2RD, UK

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9 Abstract: Aiming at the wall-wetting problem in internal combustion engines, to actively
10 control the behaviors of fuel droplets after hitting the walls, the molecular dynamics method is
11 used to investigate the effects of surface wettability and rough structure on the static and
12 dynamic wetting behaviors of the droplets. The results show that the droplet diameter has little
13 influence on the intrinsic contact angle. With the decrease of the solid-liquid interaction
14 coefficient, the interaction between the wall and the droplet is weakened and the wetting state
15 changes from the Wenzel state to the Cassie state, resulting in an increase in the apparent contact
16 angle. As the ratio of the solid-liquid contact area to the composite contact area decreases, it is
17 easier for the droplet to reach the Cassie state. Compared with the smooth surfaces, the rough
18 structures of the surfaces have an inhibitory effect on the spreading of the droplets, so the
19 apparent contact angles of the droplets on the surfaces with different rough structures are larger
20 than their intrinsic contact angles on the smooth surfaces. The secondary boss-shaped structures
21 can significantly enhance the surface oleophobicity. In addition, with the decrease of the solid-

* Corresponding author.

E-mail address: lianguo@jlu.edu.cn (L. Guo).

22 liquid interaction coefficient, the contact angle hysteresis of the droplets on different surfaces
23 reduces. Compared with the Wenzel state, the droplet in the Cassie state has a smaller contact
24 area with the surface, which makes the interaction between the wall and the droplet weaker,
25 leading to a decrease in the contact angle hysteresis.

26

27 Keywords: Droplet; Wettability; Rough structure; Static contact angle; Contact angle hysteresis;
28 Molecular dynamics

29

30 **1. Introduction**

31 Advanced combustion modes such as homogeneous charge compression ignition (HCCI),
32 premixed charge compression ignition (PCCI), reaction controlled compression ignition (RCCI) and
33 low temperature combustion (LTC) play an important role in improving combustion efficiency and
34 reducing pollutant emissions of internal combustion engines (Gordon et al., 2020; Sankaralingam
35 et al., 2022; Agarwal et al., 2017; Krishnamoorthi et al., 2019). However, premixed compression
36 ignition modes such as HCCI and PCCI often use early injection, multiple injections and high-
37 pressure injection to improve the atomization quality (Mathivanan et al., 2016; Liang et al., 2019;
38 Lee et al., 2015). Due to the low temperature and gas density in the cylinder at the early injection
39 timing, the wall-wetting phenomenon is inevitable (Bendu and Murugan, 2014). Especially when
40 the engine is cold started, the wall-wetting problem is more obvious. Spray-wall impingement can
41 cause an increase in soot particles and unburned hydrocarbons. Therefore, it is necessary to deeply
42 study the effects of wall properties on the development processes of wall-impinging fuels to achieve
43 active control of the wall-wetting problem.

44 As the applications of the technologies of drag reduction (Ou et al., 2004; Taghvaei et al., 2017),
 45 oil/water separation (Saleh and Baig, 2019), self-cleaning (Bhushan et al., 2009; Li et al., 2018),
 46 anti-icing (Farhadi et al., 2011; Qi et al., 2020) and anti-corrosion (Qian et al., 2017; Xin et al.,
 47 2021), the interest in wettability studies has been rising. The wettability is related to the
 48 morphologies and chemical compositions of the solid surfaces (Yong et al., 2015; Kim et al., 2018;
 49 Song et al., 2015). The surfaces with specific wettability can be prepared with different methods,
 50 such as mechanical treatment, chemical etching, plasma spraying and particle deposition, etc.
 51 Numerous experimental studies have been conducted on the influence of the wettability and textures
 52 of the solid surfaces on the static behaviors, dynamic behaviors (Yoshimitsu et al., 2002; Martines
 53 et al., 2005; Yao et al., 2020) and evaporation characteristics (Lee et al., 2012; Yu et al., 2015; Guo
 54 et al., 2022; Chen et al., 2023) of the droplets.

55 In addition, different wetting models have been proposed. The equilibrium contact angle (CA)
 56 of the droplet on a flat homogeneous surface, θ_Y , is obtained by Young equation (Young, 1805).
 57 The expression of Young equation is as follows:

$$58 \quad \cos\theta_Y = \frac{\gamma_{sv} - \gamma_{sl}}{\gamma_{lv}} \quad (1)$$

59 Where, γ_{sv} , γ_{sl} , and γ_{lv} are interfacial tensions per unit length of the solid-vapor, solid-liquid
 60 and liquid-vapor interfaces, respectively.

61 Considering that the actual surface has the rough structures, the CA of the droplet on a rough
 62 surface is called the apparent CA. The Young equation has been modified by Wenzel (1936), Cassie
 63 and Baxter (1944), respectively. The Wenzel equation is expressed as follows:

$$64 \quad \cos\theta_W = r_s \frac{\gamma_{sv} - \gamma_{sl}}{\gamma_{lv}} = r_s \cos\theta_Y \quad (2)$$

65

66 Where, r_s is the roughness factor. The value of r_s is the ratio of the real area of a solid surface
67 in contact with the droplet to its projection onto the horizontal plane.

68 In the Cassie-Baxter theory, the droplet does not wet the inside of the grooves on the rough
69 surface and the grooves are filled with air. The lower part of the droplet is in contact with both a
70 solid surface and air. As a result, a composite contact surface consisting of a solid-liquid contact
71 surface and a liquid-vapor contact surface is formed. The Cassie-Baxter equation is expressed as
72 follows:

$$73 \quad \cos\theta_C = f_1 \frac{\gamma_{sv} - \gamma_{sl}}{\gamma_{lv}} - f_2 = f_1 \cos\theta_Y - f_2 \quad (3)$$

74 Where, f_1 is the ratio of the solid-liquid contact area to the composite contact area. f_2 is the
75 ratio of the liquid-vapor contact area to the composite contact area. Also, $f_1 + f_2 = 1$.

76 Due to the limitation of experimental conditions, it is difficult to measure some microscopic
77 processes with experimental methods. Numerical simulation methods are widely used. The
78 thicknesses of the liquid-solid interface and the liquid-vapor interface are usually about a few
79 nanometers. The heat and mass transfer between the solid, liquid and vapor phases are carried out
80 by atoms and molecules as individuals. Therefore, it is particularly important to use a discrete
81 method to conduct related studies, and the molecular dynamics (MD) method is a good choice. In
82 the research field of wettability, MD simulation makes it possible to investigate the wetting
83 behaviors and microscopic mechanisms of the droplets on different surfaces. Guo and Fang (2005)
84 studied the CAs of argon droplets on a solid substrate. They found the influence of the droplet size
85 on the CA was related to the interaction between the liquid molecules and the solid substrate. The
86 CA reduced with the decreasing droplet size for larger interaction between the liquid molecules and
87 the solid substrate, and vice versa. Burt et al. (2016) simulated the wetting behaviors of ionic-liquid

88 droplets on graphene sheets. They found that the droplet size had no significant effect on the CA at
89 low graphene interaction potential. When increasing the surface interaction potential toward actual
90 graphene, the spreading rate and extent of the droplets were influenced by the droplet size. Many
91 scholars have carried out simulation studies on water molecules and compared the models of water
92 such as TIP3P, TIP4P, TIP5P, SPC and SPC/E (Zielkiewicz, 2005). Chen et al. (2014) studied the
93 wetting behaviors of water droplets on flat and pillar polytetrafluorethylene surfaces. They found
94 that the cutoff of the Lennard-Jones potential had a large effect on the CA.

95 There are many MD simulation studies on the static and dynamic wetting behaviors of water
96 droplets on the surfaces with different microstructures. Ambrosia et al. (2013) pointed out that the
97 wetting states of water droplets on the surfaces with pillars included the Wenzel state and the Cassie
98 state. Niu and Tang (2014) also conducted simulation studies on the behaviors of water droplets on
99 the surfaces with pillar-type nanostructures and found that the wetting state of the droplet depended
100 on the pillar height and the pillar surface fraction. Chen et al. (2014) studied the wetting behaviors
101 of water droplets on the nanostructured pillar surfaces. They proposed the equilibrium states could
102 be classified into four categories: the Wenzel, the metastable Cassie, the globally steady Cassie and
103 the Cross state. In addition, the dual structures (Kwon et al., 2020) can make the surface more
104 hydrophobic compared to the single structures. Zhang et al. (2016) analyzed the wettability of water
105 droplets on the gold surfaces corrugated with spherical cavities and found that the CA varied from
106 a hydrophilic (69°) to a hydrophobic value ($>109^\circ$) with increasing depth of the cavities. Hong et
107 al. (2009) simulated the static and dynamic CAs of water droplets on the solid surfaces using the
108 method of MD. They found that as the characteristic energy of the solid surface increased, the static
109 CA decreased and the CAH increased. Jeong et al. (2012) found that the CAH of water droplets on

110 the surfaces with pillar-type nanostructures depended on the dynamic behaviors of the droplet under
111 an external force. Similarly, Koishi et al. (2011) measured the CAH of water droplets on
112 nanopillared surfaces. The results showed that the CAH for the droplet in the Wenzel state was larger
113 than that in the Cassie state. In addition to exploring the effects of the droplet size, solid-liquid
114 interaction coefficient and rough structure on the wetting states and CAs, many scholars have
115 proposed some new methods for determining the CA suitable for MD simulations to improve the
116 reliability and accuracy of the CA calculation results (Khalkhali et al., 2017; Ravipati et al., 2018;
117 Abramov and Iglauer, 2019).

