



# AUTOSPEC: Fast Automated Spectral Extraction Software for IFU Data Cubes

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## Abstract

With the ever-growing popularity of integral field unit (IFU) spectroscopy, countless observations are being performed over multiple object systems such as blank fields and galaxy clusters. With this, an increasing amount of time is being spent extracting one-dimensional object spectra from large three-dimensional data cubes. However, a great deal of information available within these data cubes is overlooked in favor of photometrically based spatial information. Here we present a novel yet simple approach of optimal source identification utilizing the wealth of information available within an IFU data cube, rather than relying on ancillary imaging. Through the application of these techniques, we show that we are able to obtain object spectra comparable to deep photometry-weighted extractions without the need for ancillary imaging. Further, implementing our custom-designed algorithms can improve the signal-to-noise ratio of extracted spectra and successfully deblend sources from nearby contaminants. This will be a critical tool for future IFU observations of blank and deep fields, especially over large areas where automation is necessary. We implement these techniques in the Python-based spectral extraction software, AUTOSPEC, which is available via GitHub at <https://github.com/a-griffiths/AutoSpec> and Zenodo at <https://doi.org/10.5281/zenodo.1305848>.

**Key words:** galaxies: distances and redshifts – methods: data analysis – techniques: imaging spectroscopy – techniques: spectroscopic

## 1. Introduction

Spectroscopic analysis of galaxies provides a wealth of information not available from photometric methods. Most of the advances in astrophysics over the past 100 yr have come about due in part to spectroscopy coupled with imaging, and this shows no sign of abating over the next few decades. Insights provided by spectroscopy include, but are not limited to, radial velocities and redshifts, chemical abundances, internal motions of objects, and the identification of objects along the line of sight that can only be seen in absorption, such as Ly $\alpha$  clouds.

The analysis of a galaxy’s content from absorption and emission lines can thus provide insight into its formation and evolutionary history. The benefits of spectroscopy are ever more prevalent with the introduction of integral field units (IFUs) that can simultaneously obtain spectra over large regions of the sky. Traditionally, IFUs have been used to determine the internal properties of galaxies, with each optical fiber probing a different physical location within a galaxy. However, new-generation IFUs with large fields of view can now be used to probe galaxy clusters or “blank” fields where, in principle, many galaxies are observed within a single IFU pointing.

In current and upcoming eras of astronomy, there is a wealth of information that multi-object IFU observations can provide within the dense or blank field areas of the universe. This includes finding galaxies that cannot be seen in the deepest optical imaging (Bacon et al. 2017), as well as in the study of galaxy clusters (e.g., Griffiths et al. 2018; Mahler et al. 2018). Not only does an IFU give information on the radial velocity and thus membership and physical properties of member galaxies, it also provides information on the background lensed systems. For example, the accurate identification of multiply imaged galaxies through spectroscopic redshifts provides critical constraints for lensing models. Currently, IFUs are

the best, most efficient way to get a complete sample of lensed galaxy redshifts.

An ever-increasing amount of scientific research is being conducted with the aid of IFUs such as the multi-unit spectroscopic explorer (MUSE; Bacon et al. 2010) and the Gemini Multi-object Spectrograph (Hook et al. 2004), as well as plans for future instruments on the *James Webb Space Telescope* and the Extremely Large Telescope. With this comes the daunting and time-consuming process of extracting useful information from the large data-cube files produced.

For astronomical images, this process is well established; software such as SEXTRACTOR (Bertin & Arnouts 1996) is widely used to detect, measure, and classify sources through the creation of photometric catalogs. However, for the analogous process of extracting spectra from three-dimensional data, the optimal methodology at this time remains unclear and is typically carried out using various unrefined approaches.

Many spectroscopic IFU studies are based on the photometric preselection of objects, in which catalogs derived from ancillary imaging data or taken from previous studies are used as a basis of spectral extractions. An alternative comes in the form of software such as the Line Source Detection and Cataloging Tool<sup>1</sup> (LSDCAT; Herenz & Wisotzki 2017) and the MUSE Line Emission Tracker<sup>2</sup> (MUSELET; Bacon et al. 2016). These software packages employ computational techniques to perform blind searches of a data cube in order to identify emission lines. In fact, a combination of photometric preselection and blind searches has been found to be favorable (e.g., Bacon et al. 2017; Griffiths et al. 2018; Mahler et al. 2018) to produce source catalogs for spectral extraction. Unfortunately, the optimal method for obtaining one-dimensional spectra from an IFU data cube still remains unclear.

<sup>1</sup> LSDCAT is available at <https://bitbucket.org/Knuser2000/lscat>.

<sup>2</sup> MUSELET is part of MPDAF; documentation is available at <http://mpdaf.readthedocs.io/en/latest/muselet.html>.

The simplest approach is to extract spectra based on fixed apertures, such as is commonly done when measuring galaxy photometry and implemented through source extraction methods and tools such as SEXTRACTOR (e.g., Bina et al. 2016; Karman et al. 2017). An evident drawback to this method is encountered when dealing with more complex sources, such as lensing arcs and extended galaxies or emission regions.