118 A lot of studies on the wetting processes of the droplets on different surfaces have been
119 conducted. However, there are few studies on the wetting behaviors of alkane nanodroplets. Aiming
120 at the wall-wetting problem in internal combustion engines, to actively control the development
121 behaviors of the wall-impinging droplets, the molecular dynamics method is used to simulate the
122 static and dynamic wetting behaviors of nano-scale droplets on the surfaces with different rough
123 structures under the conditions of different solid-liquid interaction coefficients. The influence of the
124 solid-liquid interaction coefficient and rough structure on the apparent CA and CAH of the alkane
125 droplets are investigated. This study provides a theoretical foundation for guiding the design, choice,
126 optimization and fabrication of combustion chamber surfaces in internal combustion engines to
127 satisfy practical operating conditions.

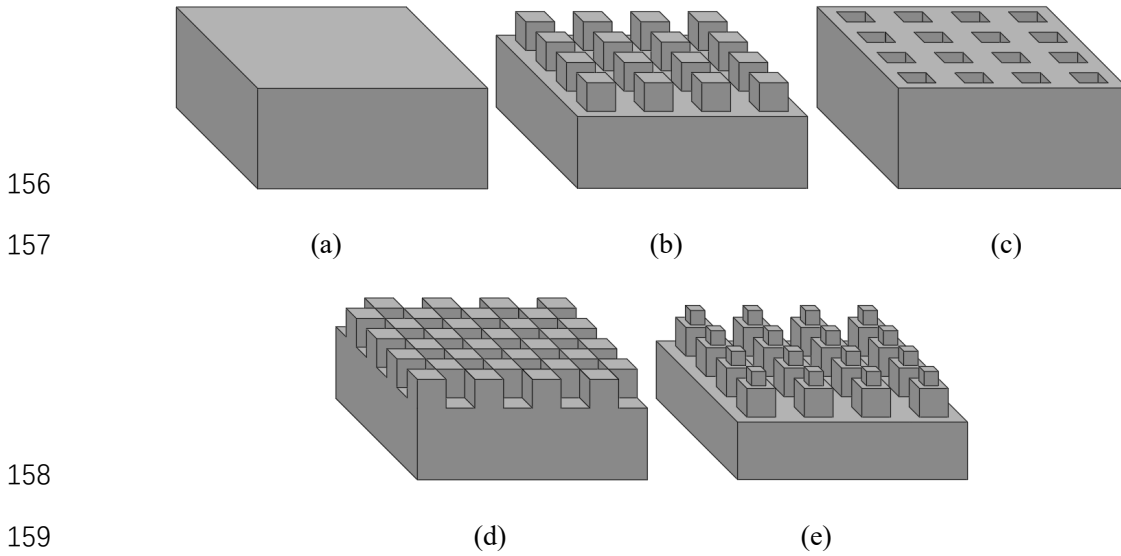
128 **2. Simulation method**

129 **2.1. The establishment of the simulation system**

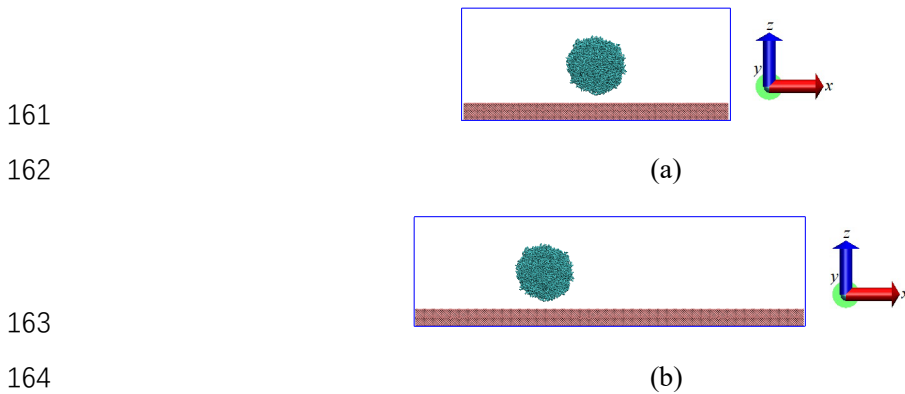
130 Molecular dynamics simulation is performed using the LAMMPS (Large-scale
131 Atomic/Molecular Massively Parallel Simulator) software (Plimpton, 1995). For the study of the

132 effects of the droplet size and cutoff radius on the static wetting behaviors of the droplets on the
133 smooth surfaces, a simulation system with the three dimensions of $480 \text{ \AA} \times 480 \text{ \AA} \times 200 \text{ \AA}$ in the x ,
134 y and z directions is built. For the study of the static and dynamic wetting characteristics of the
135 droplets on the surfaces with different rough structures, considering that a lateral force needs to be
136 applied to the droplets, the three dimensions of the simulation system are determined to be $720 \text{ \AA} \times$
137 $480 \text{ \AA} \times 200 \text{ \AA}$. A spherical region for the addition of droplet molecules is defined in the simulation
138 system. The droplet is composed of n-hexadecane molecules in a body-centered cubic lattice
139 structure. The n-hexadecane molecules are initially distributed with a density close to the liquid
140 density (0.773 g/cm^3). To eliminate the influence of the initial configuration of the droplets, the
141 process of the energy minimization is performed. The initial velocity of n-hexadecane molecules is
142 determined by a random number generator. To avoid the lateral movement of the droplet due to
143 accidental factors, the x -coordinate, y -coordinate and z -coordinate of the mass centroid (COM) of
144 the droplet are fixed. The solid wall consists of aluminum atoms in a face-centered cubic lattice
145 structure with a lattice constant is 4.0495 \AA . The initial distance between the bottom of the droplet
146 and the top of the wall is 20 \AA . In this study, five kinds of surfaces are studied, which are smooth
147 surface (SS), boss-shaped surface, pit-shaped surface (PS), grid-shaped surface (GS) and secondary
148 boss-shaped surface (DS). Schematic diagrams of different surfaces are shown in Fig. 1. To describe
149 the morphologies of the rough surfaces, the lattice length of the aluminum atom is defined as L . For
150 the BS (PS), the length, width and height of each boss (pit) are $2L$, and the distance between two
151 adjacent bosses (pits) is $2L$. For the GS, the length, width and height of each pit are $2L$. For the DS,
152 the length, width and height of the bottom boss are $2L$, and the distance between two adjacent
153 bottom bosses is $2L$. The length, width and height of the upper boss are L . Taking a droplet on a

154 smooth surface as an example, the initial configurations of the simulation systems with different
 155 sizes are shown in Fig. 2.



160 Fig. 1. Schematic diagrams of (a) SS, (b) BS, (c) PS, (d) GS and (e) DS.

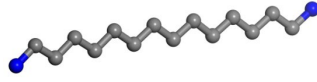


165 Fig. 2. Initial configurations of the simulation systems with the three dimensions of (a) $480 \text{ \AA} \times$
 166 $480 \text{ \AA} \times 200 \text{ \AA}$ and (b) $720 \text{ \AA} \times 480 \text{ \AA} \times 200 \text{ \AA}$.

167 2.2. Selection of potential energy model

168 Because the n-hexadecane molecule contains many atoms, to simplify the calculations, a joint
 169 atomic model is used (Bai et al., 2017), as shown in Fig. 3. Methyl (CH_3) and methylene (CH_2) are
 170 regarded as independent atoms, and their relative atomic masses are 15.0345 g/mol and 14.0266
 171 g/mol , respectively. The simplified force field obtained is called the joint atomic force field. The

172 chain-like property of n-hexadecane molecules will not be destroyed with the joint atomic force
 173 field.



174
 175 Fig. 3. Joint atomic model of n-hexadecane molecule.

176 The potential energy of n-hexadecane molecular system includes bonded and non-bonded
 177 potentials. The bonded potential includes bond length stretching potential, bond angle bending
 178 potential and dihedral angle twisting potential. The non-bonded potential is described by the 12-6
 179 Lennard-Jones (L-J) potential. The potential energy function of n-hexadecane molecules is
 180 expressed as follows:

$$\begin{aligned}
 U^{\text{tot}} = U^{\text{NB}} + U^{\text{B}} = & \sum_{i=1}^N \sum_{j>1}^N 4\varepsilon_{ij} \left[\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - \left(\frac{\sigma_{ij}}{r_{ij}} \right)^6 \right] + \sum_{\text{bonds}} \frac{1}{2} k_r (r - r_0)^2 + \sum_{\text{angles}} \frac{1}{2} k_\theta (\theta - \theta_0)^2 + \\
 & \sum_{\text{dihedrals}} \frac{1}{2} [k_1 (1 + \cos\alpha) + k_2 (1 - \cos 2\alpha) + k_3 (1 + \cos 3\alpha) + k_4 (1 - \cos 4\alpha)] \quad (1)
 \end{aligned}$$

182 Where, U^{tot} is the total potential, U^{NB} is the non-bonded potential and U^{B} is the bonded
 183 potential. N is the number of n-hexadecane molecules. ε_{ij} and σ_{ij} are the energy parameter and
 184 size parameter of the L-J potential between two non-bonded virtual atoms in molecules i and j . r_{ij}
 185 is the distance between two non-bonded virtual atoms in molecules i and j . k_r is the bond
 186 constant. r and r_0 are the actual bond length and equilibrium bond length between two covalently
 187 bonded virtual atoms. k_θ is the angle constant. θ and θ_0 are the actual angle and equilibrium
 188 angle between three covalently bonded virtual atoms. k_1 , k_2 , k_3 and k_4 are the dihedral angle
 189 constants. α is the dihedral angle.

190 The interaction parameters of bond length, bond angle and dihedral angle are shown in Tables
 191 1, 2 and 3 (Bai et al., 2017).

192

Table 1. Interaction parameters of bond length.

Bond length	$k_r/\text{kJ}\cdot\text{mol}^{-1}\cdot\text{\AA}^{-2}$	$r_0/\text{\AA}$
CH ₃ -CH ₂	1090.98	1.6100
CH ₂ -CH ₂	813.43	1.6100

193

Table 2. Interaction parameters of bond angle.

Bond angle	$\theta_0/^\circ$	$k_\theta/\text{kJ}\cdot\text{mol}^{-1}\cdot\text{rad}^{-2}$
CH ₃ -CH ₂ -CH ₂	104.8	113.6
CH ₂ -CH ₂ -CH ₂	102.2	93.6

194

Table 3. Interaction parameters of dihedral angle.

Dihedral angle	$k_1/\text{kJ}\cdot\text{mol}^{-1}$	$k_2/\text{kJ}\cdot\text{mol}^{-1}$	$k_3/\text{kJ}\cdot\text{mol}^{-1}$	$k_4/\text{kJ}\cdot\text{mol}^{-1}$
CH ₃ -CH ₂ -CH ₂ -CH ₂	-3.4	1.25	0.3	0
CH ₂ -CH ₂ -CH ₂ -CH ₂	-3.4	1.25	0.3	0

195

The energy and size parameters of the L-J potential between two non-bonded virtual atoms in

196

the droplet molecules are shown in Table 4 (Bai et al., 2017).

197

Table 4. Energy and size parameters of L-J potential in the droplet molecules.

Atom group	$\varepsilon_i/\text{kJ}\cdot\text{mol}^{-1}$	$\sigma_i/\text{\AA}$
CH ₃	0.7315	3.9050
CH ₂	0.4932	3.9050

198

The potential between the wall atoms is described by the EAM potential function. The energy

199

and size parameters of the L-J potential between virtual atoms and wall atoms can be calculated by

200

using Lorentz–Bertholet mixing rule:

201

$$\varepsilon_{sl} = \sqrt{\varepsilon_{ss}\varepsilon_{ll}} \quad (2)$$

202
$$\sigma_{sl} = \frac{\sigma_{ss} + \sigma_{ll}}{2} \quad (3)$$

203 Where, ε_{sl} , ε_{ss} and ε_{ll} are the energy parameters of the L-J potential between the droplet
 204 atoms and the wall atoms, between the wall atoms and between the droplet atoms. σ_{sl} , σ_{ss} and σ_{ll}
 205 are the size parameters of the L-J potential between the droplet atoms and the wall atoms, between
 206 the wall atoms and between the droplet atoms. The energy and size parameters of the L-J potential
 207 between different virtual atoms in the droplets are also obtained by the mixing rule. The interaction
 208 strength between the wall and the droplet can be changed by adjusting the energy parameters
 209 between the wall atoms and the droplet atoms. Therefore, the wettability can be changed by
 210 adjusting the interaction strength between the wall and the droplet. The energy parameter used to
 211 adjust the energy relationship between the wall atoms and the droplet atoms is called solid-liquid
 212 interaction coefficient. Four typical solid-liquid interaction coefficients are selected for subsequent
 213 calculations, which are represented by ε_1 , ε_2 , ε_3 and ε_4 in turn. The values of the four solid-liquid
 214 interaction coefficients can be found in Table 5.

215 Table 5. Solid-liquid interaction coefficients.

	$\varepsilon_1/\text{kJ}\cdot\text{mol}^{-1}$	$\varepsilon_2/\text{kJ}\cdot\text{mol}^{-1}$	$\varepsilon_3/\text{kJ}\cdot\text{mol}^{-1}$	$\varepsilon_4/\text{kJ}\cdot\text{mol}^{-1}$
$\varepsilon_{\text{CH}_3\text{-Al}}$	0.5908	0.4178	0.2954	0.2089
$\varepsilon_{\text{CH}_2\text{-Al}}$	0.4851	0.3431	0.2426	0.1716

216 **2.3. Simulation details**

217 In the simulations, periodic boundary condition is used in the x and y directions, while fixed
 218 boundary condition is applied in the z direction. Besides, a reflecting wall is adopted. For the
 219 simulations of the static wetting behaviors of the droplets on different surfaces, the x -coordinates
 220 and y -coordinates of the mass centroids of the droplets are controlled to be 0 to avoid the lateral

221 movements of the droplets. The time step of the simulations is set to 1 fs and the duration is 2 ns. A
222 run of the first 1 ns is used to ensure system equilibrium, and the simulation results from 1 ns to 2
223 ns are used for statistical analysis.

224 For the study relating to the effects of the rough structure on the dynamic wetting processes
225 of the droplets, when the simulation mentioned above runs for 2 ns, an external force in the positive
226 x direction is applied to the droplet in an equilibrium state. Under the same solid-liquid interaction
227 coefficient, to ensure that all droplet atoms have the same acceleration, a constant external force is
228 proportional to the mass of atoms CH_3 and CH_2 . As the solid-liquid interaction coefficient decreases,
229 the external force applied to a droplet reduces. The time step is set to 1 fs and the duration is 0.5 ns.

230 The NVT ensemble is used during the simulations with a constant number of atoms (N), fixed
231 volume (V) and fixed temperature (T). The Nosé-Hoover thermostat is used to control the droplet
232 temperature near 300.15 K. The velocity-Verlet algorithm is used to solve the motions of all
233 particles.

234 **2.4. Data processing**

235 The static CAs of the droplets on different surfaces can be obtained by processing the two-
236 dimensional density profiles obtained from the simulations. The method for obtaining the density
237 profiles is as follows. During the simulations, the simulation system is divided into some concentric
238 rings. The axes of the rings are along the z -axis direction, and the thickness of each ring in the x - y
239 plane is 2 Å. Subsequently, the rings are cut at equal intervals along the z -axis from 0 Å to 200 Å.
240 Each bin has a height of 2 Å in the z -axis direction. The density in each bin is calculated to obtain a
241 two-dimensional density profile.

242 The method of obtaining the dynamic CAs is different from the method of obtaining the static

243 CAs. The specific method for obtaining dynamic CAs is as follows. The three-dimensional
 244 hexahedron computational domain is divided into some cubic bins with a side length of 4 Å. The
 245 distributions of the droplet atoms are determined according to the coordinates of each droplet atom
 246 obtained from the simulations. To make the density field smooth, combined with a smoothing
 247 procedure for two-dimensional density field (Bonometti and Magnaudet, 2007), the weighted
 248 average density ($\tilde{\rho}$) of a given grid point (m, n, p) and its surrounding grid points in the 3D
 249 computational domain is calculated as the density (ρ) of a given grid point by the following equation.

$$250 \quad \tilde{\rho}_{m,n,p} = \frac{3}{4}\bar{\rho}_{m,n,p} + \frac{1}{24}(\bar{\rho}_{m+1,n,p} + \bar{\rho}_{m-1,n,p} + \bar{\rho}_{m,n+1,p} + \bar{\rho}_{m,n-1,p} + \bar{\rho}_{m,n,p+1} + \bar{\rho}_{m,n,p-1}) \quad (4)$$

251 Where, $\bar{\rho}$ is the average value of the density of the grid point.

252 Subsequently, a two-dimensional density profile in the x - z plane is obtained.

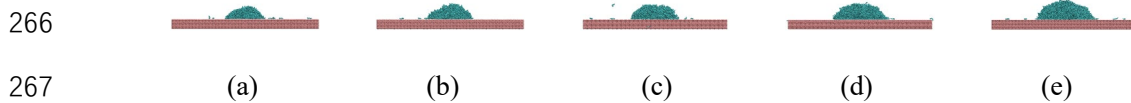
253 The CAs of the droplets on different surfaces are calculated using the isodensity circle fitting
 254 method. The 0.3865 g/cm³ isodensity line is selected as the contour line of the droplet. For fitting
 255 the contour line of the droplet, only points with a distance greater than 4 Å against the solid surface
 256 are considered to avoid density fluctuation at the wall-droplet interface.

257 **3. Results and Discussion**

258 **3.1. Analysis of the effects of the diameter on the static wetting behaviors of the droplets**

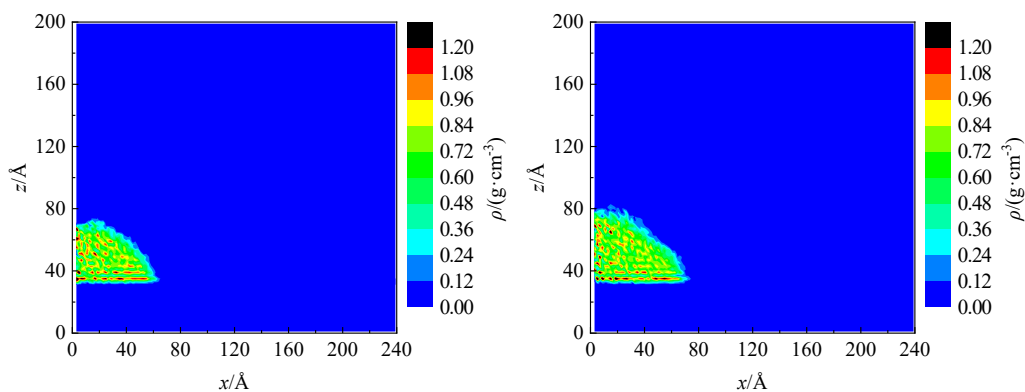
259 The wetting processes of the droplets on the walls are scale-dependent. To explore the influence
 260 of the droplet size on the simulation results, at a solid-liquid interaction coefficient of ε_2 , the static
 261 wetting behaviors of the droplets with diameters of 80 Å, 90 Å, 100 Å, 110 Å and 120 Å on the
 262 smooth surfaces are simulated. The numbers of n-hexadecane molecules contained in the above
 263 droplets are 544, 789, 1074, 1423 and 1864, respectively. The cutoff radius is 10 Å. Under a solid-
 264 liquid interaction coefficient of ε_2 , the snapshots and density profiles of the droplets with different

265 diameters on the smooth surfaces at 2 ns are shown in Fig. 4 and Fig. 5, respectively.