To circumvent some of these issues, an object’s morphology can be used when defining spectral extraction regions. Some IFU studies of galaxy clusters, such as those of Griffiths et al. (2018) and Mahler et al. (2018), implement the use of SEXTRACTOR segmentation maps derived from deep-imaging data as a basis of weighted spectral extraction. The work recently carried out on MUSE observations of the Hubble Ultra Deep Field (Bacon et al. 2017) also follows similar extraction methods. It is, however, not difficult to imagine situations where this may not be entirely applicable, such as the case where an object has extended emission in wavelength ranges not covered by the available imaging.

Here we argue that an abundance of spectral information is being overlooked in existing extraction techniques. We present a new method for the identification of the spatial extent of objects directly from IFU data cubes without the need for ancillary imaging or prior knowledge of the sources. The combination of established aperture and segmentation region extraction methods with a simple but novel custom-designed cross-correlation algorithm can lead to an improvement in the spectral signal-to-noise ratio, as well as the successful isolation of sources from neighboring contaminants.

We structure this paper in two main parts. First, in Section 2, we present our novel technique for the optimal spatial identification of sources directly from a data cube, utilizing the wealth of information available. In Section 3, we provide an overview of our Python-based software package AUTOSPEC, which implements these techniques, along with existing methods for the fast, automated extraction of one-dimensional object spectra. We conclude by showing the versatility of the techniques described in this paper by exploring alternative uses beyond the original design goals.

## 2. Optimal Source Identification

With typical spectral extractions based on circular apertures or an object’s morphology in a particular photometric band, a wealth of information is available within an IFU data cube that is entirely overlooked. Thus, current methods are not ideally suited to spatially identifying a source for the purpose of extracting its spectrum. Furthermore, obtaining a source’s spectrum from an IFU data cube is a complex process, not to mention the computing power required to handle such large file sizes. With no established methods, we are left to ask questions such as, which spectral pixels (spaxels) correspond to the source, and how can we best combine and weight them in order to obtain an optimal one-dimensional spectrum? To answer these questions, we present here a simple but novel technique, combining cross-correlation with continuum extraction to identify and isolate astronomical sources directly from within a data cube itself.

### 2.1. Cross-correlation

Our cross-correlation technique is designed to optimally locate a source from directly within a data cube. In order to

calculate the correlation weight, an initial reference spectrum is required. In principle, a spectral template could be used if there is prior knowledge of a source’s properties, such as redshift and spectral type. This is, however, often not the case, so a reference can be obtained via established methods where object masking is best defined by either a circular aperture or a morphologically based segmentation region. The first step is to create a truncated cube (subcube) around the source in order to reduce both the processing power and computation time required. From the subcube, a spectrum can be obtained via the optimal extraction algorithm (Horne 1986),

$$f(\lambda) = \frac{\sum_x M_x W_x (D_{x,\lambda} - S_\lambda) / V_{x,\lambda}}{\sum_x M_x W_x^2 / V_{x,\lambda}}, \quad (1)$$

where  $f(\lambda)$  is the resultant flux;  $M$  is the object mask;  $D$  and  $V$  are the data and variance cubes, respectively; and  $S$  is the sky spectrum. The ideal initial weight image,  $W$ , is source-dependent and can take the form of ancillary broad- or narrowband imaging. However, if this is not available, a “white-light” image created by flattening the data cube along the spectral axis is often sufficient.

Assuming the source is not extended such that Doppler-shift gradients are negligible, we employ cross-correlation techniques with zero spectral lag. This provides a measure of similarity between the reference spectrum and the spectrum of each spaxel within the subcube. A two-dimensional measure of the cross-correlation strength,  $cc(x, y)$ , is obtained via the equation

$$cc(x, y) = f \star F(x, y) = \sum_\lambda f_\lambda^* F_\lambda(x, y), \quad (2)$$

where  $cc(x, y)$  is the cross-correlation strength map,  $f_\lambda^*$  is the complex conjugate of the reference spectrum, and  $F_\lambda(x, y)$  is the subcube spaxels. This cross-correlation technique yields a strength map that details by what degree each spaxel within the subcube corresponds to the reference spectrum. A higher value is given to spaxels in which the two spectra are similar (i.e., spaxels that correspond to the source), while lower values are given where spaxels show fewer or no similarities (i.e., background sky, other objects, or contaminants). This method effectively negates any selection effects of morphological analysis via photometrically defined segmentation regions or apertures while simultaneously providing a weighting scheme for secondary spectral extraction. Further extractions can be performed via Equation (1) using the correlation strength map as a weighting scheme,  $W$ . In theory, if the source is sufficiently isolated, this technique could be applied without any additional masking; however, for general cases, we have found that masking helps to suppress noise and maintain flux conservation. In principle, this weighted extraction technique is a spectroscopic analog of the photometric methods presented in Naylor (1998).

The success of this technique is, however, limited by the initial reference spectrum used. If a cross-correlation is performed with a reference spectrum that is not a good representation of the object, this technique will provide a less useful map. The main factors that can negatively influence the results are noise and ill-defined masks or initial weight schemes. Sources of noise, such as neighboring contaminants that are not properly masked out, can heavily bias the reference

spectrum. For faint objects, where morphologies cannot be sufficiently approximated from the white-light or supplementary imaging, we find that appropriately sized apertures are best for initial extractions. For more complex sources, such as lensing arcs or extended galaxies, morphologically based extractions prove to be most efficient. For sources that are not sufficiently isolated for neighboring objects, we find that the resultant cross-correlation maps can become heavily biased and unreliable, especially when the target source is fainter than nearby contaminants.

## 2.2. Isolating and Deblending Sources

As previously mentioned, our cross-correlation technique alone is not sufficient to successfully isolate sources from neighboring objects. This issue presents itself when a contaminating object has a similar continuum shape to that of the target source, greatly biasing the resulting cross-correlation strength maps obtained. When this is the case, a continuum subtraction needs to be performed on both the reference spectrum and each spaxel within the subcube before the correlation strength is measured. As a result of this process, only emission and absorption features contribute to the derived cross-correlation strength map, and any continuum induced bias can be successfully negated.

To obtain an estimate of the continuum, we perform a simple  $5^\circ$  polynomial fit. We use this method for both its speed and its simplicity, as it is performed on both the reference spectrum and each spaxel within the subcube individually. A more robust estimation technique could be employed to include iterative processes and outlier removal, but this would become computationally expensive. Alternatively, a continuum could be estimated from only the reference spectrum and applied to the full subcube; however, during our testing, we found that the resulting strength maps were not as robust.

We find that for objects that are not sufficiently isolated, a combination of cross-correlation and continuum subtraction provides optimal identification of sources within the data cube while simultaneously deblending the source from contaminating objects. A visual example of the effectiveness of this method is shown in Figure 1. To further improve spectral quality, it is feasible to extend this method to be performed iteratively, in which a spectrum derived in step  $i$  can be implemented as a reference for iteration  $i + 1$  in order to obtain more refined cross-correlation strength maps.

## 2.3. Signal-to-noise Ratio

To provide some quantification of this method, we compare the signal-to-noise ratio of traditional morphologically and aperture-derived spectra to those extracted via our techniques described here. To investigate the signal-to-noise ratio of the spectra, we first select various source types with known redshifts. We extract spectra via an appropriately sized aperture, as well as weighted extractions with masks defined by segmentation regions. We weight these extractions using both MUSE white-light and deep  $g$ -band imaging. Further, when appropriate, we perform additional extractions based on the stellar point spread function (PSF) and narrowband (high-redshift) weighting schemes. The narrowband image is constructed from the data cube with a width of 100 Å and centered on the Ly $\alpha$  emission line.

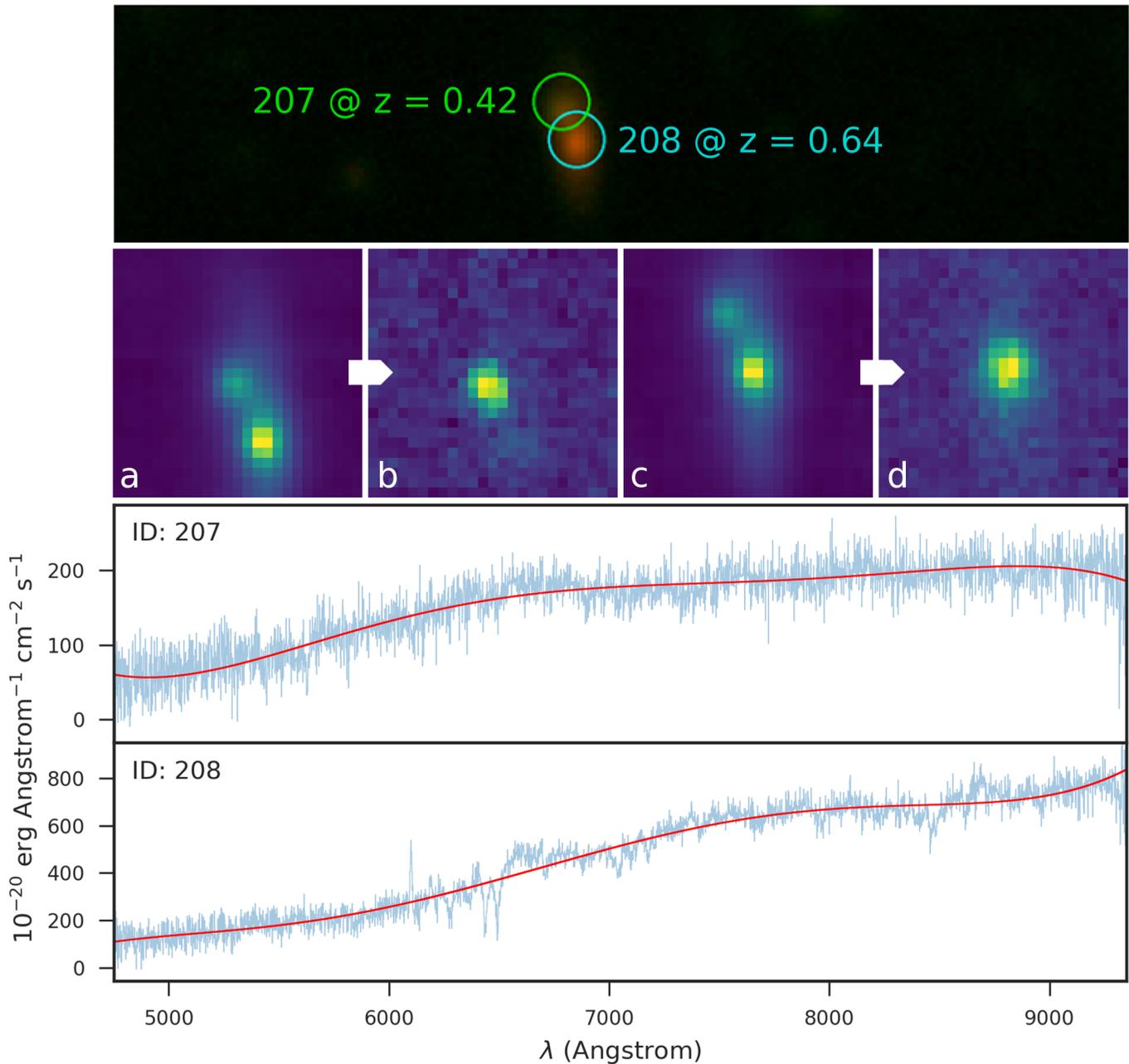
From these initial extractions, we take the best spectrum for each object and use it as a reference for our cross-correlation methods, extracting a spectrum both before and after the additional continuum subtraction step. To estimate the signal-to-noise ratio as a function of wavelength, we fit a template spectrum to each of the spectra extracted. Template fitting is performed using the Python Spectroscopic Toolkit<sup>3</sup> (PYSPECKIT; Ginsburg & Mirocha 2011). PYSPECKIT finds the optimal shift and scaling for the given template to accurately match the input spectra. We calculate the signal-to-noise ratio as a function of wavelength by dividing the shifted, scaled model by the square root of the original spectrum. We find that this provides an accurate representation of the noise in order to compare the various extraction methods.