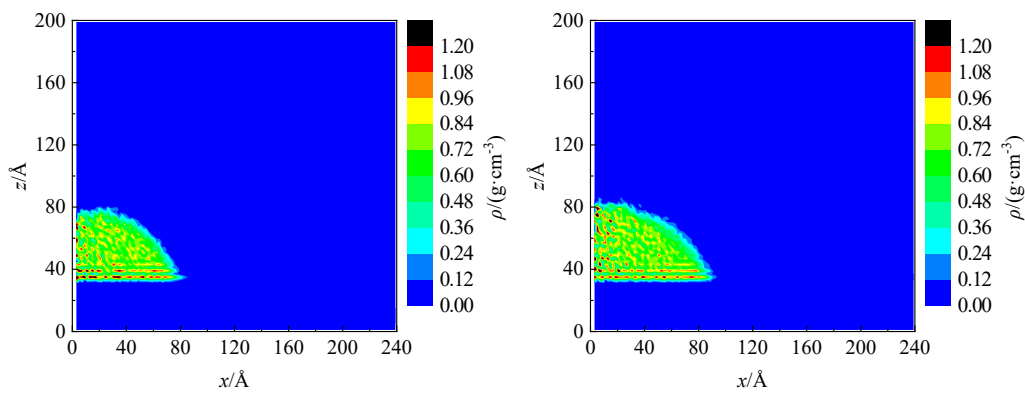
268 Fig. 4. Snapshots of the droplets with diameters of (a) 80 Å, (b) 90 Å, (c) 100 Å, (d) 110 Å and (e)

269 120 Å.



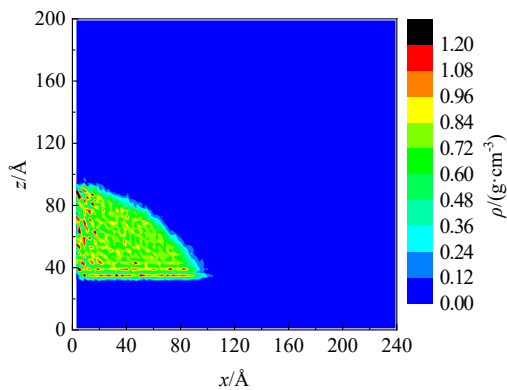
271 (a)

(b)



273 (c)

(d)



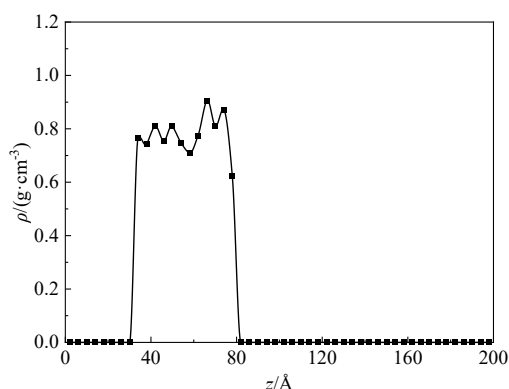
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(e)

276 Fig. 5. Density profiles of the droplets with diameters of (a) 80 Å, (b) 90 Å, (c) 100 Å, (d) 110 Å
277 and (e) 120 Å.

278 It can be seen from Fig. 4 and Fig. 5 that when the solid-liquid interaction coefficient is ϵ_2 , the
279 shapes of the droplets with different diameters on the smooth surfaces are similar and are all coronal.
280 This indicates that the droplets with different diameters have small difference in shape when they
281 reach the equilibrium states, that is, the influence of the droplet diameter on the shape of the
282 equilibrium droplet is small.

283 At a solid-liquid interaction coefficient of ϵ_2 , the density profile along the centerline of n-
284 hexadecane droplet with a diameter of 100 Å on the SS at 2 ns is described in Fig. 6.



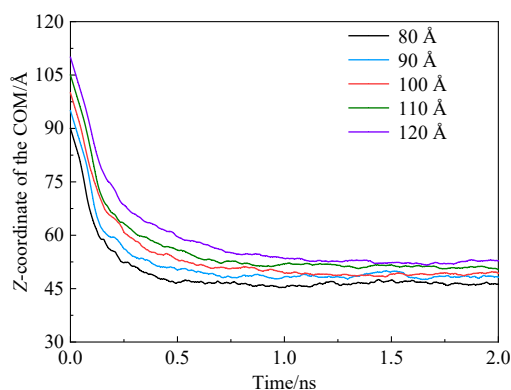
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286 Fig. 6. Density profile of the droplet with a diameter of 100 Å.

287 As shown in Fig. 6, near the solid surface, the density fluctuation is large because of the
288 presence of the wall. The density fluctuation inside the droplet is small, and the average value of the
289 density of the droplet is calculated to be $0.7772 g/cm^3$, which is very close to the density of n-
290 hexadecane at room temperature. The above results verify the accuracy of the simulation processes.
291 As the distance from the solid surface increases, the density decreases sharply and a liquid-vapor
292 interface is formed. When the distance from the solid surface further increases, a vapor phase region

293 is formed.

294 For the wetting processes of the droplets on the smooth surfaces, the variations of the z -
295 coordinates of the mass centroids of the droplets with different diameters over time are compared
296 as shown in Fig. 7.

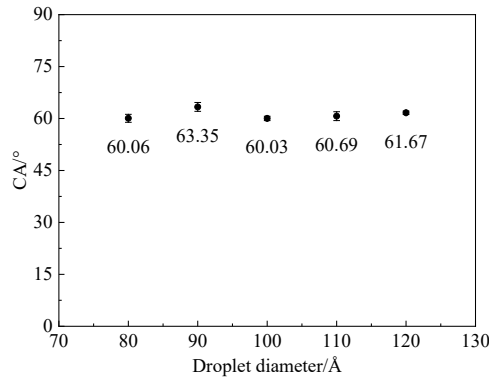


297

298 Fig. 7. Effects of the droplet diameter on the z -coordinates of the mass centroids of the droplets.

299 It can be seen from Fig. 7 that the z -coordinates of the mass centroids decrease rapidly when
300 the droplets with different diameters wet the smooth surfaces. When the droplet reaches an
301 equilibrium state, the changes in the z -coordinate of the mass centroid turn small. As the droplet
302 diameter increases, the time it takes for the droplet to reach an equilibrium state is longer. After the
303 droplet reaches an equilibrium state, it shows that the z -coordinate of the mass centroid slightly
304 increases with increasing droplet diameter at the same time.

305 After calculations, the intrinsic CAs of the droplets with different diameters on the smooth
306 surfaces are shown in Fig. 8.



307

308

Fig. 8. Effects of the droplet diameter on the intrinsic CAs.

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It can be seen from Fig. 8 that under the same solid-liquid interaction coefficient, the intrinsic

310

CA of the droplet on the SS increases by 3.29° when the droplet diameter increases from 80 Å to 90

311

Å. When the droplet diameter further increases to 100 Å, 110 Å and 120 Å, the difference in the

312

intrinsic CA of the droplet on the SS is less than 3° . It can be concluded that when the droplet

313

diameter increases to 100 Å and above, the influence of the droplet diameter on the intrinsic CA is

314

small. Therefore, considering the accuracy and efficiency of the calculations, in the follow-up

315

simulations, the diameter of the droplet is selected to be 100 Å.

316

3.2. Analysis of the effects of the cutoff radius on the static wetting behaviors of the droplets

317

The cutoff radius of the Lennard-Jones potential affects the simulation results. To determine a

318

reasonable cutoff radius, it is necessary to study the effects of the cutoff radius on the static wetting

319

behaviors of the droplets. When the solid-liquid interaction coefficient is ϵ_2 , under the conditions

320

of the cutoff radii of 8 Å, 10 Å, 12 Å, 14 Å and 16 Å, the processes of n-hexadecane droplets with

321

a diameter of 10 nm wetting a smooth surface are simulated. At a solid-liquid interaction coefficient

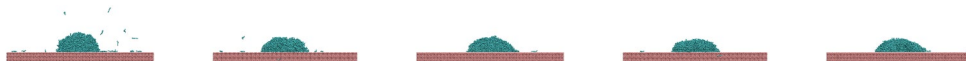
322

of ϵ_2 , under different cutoff radii, the snapshots and density profiles of the droplets on the smooth

323

surfaces at 2 ns are shown in Fig. 9 and Fig. 10, respectively.

324



325

(a)

(b)

(c)

(d)

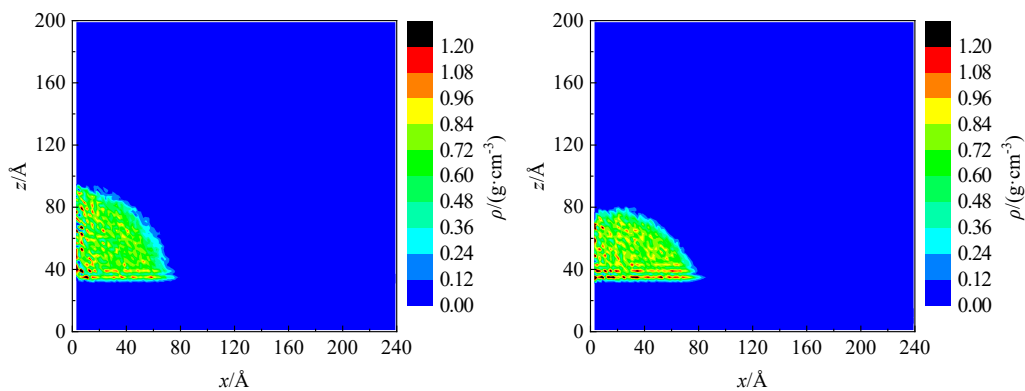
(e)

326

Fig. 9. Snapshots of the droplets on the smooth surfaces under cutoff radii of (a) 8 Å, (b) 10 Å, (c)

327

12 Å, (d) 14 Å and (e) 16 Å.