In Figure 2, we show the spectral signal-to-noise ratio for an example source, an extended lensing arc with nearby foreground contamination (this object can also be seen in Figure 5, panels 2.1 and 2.2). White-light and deep-imaging-weighted spectra show an improved signal-to-noise ratio over a circular aperture extraction, as can be expected for an extended object. Through the use of our cross-correlation derived strength map alone, we find approximately the same results as imaging-weighted extractions. Including the extra continuum subtraction step, we see  $\sim 20\%$  improvement in the spectral signal-to-noise ratio over the next best method. This improvement in signal-to-noise ratio shows that our techniques are able to successfully isolate the source from the foreground contamination and provide a sufficient weighting scheme for the spectral extraction. Improvements such as this are especially significant when dealing with faint and obscured galaxies or looking to obtain accurate spectral-line measurements.

We show the results from other object types investigated in Figure 3. Here we take the median signal-to-noise value over the entire spectral range to more easily represent the data. We further normalize the signal-to-noise measurements such that the peak value for each source is equal to 1. These examples show that for well-defined objects, such as stars and low-redshift galaxies, extractions based on our cross-correlation strength maps provide only a marginal improvement over traditional extraction techniques. However, for more complex sources, such as unresolved high-redshift galaxies and extended lensing arcs, the implementation of our techniques produces a clear increase in the resulting spectral signal-to-noise ratio. Further, the benefits of our technique combined with continuum subtraction are exemplified when considering nonisolated sources. The source labeled “Deblended Galaxy” here refers to object ID 208 from Figure 1; it can be seen that the use of cross-correlation alone induces noise from the contaminating galaxy (as described in Section 2.2). However, when employing the additional continuum subtraction step, we find a significant increase in the spectral signal-to-noise ratio over all traditional extraction methods. Similar results can be seen for the “Deblended Lensing Arc,” which is also shown in Figures 2 and 5 (panels 2.1 and 2.2).

Again, it is worth mentioning here that any signal-to-noise improvements of the resultant spectrum are highly dependent on the reference used. We find that when the reference is poorly defined, this method is strongly biased by contamination, which can result in an overall decrease in signal-to-noise ratio.

<sup>3</sup> PYSPECKIT is available at <https://github.com/pyspeckit/pyspeckit> and <https://bitbucket.org/pyspeckit/pyspeckit>.