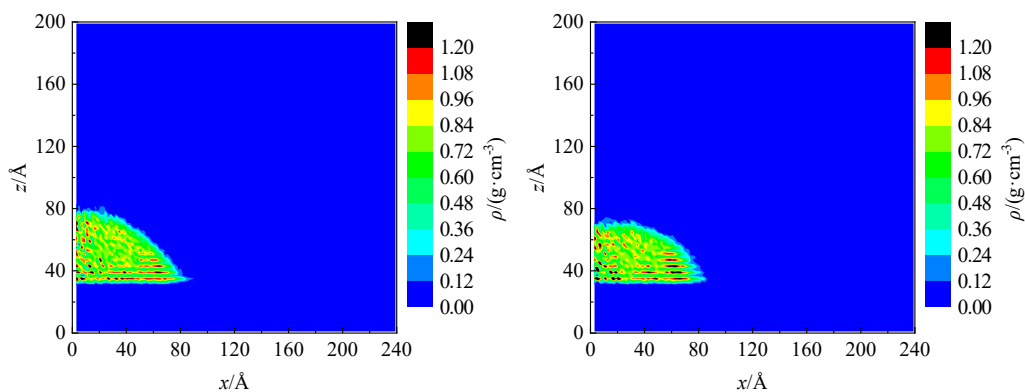


328

329

(a)

(b)

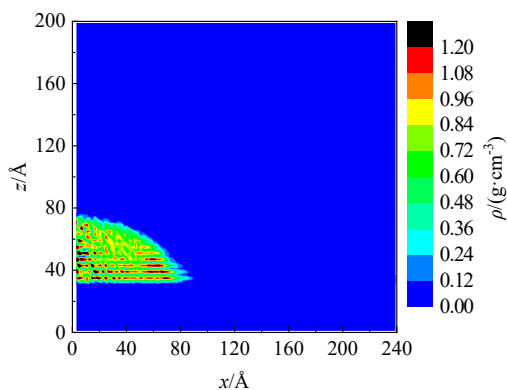


330

331

(c)

(d)



332

333

(e)

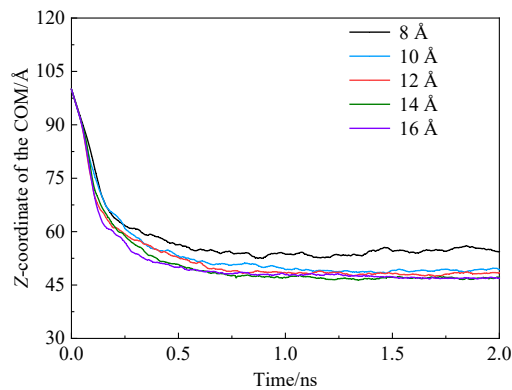
334

Fig. 10. Density profiles of the droplets on the smooth surfaces under cutoff radii of (a) 8 Å, (b) 10

335 Å, (c) 12 Å, (d) 14 Å and (e) 16 Å.

336 As seen in Fig. 9 and Fig. 10, at a solid-liquid interaction coefficient of ϵ_2 , when the cutoff
337 radius increases from 8 Å to 10 Å, the wetting ability of the droplet to the wall is enhanced. This is
338 because the number of atoms within the cutoff radius increases with the increase of the cutoff radius,
339 making the interaction between the wall and the droplet stronger. As the cutoff radius further
340 increases to 12 Å, 14 Å and 16 Å, the shape of the droplet does not change significantly when it
341 reaches an equilibrium state, that is, the influence of the cutoff radius on the shape of the equilibrium
342 droplet is small.

343 When the solid-liquid interaction coefficient is ϵ_2 , the influence of the cutoff radius on the z -
344 coordinates of the mass centroids of the droplets is shown in Fig. 11.

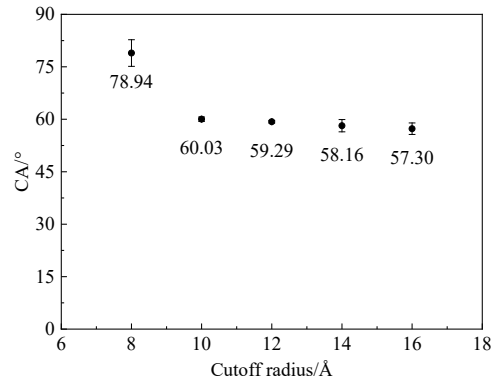


345

346 Fig. 11. Effects of the cutoff radius on the z -coordinates of the mass centroids of the droplets.

347 It can be seen from Fig. 10 that at a solid-liquid interaction coefficient of ϵ_2 , when the cutoff
348 radius rises from 8 Å to 10 Å, the z -coordinate of the mass centroid of the droplet in an equilibrium
349 state reduces. As the cutoff radius further rises to 12 Å, 14 Å and 16 Å, the changes of the z -
350 coordinate of the mass centroid of an equilibrium droplet become smaller. It can be concluded that
351 after the cutoff radius reaches 10 Å, the cutoff radius has small effects on the z -coordinate of the
352 COM.

353 When the solid-liquid interaction coefficient is ε_2 , the intrinsic CAs of the droplets on the
354 smooth surfaces under different cutoff radii are shown in Fig. 12.



355

356 Fig. 12. Effects of the cutoff radius on the intrinsic CAs.

357 It can be seen from Fig. 12 that the intrinsic CA of the droplet on the SS decreases continuously
358 with the increase of the cutoff radius. This is because the larger the cutoff radius, the stronger the
359 wetting ability of the droplet to the wall and the smaller the intrinsic CA. When the cutoff radius is
360 8 Å, the intrinsic CA of the droplet on the SS is 78.94°. When the cutoff radius increases to 10 Å,
361 the intrinsic CA is 60.03°, which decreases by 18.91°. Compared with the cutoff radius of 10 Å,
362 when the cutoff radius further increases to 12 Å, 14 Å and 16 Å, the intrinsic CA of the droplet in
363 an equilibrium state decreases slightly, being 59.29°, 58.16°, 57.30°, respectively. It can be
364 concluded that the cutoff radius has small effects on the intrinsic CA. As a result, in the subsequent
365 simulations of this study, the cutoff radius is selected to be 10 Å.

366 3.3. Analysis of the effects of the rough structure on the static wetting behaviors of the droplets

367 To deeply study the effects of the rough structure on the static wetting behaviors of the droplets,
368 the static wetting processes of the droplets on the surfaces with different structures are simulated
369 under the conditions of four solid-liquid interaction coefficients. The values of the roughness factor
370 (r_s) of the surfaces with different structures and the ratio of the solid-liquid contact area to the

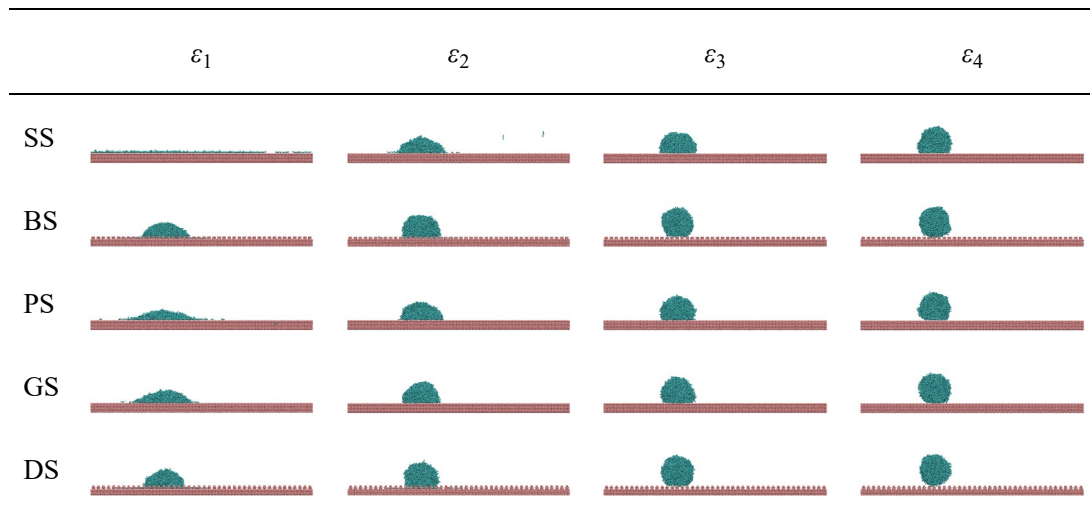
371 composite contact area (f_1) are shown in Table 6.

372 Table 6. Values of r_s and f_1 of the surfaces with different rough structures.

	BS	PS	GS	DS
r_s	2	2	3	9/4
f_1	1/4	3/4	1/2	1/16

373 Under the conditions of four different solid-liquid interaction coefficients of ε_1 , ε_2 , ε_3 and ε_4 ,

374 the snapshots of n-hexadecane droplets on different surfaces at 2 ns are shown in Fig. 13.



375 Fig. 13. Snapshots of the droplets on different surfaces.

376 In the simulation processes, it is found that when the solid-liquid interaction coefficient is ε_1 ,

377 the droplet rapidly spreads after contacting the smooth surface, and the solid-liquid-vapor contact

378 line rapidly expands. It can be seen from Fig. 13 that a precursor film appears during the spreading

379 process of the droplet on the PS. With the decrease of the solid-liquid interaction coefficient, the

380 three-phase contact lines on different surfaces retract. Compared with the smooth surfaces, the rough

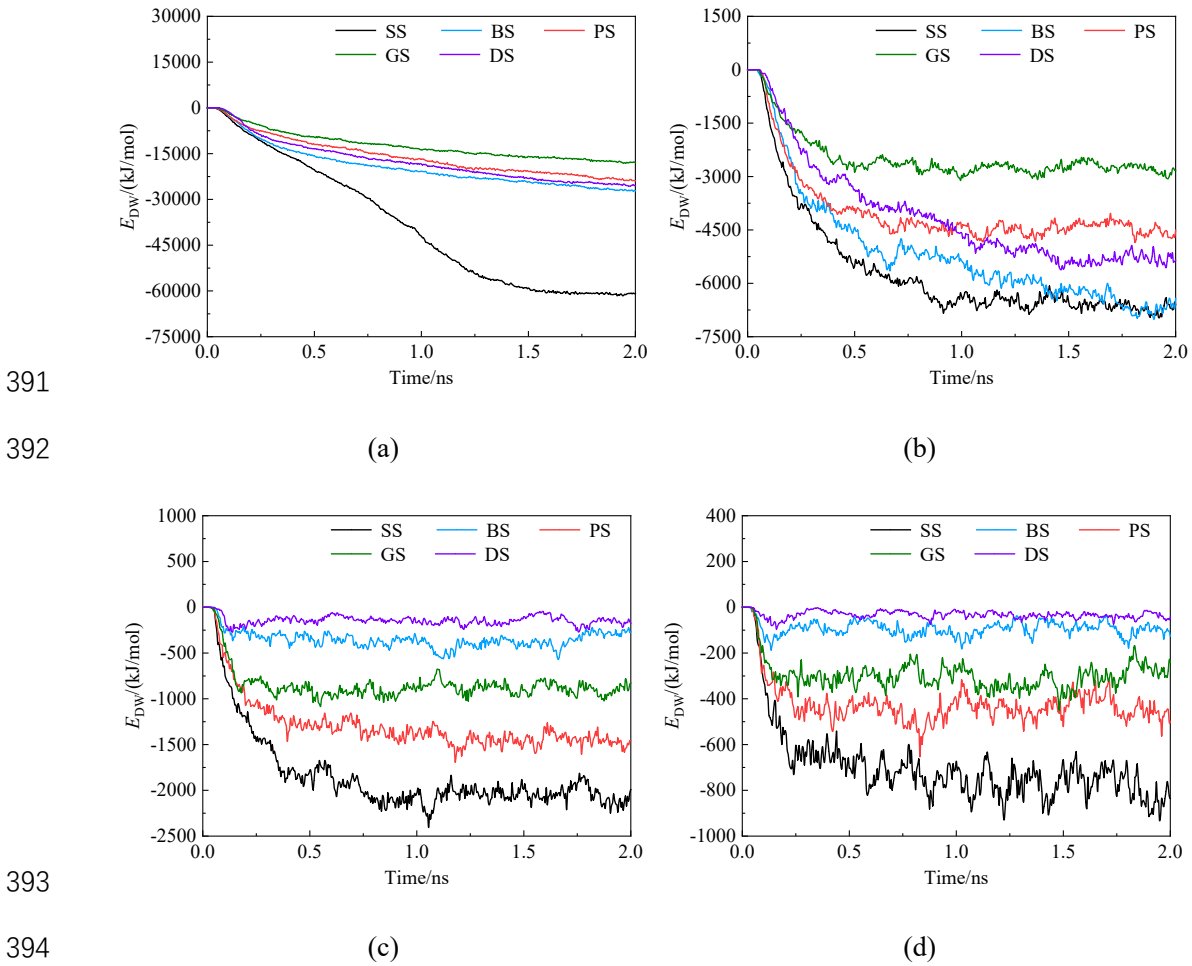
381 structures of other surfaces have an inhibitory effect on the spreading of the droplets. As the solid-

382 liquid interaction coefficient decreases, the interaction between the wall and the droplet is weakened,

383 and the wetting state changes from the Wenzel state to the Cassie state. On the BS, when the solid-

384 liquid interaction coefficient decreases from ε_2 to ε_3 , the wetting state changes from the Wenzel
 385 state to the Cassie state. For the Cassie state, the droplet in an equilibrium state is supported by the
 386 top of the rough structures, and the bottom of the droplet only contacts the top of the bosses of the
 387 surface without infiltrating into the pits. In addition, as the ratio of the solid-liquid contact area to
 388 the composite contact area decreases, it is easier for the droplet to reach the Cassie state.

389 Under different solid-liquid interaction coefficients, the variations of the energy between the
 390 droplets and the walls (E_{DW}) with time are shown in Fig. 14.

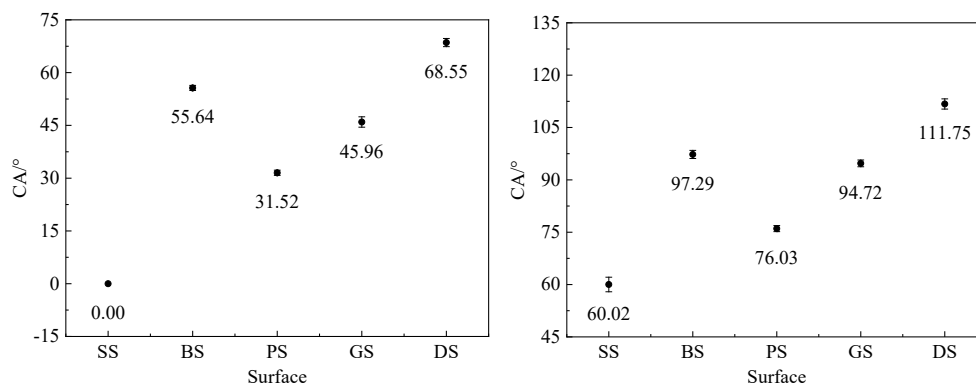


395 Fig. 14. Variations of E_{DW} with time under the solid-liquid interaction coefficients of (a) ε_1 , (b)
 396 ε_2 , (c) ε_3 and (d) ε_4 .

397 It can be seen from Fig. 14 that the interaction forces between different walls and the droplets

398 are all attractive forces. On the same surface, as the solid-liquid interaction coefficient decreases,
399 the interaction between the wall and the droplet is significantly weakened, and the inflection point
400 of the time when the E_{DW} tends to be stable appears earlier. When the solid-liquid interaction
401 coefficient is high, the interaction between the solid surface and the droplet is strong, so the droplet
402 on the surface needs to be stable after a while. However, when the solid-liquid interaction coefficient
403 is low, the interaction strength is weak, the wetting behaviors of the droplet on the surface are mainly
404 affected by the force of the droplet molecules themselves, and the droplet tends to be stable in a
405 short time. Under the same solid-liquid interaction coefficient, compared with the surfaces with
406 different structures, the interaction between the smooth surface and the droplet is the strongest due
407 to the largest contact area between the smooth surface and the droplet.

408 Under different solid-liquid interaction coefficients, the intrinsic CAs of n-hexadecane
409 droplets on the smooth surfaces and the apparent CAs on the surfaces with different structures are
410 shown in Fig. 15.



411

412

(a)

(b)

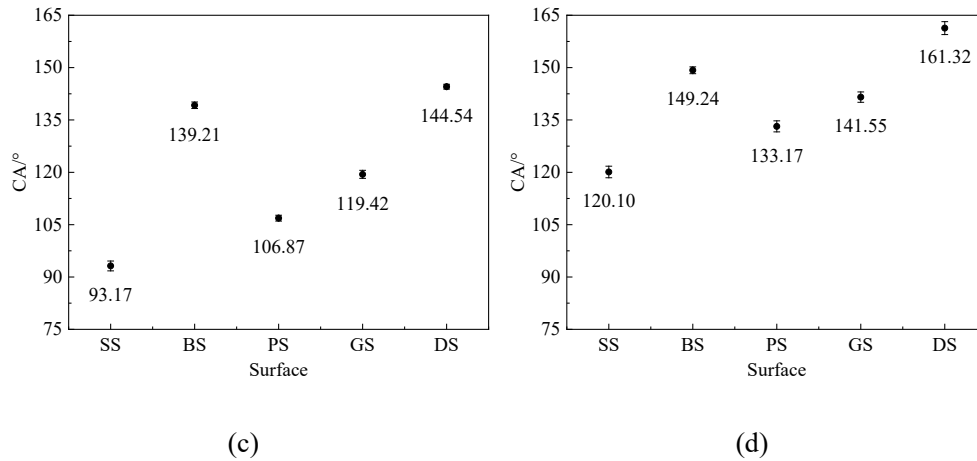


Fig. 15. Static CAs of the droplets on different surfaces under the solid-liquid interaction

coefficients of (a) ε_1 , (b) ε_2 , (c) ε_3 and (d) ε_4 .