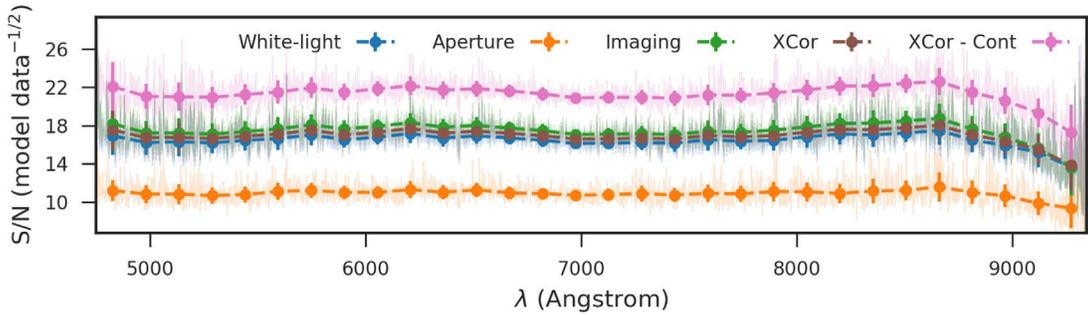


**Figure 1.** We show here the effectiveness of continuum subtraction for a pair of galaxies in close proximity within an observation. The top panels show the false-color image with source positions overlaid. The bottom two panels show the reference spectrum of each source in blue, and in red we show the continuum estimated using a  $5^{\circ}$  polynomial fit. Here it can be seen that even though the continuum of the two sources is different, the overall similarity will bias cross-correlation results when the two objects are in this close a proximity. Panels (a) and (c) show the cross-correlation map without the additional continuum subtraction step for source IDs 207 and 208, respectively. It can be seen in these images that the contaminating source is also picked up by our cross-correlation methods. Panels (b) and (c) show the cross-correlation maps over the same spatial region, this time performed after the additional continuum subtraction routine. Through the comparison of panels (a) and (b) or (c) and (d), the strength of the cross-correlation algorithm combined with continuum subtraction is shown to successfully identify a source’s spatial distribution and isolate it from nearby contaminants.

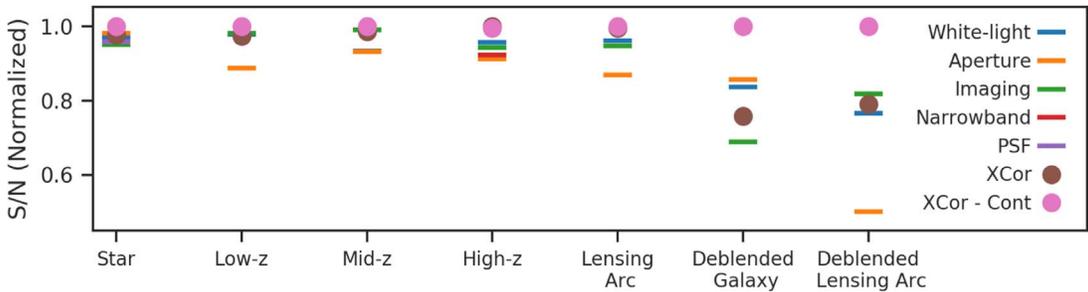
Similarly, the availability of ancillary imaging data will help define robust reference spectra, and even though in our test cases shown here, we find improvements for all objects, for faint sources, the white-light image is not always satisfactory to define extractions. A further limitation is the spatial extent of the object; if it is extended such that Doppler-shift gradients are nonnegligible, this technique is not ideal for spectral extractions.

### 3. Software Methods

The Python-based AUTOSPEC software we introduce here aims to provide the user with simple but robust extraction of one-dimensional spectra from IFU data cubes using both existing techniques and our novel methods described in Section 2. At a minimum, the user is required to supply the software with an IFU data cube, along with a catalog of sources to be extracted. A parameter file is supplied that can be used to



**Figure 2.** We show here the improvement in spectral signal-to-noise ratio through the use of our cross-correlation strength map for an extended lensing arc with various sources of foreground contamination. Additionally, we show the average signal-to-noise ratio of this object in Figure 3, as well as the white-light image and cross-correlation strength map in Figure 5 (panels 2.1 and 2.2). In blue and green, we show the signal-to-noise ratio of a spectrum extraction defined via a segmentation region weighted by the MUSE white-light image and deep  $g$ -band imaging, respectively. Orange shows the signal-to-noise ratio of a spectrum extracted via a circular aperture region, while brown and pink show cross-correlation weighted extractions (with and without the additional continuum subtraction steps, respectively). The signal-to-noise ratio is represented as a function of wavelength across the entire range of the IFU data cube, while the dots show the mean data value for bins of  $\sim 150 \text{ \AA}$ . We show that for this object, our cross-correlation technique combined with continuum subtraction improves the signal-to-noise ratio by  $\sim 20\%$  from the next best extraction method (a deep-imaging-weighted extraction).



**Figure 3.** We show here the normalized spectral signal-to-noise ratio for a variety of objects and extraction methods. Horizontal lines show traditional weighting schemes: blue and green show spectral extractions weighted by the MUSE white-light image and deep  $g$ -band imaging, respectively, while orange represents aperture extractions. For the high-redshift galaxy, we construct a narrowband image of  $100 \text{ \AA}$  width centered on the  $\text{Ly}\alpha$  emission line; the spectral signal-to-noise ratio derived using this image is shown in red. For stellar spectral extractions, we employ an additional PSF weighting scheme, which we show here in purple. Circles show the signal-to-noise ratios of spectral extractions weighted via our cross-correlation maps before (brown) and after (pink) the additional continuum subtraction step. All points shown here represent the median signal-to-noise value across the full wavelength range of the data cube. It can be seen here that in most of the test cases, our cross-correlation methods either improve or are approximately equal to the average spectral signal-to-noise ratio of the best traditional extraction method. When it is not, the use of the additional continuum subtraction step helps to improve the resultant signal-to-noise ratio beyond that of traditional methods by an average of  $\sim 20\%$ . Here “Deblended Galaxy” refers to object ID 208 from Figure 1, and the “Deblended Lensing Arc” can also be seen in Figures 2 and 5 (panels 2.1 and 2.2).

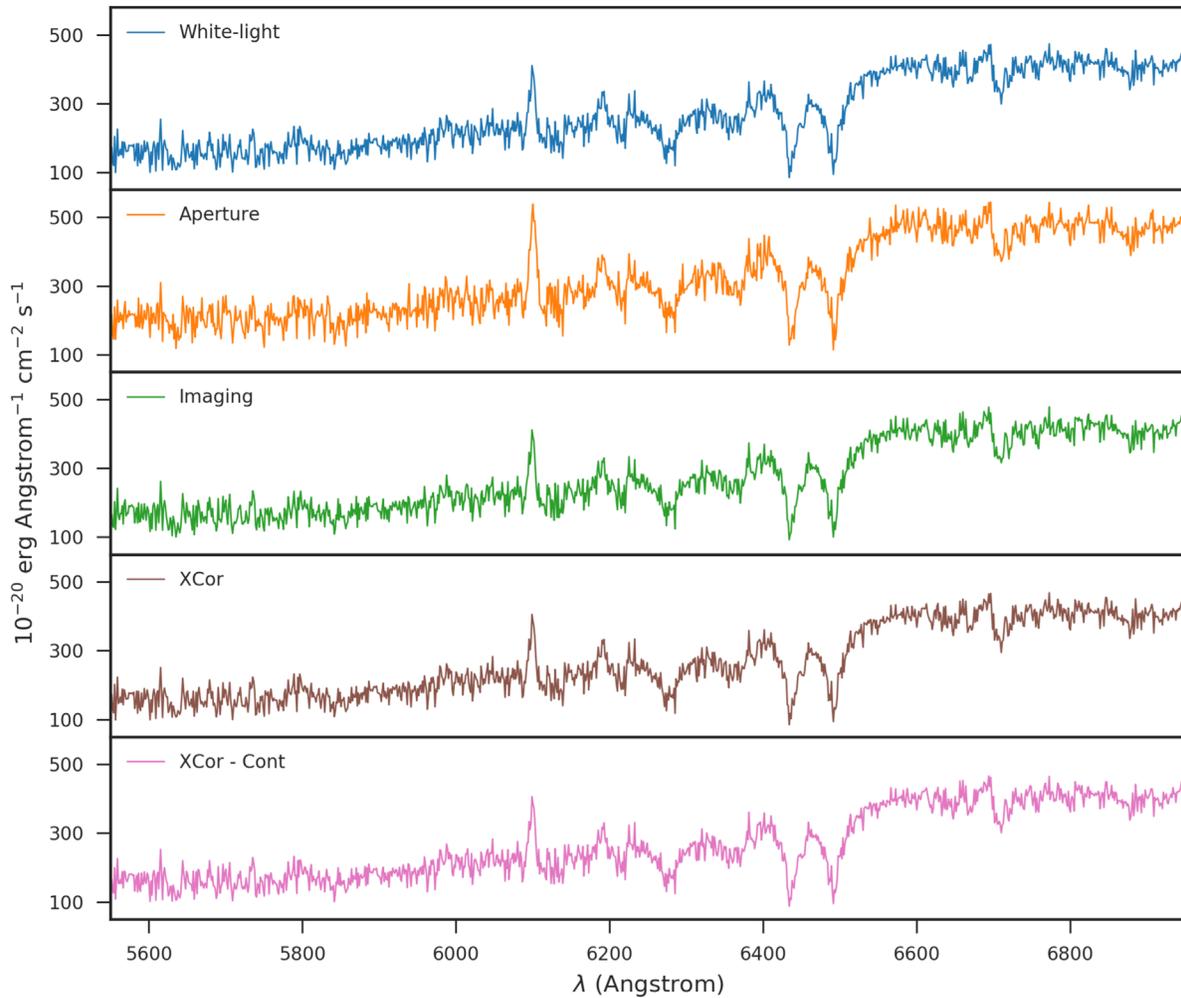
fine-tune the functionality of the software to the user’s requirements. AUTOSPEC makes use of the MUSE Python Data Analysis Framework (MPDAF; Bacon et al. 2016) for various aspects of source extraction and the construction of the output data files.

Initial spectral extractions are performed in which the spatial extent is defined via either user-defined apertures or segmentation regions. Segmentation regions can be automatically calculated within the code or supplied by the user (see Section 3.1). With one of the initial spectra defined as a reference, the software performs our custom-designed cross-correlation algorithm across a truncated data cube centered on the object (see Section 3.2). This cross-correlation algorithm provides detailed insight into which spaxels correspond to the source in question. This analysis is employed as a unique weighting scheme that can be shown to increase the overall signal-to-noise ratio of the resulting spectra. By performing the additional continuum subtraction step, the software can also successfully deblend sources from neighboring contaminants. In Section 3.3, we provide a brief overview of the required input files, as well as the output products produced.