As can be seen in Fig. 15, under the conditions of four solid-liquid interaction coefficients of ε_1 , ε_2 , ε_3 and ε_4 , the intrinsic CAs of n-hexadecane droplets on the smooth surfaces are 0° , 60.02° , 93.17° and 120.10° , respectively, which means that under the above solid-liquid interaction coefficients, the surfaces are superoleophilic, oleophilic, neutral and oleophobic in turn. The CA linearly increases with the decrease of the solid-liquid interaction coefficient. The main reason for the above results is that with the decrease of the solid-liquid interaction coefficient, the interaction between the wall and the droplet is weakened, and the tendency of the droplet molecules to move closer to the wall is weakened, which reduces the number of droplet molecules attracted to the wall, resulting in an increase in the intrinsic CA.

Under the conditions of ε_1 , ε_2 , ε_3 and ε_4 , the apparent CAs of n-hexadecane droplets on the surfaces with different structures are all larger than their intrinsic CAs on the smooth surfaces. Taking ε_2 as an example, the intrinsic CA of n-hexadecane droplet on the SS is 60.02° , and the apparent CAs on the BS, PS, GS and DS are 97.29° , 76.03° , 94.72° and 111.75° , respectively. The apparent CA on the DS increases by 51.73° compared to the intrinsic CA on the SS. It can be

431 concluded that the rough structures of the surfaces are beneficial to enhance the oleophobicity of
 432 the surfaces, especially the secondary boss-shaped structures can significantly enhance the
 433 oleophobicity. This is because the rough microstructures of the surfaces hinder the spreading
 434 processes of the droplets on the surfaces. Compared with the BS, PS and GS, the value of f_1 of the
 435 DS is the smallest. That means, in the composite contact area, the proportion of the solid-liquid
 436 contact area of the DS is the smallest, and the proportion of the liquid-vapor contact area of it is the
 437 largest. It can be inferred that the ability of the secondary boss-shaped structures to capture air is
 438 stronger, which leads to the largest CA on the DS. According to the above results, when the thermal
 439 atmosphere in the engine cylinder is poor and the wall temperature is low, increasing the
 440 oleophobicity of the cylinder walls in the areas with a high probability of being hit by the fuel
 441 droplets through constructing the secondary structures is conducive to the rebound of the droplets,
 442 thereby promoting the evaporation of the droplets in the gas-phase space of the cylinder and
 443 improving the atomization quality.

444 **3.4. Analysis of the effects of the rough structure on the dynamic wetting behaviors of the** 445 **droplets**

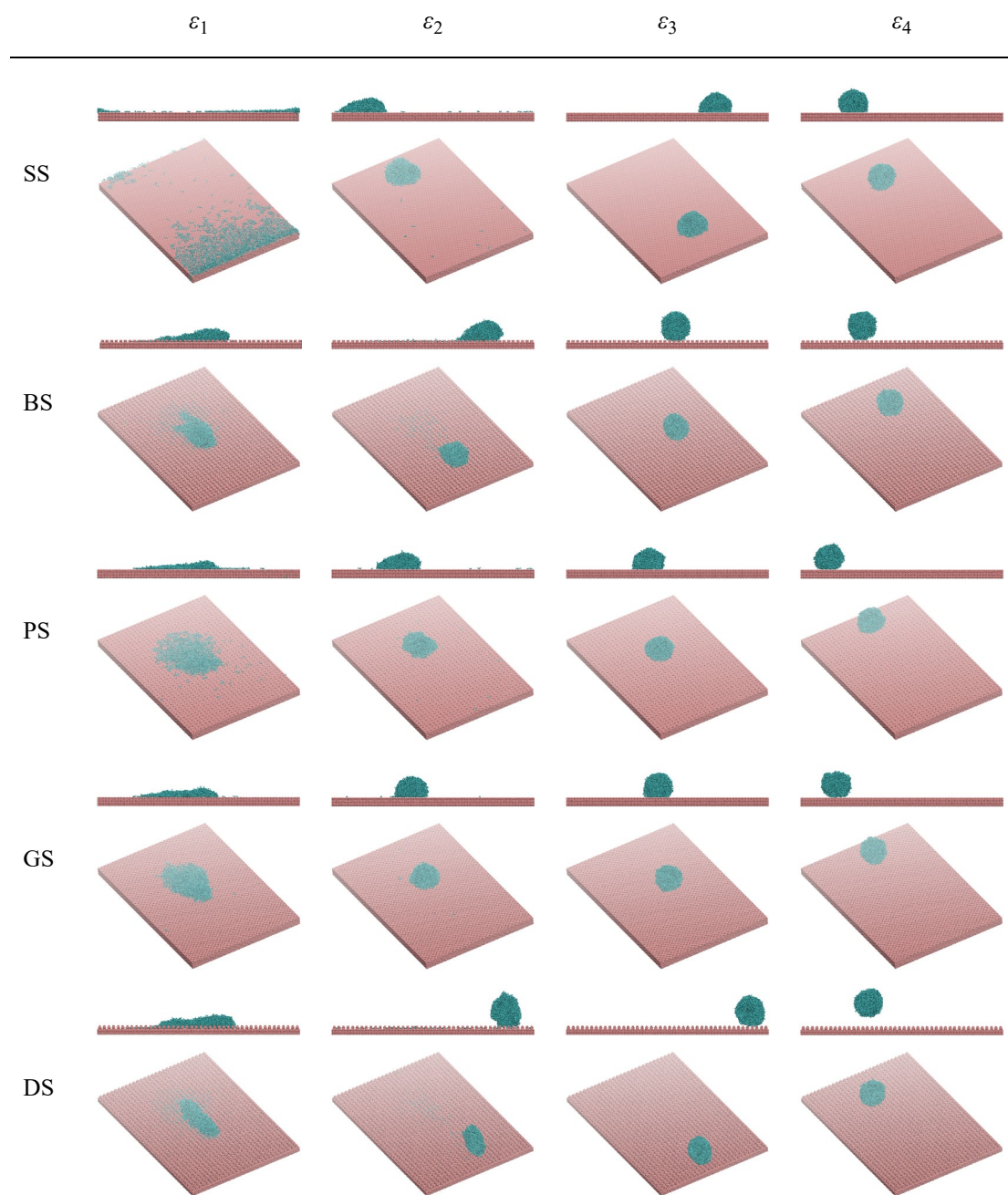
446 To simulate the dynamic wetting processes of the droplets in the equilibrium states on different
 447 surfaces under various solid-liquid interaction coefficients, an external force is applied to them. The
 448 values of the external forces exerted on the atoms CH₃ and CH₂ under the four solid-liquid
 449 interaction coefficients are shown in Table 7.

450 Table 7. Values of the external forces applied to atoms CH₃ and CH₂.

	ε_1	ε_2	ε_3	ε_4
$F_{\text{CH}_3}/\text{kJ}\cdot\text{mol}^{-1}\cdot\text{\AA}^{-1}$	0.008969	0.004485	0.002242	0.001121

$F_{\text{CH}_2}/\text{kJ}\cdot\text{mol}^{-1}\cdot\text{\AA}^{-1}$	0.008368	0.004184	0.002092	0.001046
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451 The snapshots of n-hexadecane droplets on different surfaces at 0.5 ns after the external force
 452 is applied are shown in Fig. 16.

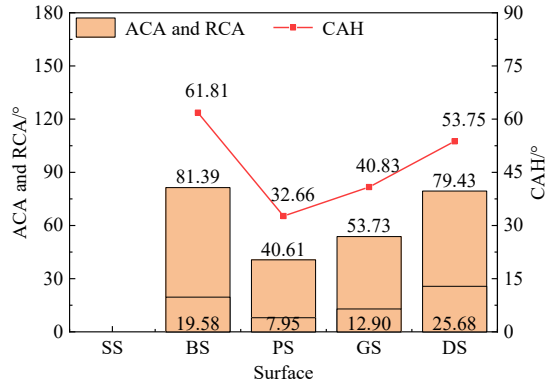


453 Fig. 16. Snapshots of the dynamic wetting processes of the droplets on different surfaces.

454 As can be seen in Fig. 16, under different solid-liquid interaction coefficients, the
 455 morphologies of the droplets during the lateral movements on different surfaces can be mainly

456 classified into three categories: being continuously stretched, being considerably distorted and
457 maintaining the initial shape. The simulation results are similar to those of Jeong et al. (2012).
458 During the simulations, it was found that the droplet gained a velocity in the positive x direction
459 under the action of the external force. However, due to the external force and the pinning effect of
460 the wall on the droplet, the droplet molecules generate a velocity gradient, which leads to the
461 deformation of the droplet. Furthermore, it is found that the droplet moves on the surface in a rolling
462 manner rather than in a translational manner. As can be seen in Fig. 16, when the solid-liquid
463 interaction coefficient is ε_1 , the droplets infiltrate into the pits of the walls and are in a Wenzel state
464 on different surfaces. As a result, the micro rough structures of the surfaces have significant effects
465 on the lateral movements of the droplets. Due to the large difference in the moving speed of the
466 droplet molecules, the droplet is greatly stretched in the x -axis direction. At ε_2 , the droplets are still
467 in a Wenzel state on the SS, BS, PS and GS under the action of external force, and their shapes
468 become asymmetrical. However, the droplet on the DS is in a Cassie state, and its shape does not
469 significantly change. When the solid-liquid interaction coefficients are ε_3 and ε_4 , under the action
470 of the external force, the droplets are in a Cassie state on all different surfaces, and there are slight
471 variations in their contours.

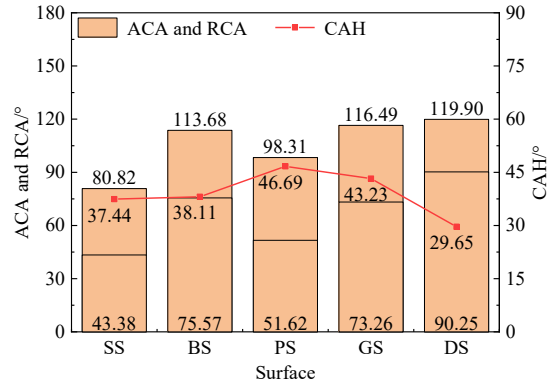
472 To quantify the effects of the solid-liquid interaction coefficient and structure on the dynamic
473 wetting processes of the droplets, the advancing contact angle (ACA), receding contact angle (RCA)
474 and contact angle hysteresis (CAH) are calculated. The results are shown in Fig. 17.



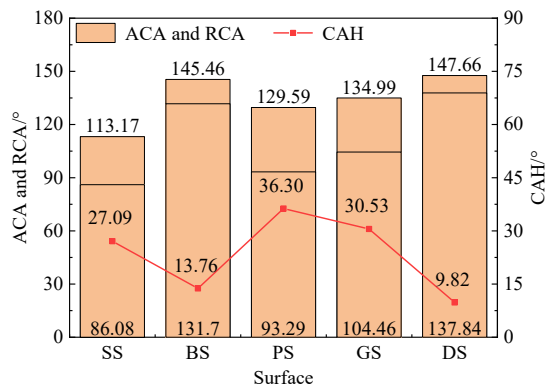
475

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(a)



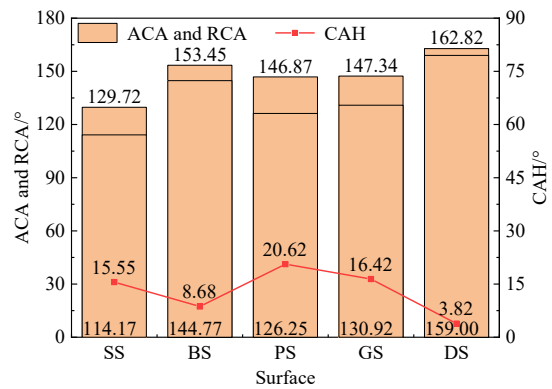
(b)



477

478

(c)



(d)

479 Fig. 17. Dynamic CAs of the droplets on different surfaces under the solid-liquid interaction

480 coefficients of (a) ε_1 , (b) ε_2 , (c) ε_3 and (d) ε_4 .

481 As shown in Fig. 17, at a solid-liquid interaction coefficient of ε_1 , the receding contact angles

482 of the droplets on the four rough surfaces are small. This is mainly because, as mentioned in the

483 previous section, when the solid-liquid interaction coefficient is ε_1 , the Wenzel state is maintained

484 during the movements of the droplets on all the surfaces with different structures, and the droplets

485 are stretched on different surfaces. It should be noted that since the droplet on the SS is greatly

486 stretched to form a thin liquid film, the ACA, RCA and CAH on the SS are not given in Fig. 17(a).

487 When the solid-liquid interaction coefficients are ε_2 , ε_3 and ε_4 , the effects of the rough structure

488 on the CAH mainly include two aspects. On the one hand, compared with the smooth surfaces, the

489 rough structures hinder the movements of the droplets, resulting in an increase in the CAH. On the
490 other hand, the rough structures can enhance the surface oleophobicity compared with the smooth
491 surfaces, leading to a decrease in the CAH. For example, for the PS, the former plays a major role.
492 As a result, the CAH on the PS is larger than that on the SS. As shown in Figures 17(b), 17(c) and
493 17(d), among the four rough surfaces, the CAH of the droplet on the PS is the largest, and the CAH
494 is 46.69° , 36.30° and 20.62° , respectively. The main reason for the above results is that the value of
495 f_1 of the PS is the largest among the four rough surfaces, which makes the interaction between the
496 surface and the droplet the strongest, resulting in the highest potential barrier that needs to be
497 overcome during the movement of the droplet. In addition, at the solid-liquid interaction coefficients
498 of ε_2 , ε_3 and ε_4 , on the four rough surfaces, the CAH on the DS is the smallest, which is 29.65° ,
499 9.82° and 3.82° , respectively. This is related to the strongest oleophobicity of the DS resulting from
500 the smallest value of f_1 among the four rough surfaces. Also, the CAH of the droplets on the DS is
501 7.79° , 17.27° and 11.73° lower than that on the SS. The above results show that the secondary boss-
502 shaped structures can significantly enhance the oleophobicity of the surface, which is consistent
503 with the previous conclusion.

504 As the solid-liquid interaction coefficient decreases from ε_2 to ε_4 , the pinning effect is
505 weakened, so the binding effect of the wall atoms to the droplet molecules near the solid surface
506 becomes weaker, which reduces the number of slow-moving droplet molecules near the solid
507 surface. As a result, the CAH of the droplets on different surfaces continuously decreases with the
508 decrease of the solid-liquid interaction coefficient. At the same time, the interaction between the
509 wall atoms and the molecules in the middle and upper parts of the droplet is weakened, so the
510 resistance to movement during the dynamic wetting process reduces. Also, because there is a small

511 velocity gradient between the molecules of each layer of the droplet, the change degree in the shape
512 of the droplet reduces, which reduces the variations of the ACA and RCA relative to the apparent
513 CA. Therefore, the CAH reduces. Compared with the Wenzel state, since the droplet in the Cassie
514 state is in contact with the upper parts of the rough structures and does not infiltrate into the pits of
515 the structures, the movement of the droplet is not significantly hindered by the rough structures. In
516 addition, when the droplet is in the Cassie state, the actual contact area between the wall and the
517 droplet is small, which makes the interaction between the wall and the droplet weak, resulting in
518 low resistance during the lateral movement process. Therefore, the CAH of a droplet in the Cassie
519 state is smaller than that of a droplet in the Wenzel state.

520 **4. Conclusion**

521 The molecular dynamics method is used to simulate the static and dynamic wetting behaviors
522 of the droplets on different surfaces. The influence of the droplet diameter on the intrinsic CA is
523 analyzed. The effects of the solid-liquid interaction coefficient and rough structures on the apparent
524 CA and the CAH are revealed. The main conclusions are as follows:

525 (1) Under the condition of the same solid-liquid interaction coefficient, after the droplets with
526 different diameters reach the equilibrium states on the smooth surfaces, the variations of the z -
527 coordinates of the mass centroids are small. As the droplet diameter increases, it takes longer for the
528 droplet to reach an equilibrium state, and the z -coordinate of the mass centroid after reaching the
529 equilibrium state slightly increases. The droplet diameter has little influence on the intrinsic CA.

530 (2) At a solid-liquid interaction coefficient of ε_2 , as the cutoff radius increases, the interaction
531 between the wall and the droplet is enhanced, so the wetting ability of the droplet to the wall is
532 enhanced, the z -coordinate of the mass centroid of the droplet in an equilibrium state decreases, and

533 the intrinsic CA reduces. As the cutoff radius further increases from 1.0 nm to 1.2 nm, 1.4 nm and
534 1.6 nm, the effects of the cutoff radius on the shape, the z -coordinate of the mass centroid and the
535 intrinsic CA of an equilibrium droplet are small.

536 (3) Compared with the smooth surfaces, the rough structures of the surfaces have an inhibitory
537 effect on the spreading of the droplets. As the solid-liquid interaction coefficient decreases, the
538 interaction between the wall and the droplet is weakened, and the wetting state changes from the
539 Wenzel state to the Cassie state. As the ratio of the solid-liquid contact area to the composite contact
540 area decreases, it is easier for the droplet to reach the Cassie state.

541 (4) Under the conditions of four solid-liquid interaction coefficients of ε_1 , ε_2 , ε_3 and ε_4 , the
542 intrinsic CAs of the droplets on the smooth surfaces are 0° , 60.02° , 93.17° and 120.10° , respectively.
543 The apparent CAs of the droplets on the surfaces with different structures are all larger than their
544 intrinsic CAs on the smooth surfaces. At a solid-liquid interaction coefficient of ε_2 , the apparent
545 CA on the surface with the secondary boss-shaped structures increases by 51.73° compared to the
546 intrinsic CA on the smooth surface. It can be concluded that the secondary boss-shaped structures
547 can effectively enhance the surface oleophobicity.

548 (5) Under the action of the external force, the velocities of all the droplet molecules are not the
549 same, resulting in a velocity gradient, which changes the shape of the droplet. Furthermore, the
550 droplet moves on the surface in a rolling manner rather than in a translational manner. The decrease
551 in the solid-liquid interaction coefficient weakens the pinning effect of the wall on the droplet,
552 resulting in a lower CAH. The CAH significantly decreases when the droplet transitions from the
553 Wenzel state to the Cassie state.

554 **CRedit authorship contribution statement**

555 **Yanling Chen:** Conceptualization, Data curation, Formal analysis, Investigation, Methodology,
556 Software, Writing – original draft. **Liang Guo:** Formal analysis, Funding acquisition, Validation,
557 Writing – review & editing. **Wanchen Sun:** Formal analysis, Supervision, Validation. **Ningning**
558 **Cai:** Writing – review & editing. **Yuying Yan:** Supervision, Validation.

559 **Declaration of competing interest**

560 The authors declare that they have no known competing financial interests or personal
561 relationships that could have appeared to influence the work reported in this paper.

562 **Data availability**

563 Data will be made available on request.

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567 Technology Research & Development (Project code: 2020C025-2), Free Exploration Project of
568 Changsha Automotive Innovation Research Institute of Jilin University (Project code:
569 CAIRIZT20220202), 2021 “Interdisciplinary Integration and Innovation” Project of Jilin University
570 (Project code: XJRCYB07) and Horizon 2020 MSCA (Project code: H2020-MSCA-RISE-778104-
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