### 3.1. Initial Extraction

For the first step in the extraction procedure, AUTOSPEC iterates through each source in the input catalog and creates a subcube from the supplied IFU data cube. The subcube is centered on the source coordinates with its extent defined by the user. The creation of the subcube is a necessary step in improving computational memory usage and processing time.

To provide the user with as much flexibility as possible, the AUTOSPEC software automatically extracts initial object spectra based on individual or multiple user-defined apertures, weight images, and segmentation maps. First, aperture spectra are calculated from within circular regions with no additional weighting applied. Second, the software will use all user-supplied images to derive a segmentation region using SExtractor, the parameter files for which can be supplied by the user if required. It is also possible to perform segmentation region extraction without additional data; however, by supplying ancillary imaging data or segmentation maps, extraction regions can be more accurately estimated. This is especially important for faint sources that are unlikely to be detected directly from the data cube’s white-light image. For each additional image supplied, as well as



**Figure 4.** Example galaxy spectra extracted via the various methods available within AUTOSPEC. In blue, orange, and green, we show spectra extracted using traditional methods. Orange shows an extraction defined by a circular aperture, while blue and green are masked using segmentation regions generated within the software and weighted by the MUSE white-light and deep  $g$ -band imaging, respectively. The  $g$ -band-weighted spectrum is used as a reference in order to define a cross-correlation weight map both before and after continuum subtraction and used to weight the spectra shown in brown and pink, respectively. For cross-correlation extractions, AUTOSPEC uses the same masks as used by the reference spectrum in order to reduce sources of noise and maintain flux conservation.

the MUSE white-light image, a weighted spectrum will be calculated using Equation (1). Further, if the user has access to existing segmentation maps, these can be supplied in place of or in addition to those calculated within the software.

### 3.2. Improving Spectral Quality

To make use of the wealth of information available within the data cube, we provide the user with the option to implement our cross-correlation and continuum subtraction algorithms in order to deblend sources and perform secondary spectral extractions if required.

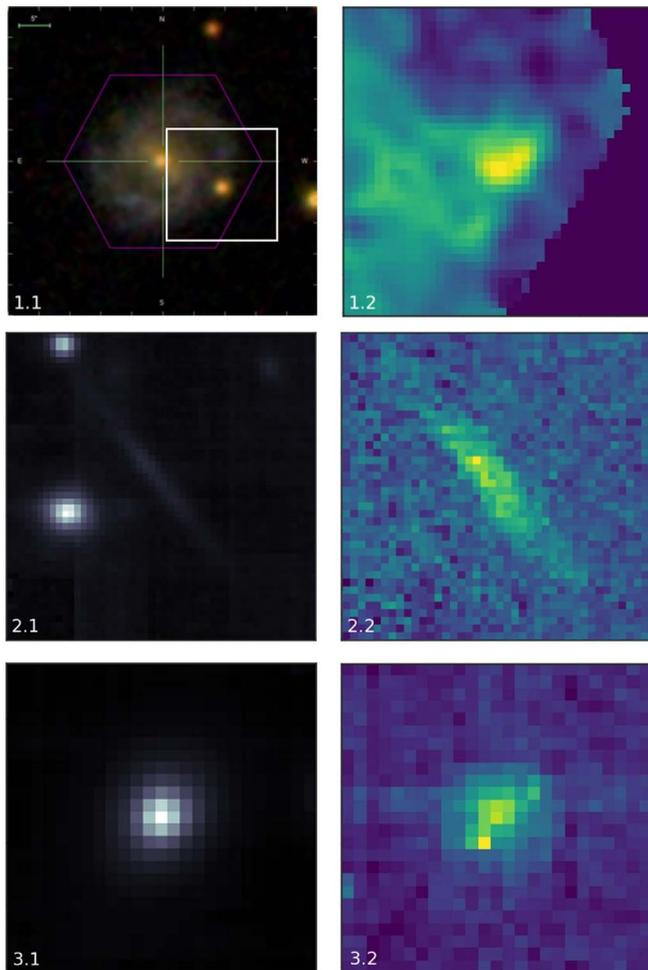
If this step is to be undertaken, the user is required to define one of the preliminary spectra (obtained as described in Section 3.1) as a reference; this can be done on a source-to-source or per-run basis. The software performs our cross-correlation algorithm across the full subcube using Equation (2) and the methods described in Section 2.1. The masks used to produce the reference spectrum are also used in this step. This additional masking is not always necessary; however, we find that in most cases it helps to negate sources of noise and improve flux conservation in these secondary extractions. This analysis yields a weight map, providing a detailed description of the

extent of the source within the data cube itself. This weight map is then used as the basis for a secondary source extraction.

If the subcube is likely to be contaminated by neighboring objects, the user can also choose to perform the additional continuum subtraction step here. Following the methods described in Section 2.2, the target source can be isolated from neighboring objects. While subtracting the continuum from the subcube increases the processing time of each source extraction, we find that the resulting spectral quality can be greatly improved (see Figure 3). Following this step, AUTOSPEC will produce an additional secondary spectral extraction. In Figure 4, we show examples of the spectra extracted for a single object in a run of the AUTOSPEC software. In this case, the software is supplied with a single aperture and an additional image. While it is difficult to see by eye any noticeable improvements in the spectral quality, we note that flux conservation is maintained through all spectral extraction methods undertaken by AUTOSPEC.

### 3.3. Using the Software

The software has been designed to be as user friendly as possible. The user is required to supply the IFU data cube, along



**Figure 5.** Here we show three examples demonstrating the power of our source identification methods. Panel (1.1) is an SDSS image of a galaxy observed in the MaNGA survey (Bundy et al. 2015); the overlaid white box shows the extraction region. Panel (1.2) shows the cross-correlation map. Panels (2.1) and (2.2) show the MUSE white-light image and cross-correlation strength map of a lensing arc detected in the CLIO cluster (Griffiths et al. 2018). Panels (3.1) and (3.2) show a white-light image of a quasar and the corresponding cross-correlation map from MUSE observations of quasar field SDSS J1422–00 (Bouché et al. 2016).

with a catalog of the central positions (R.A. and decl.) of the sources. The catalog can be supplied in one of two different formats. If settings are provided on a per-run basis, the first three columns of the catalog are required to be in the format of source ID (integer), right ascension (degrees), and declination (degrees). This is compatible with a wide variety of existing catalogs, including those produced by MUSELET, which can be implemented directly to AUTOSPEC. Alternatively, if users want to define extraction parameters on a source-to-source basis, they are required to provide two additional columns of data: extraction size of subcube (in arcseconds) and a reference spectrum label (either aperture or weight image).

The user can supply additional images from which the segmentation region can be defined and weighted extractions undertaken. The user can also directly supply SEXTRACTOR segmentation maps derived independently of AUTOSPEC. Our software runs through the command line interface via the Python environment, and all user settings can be configured via the provided parameter and catalog files. The AUTOSPEC

software and detailed usage instructions are available on GitHub.<sup>4</sup>

We test our software on a standard research computer (Intel i3-6100 3.70 GHz CPU with 8 GB of RAM). After a onetime initial set-up procedure per run (which will vary depending on the size of the data cube and number of additional images supplied), source extraction typically takes 3–4 s per object. This includes three aperture extractions, three image-weighted extractions (including white-light), and calculating and extracting cross-correlation weighted spectra before and after the additional continuum subtraction step, effectively processing catalogs of hundreds or thousands of objects in a very short time span.

### 3.3.1. Output

For each source successfully extracted, the user is presented with a FITS format file, the contents of which can be customized according to the user’s preferences. Additionally, for the ease of the user, AUTOSPEC can output JPG files showing the generated masks, cross-correlation weight maps, and spectra obtained for each object.

## 4. Alternative Uses

The development of the techniques and software as detailed in this paper is motivated by work on lensing clusters where the identification and extraction of spectra from a MUSE IFU data cube proved to be a laborious process. However, we show here that their application is not limited to a particular type of observation or instrument.

For IFU observations of single galaxies, such as those obtained in the Mapping Nearby Galaxies at APO survey (MaNGA; Bundy et al. 2015), our cross-correlation techniques are able to spatially identify regions with common spectral features. The produced cross-correlation maps may also help to identify the spatial extent of particular galactic components. Additionally, we suggest that a combination of the cross-correlation and continuum extraction techniques as detailed in this paper are ideal for the identification of multiple images to constrain strong lensing models; this, however, would require significant computing power to be run across large data cubes.

In Figure 5, we show the versatility of our cross-correlation method using various data cubes and observations.

## 5. Summary

We find that by utilizing the wealth of information available within IFU data cubes, we are able to isolate sources and obtain increased signal-to-noise spectra. Our cross-correlation algorithm paired with continuum subtraction performs consistently well at deblending sources and providing a unbiased weighting scheme for spectral extractions.

As these techniques are designed for the extraction of a single one-dimensional spectrum per object, their usefulness is limited to observations in which sources do not subtend large areas of the sky such that Doppler-shift gradients are negligible. Thus, it is best employed for cluster or field studies where these velocity gradients will have minimal effect. As the production of this software was motivated by the work carried out in Griffiths et al. (2018), we find that it is particularly useful for observations of lensing clusters where it is able to successfully identify and extract the spectra of both cluster and background

<sup>4</sup> <https://github.com/a-griffiths/AutoSpec>

galaxies, as well as extended lensing arcs. However, we have shown that its application is not limited to these types of observations.

We provide a simple-to-use tool for the spectral extraction of small or large catalogs of objects with minimized set-up and run time. While this software has been designed with MUSE observations in mind, it is applicable to any IFU data, provided it can be read by the MPDAF Python package. We make this software available under a BSD 3-Clause License via Zenodo (Griffiths 2018) and GitHub at <https://github.com/a-griffiths/AutoSpec>.

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*Facility:* VLT:Yepun (MUSE).

*Software:* AUTOSPEC (Griffiths 2018), LSDCAT (Herenz & Wisotzki 2017), MPDAF (Bacon et al. 2016), PYSPECKIT (Ginsburg & Mirocha 2011), SEXTRACTOR (Bertin & Arnouts 1996).

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